

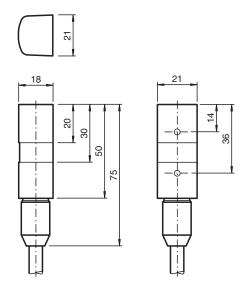
# Magnetic field sensor

## MB-F32-A2

- For mounting on a hydraulic cylinder
- Detects the piston position through the cylinder wall
- Suitable for magnetic, hydraulic cylinders made of steel



### **Dimensions**



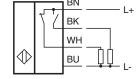
## **Technical Data**

General specifications		
Switching function		complementary
Output type		PNP
Connection		Switching output 1 : black Switching output 2 : white
Installation		on the cylinder
Output polarity		DC
Switching range	Sb	typ. 50 mm
Output type		4-wire
Nominal ratings		

Refer to "General Notes Relating to Pepperl+Fuchs Product Information"

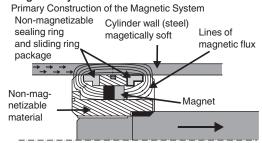
Technical Data		
Operating voltage	$U_B$	10 30 V DC
Reverse polarity protection		reverse polarity protected
Short-circuit protection		pulsing
Voltage drop	$U_{d}$	≤ 1.5 V
Operating current	IL	0 100 mA
No-load supply current	I <sub>0</sub>	≤ 30 mA
Functional safety related parameters		
MTTF <sub>d</sub>		739 a
Mission Time (T <sub>M</sub> )		20 a
Diagnostic Coverage (DC)		0 %
Indicators/operating means		
LED indication		red: switching state output 1 yellow: switching state output 2
Compliance with standards and directives		
Standard conformity		
Standards		EN 60947-5-2:2007 EN 60947-5-2/A1:2012 IEC 60947-5-2:2007 IEC 60947-5-2 AMD 1:2012
Approvals and certificates		
CCC approval		CCC approval / marking not required for products rated ≤36 V
Ambient conditions		
Ambient temperature		-25 85 °C (-13 185 °F)
Storage temperature		-40 85 °C (-40 185 °F)
Mechanical specifications		
Connection type		cable PVC , 2 m
Core cross section		0.5 mm <sup>2</sup>
Housing material		Polyamide (PA)
Sensing face		Polyamide (PA)
Degree of protection		IP67
Cable		
Cable diameter		$6.2 \text{ mm} \pm 0.2 \text{ mm}$
Bending radius		> 10 x cable diameter

## Connection



### **Additional Information**

#### **Magnetic System**



For this sensor principle it is not sufficient to simply mount the permanent magnet onto the piston. A magnetic system has to be constructed which conducts the magnetic flux of the permanent magnets directlt into the cylinder wall in order to achieve the strongest possible magnetization. For further details regarding the construction of magnetic systems, refer to the manual. A field trial is generally recommended before practical operation!

#### Magnets

The magnets are axially magnetized. It must be ensured that all magnets are mounted with the same polarity!

#### **Definition of polarity**

An approaching permanent magnet with the north pole pointing towards the cable connection of the sensor causes output 1 to respond and the red LED to light.



#### **Antivalient output**

By means of the sensor's antivalent output stage the appropriate output can be chosen depending on the polarity of the magnetic system or the mounting location of the sensor

#### Mounting

The sensor is mounted directly on the surface towards the cylinder axis. For this purpose, pressure bands, tightening straps, or hose band clamps can be used.