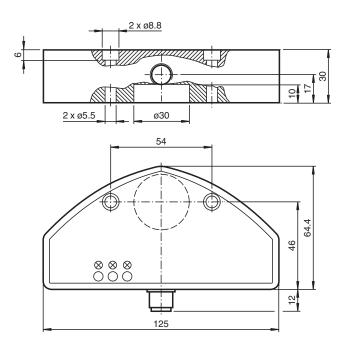
Ultrasonic sensor UC1500-F65-E8R2-V15



- Level indication
- 2 switch outputs
- Program input
- Programmable by means of Interface (see accessories) and SONPROG
- Synchronization options
- Temperature compensation

Dimensions



Technical Data

General specifications		
Sensing range		200 1500 mm
Adjustment range		200 1500 mm
Dead band		0 200 mm
Standard target plate		20 mm x 20 mm
Transducer frequency		approx. 200 kHz
Nominal ratings		
Time delay before availability	t _v	250 ms
Limit data		
Permissible cable length		max. 300 m

Refer to "General Notes Relating to Pepperl+Fuchs Product Information"

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Technical Data

Indicators/operating means			
LED green		Power on	
LED yellow 1		solid: switching state switch output 1 flashing: misadjustment	
LED yellow 2		solid: switching state switch output 2 flashing: misadjustment	
Electrical specifications			
Rated operating voltage	U _e	24 V DC	
Operating voltage	U _B	12 30 V (including ripple) In supply voltage interval 12 20 V sensitivity reduced to 20% 0%	
Ripple		≤ 10 %	
No-load supply current	Io	≤ 60 mA	
Input			
Input type		1 program input Teach-In of S _{min}	
Input voltage		≤ Operating voltage	
Level		low level : 0 3 V (Teach-In active) high level : ≥ 15 V (Teach-In inactive)	
Pulse length		≥ 150 ms	
Output			
Output type		2 switch outputs PNP, NO	
Rated operating current	le	150 mA , short-circuit/overload protected	
Default setting		Switching distance "full", S_{max} : 250 mm Switching distance "empty", S_{min} : 1400 mm Switching hysteresis "full", H_{Smax} : 50 mm Switching hysteresis "empty", H_{Smin} : 100 mm average value "full", M_{Smax} : 20 average value "empty", M_{Smin} : 110	
Voltage drop	U _d	≤3 V	
Switch-on delay	t _{on}	110 ms	
Repeat accuracy		±2 mm	
Off-state current	l _r	0.01 mA	
Temperature influence		≤±1.5 %	
Compliance with standards and directives			
Standard conformity			
Standards		EN IEC 60947-5-2:2020 IEC 60947-5-2:2019	
Approvals and certificates			
UL approval		cULus Listed, General Purpose	
CCC approval		CCC approval / marking not required for products rated \leq 36 V	
Ambient conditions			
Ambient temperature		-25 70 °C (-13 158 °F)	
Storage temperature		-40 85 °C (-40 185 °F)	
Shock resistance		30 g , 11 ms period	
Vibration resistance		10 55 Hz , Amplitude ± 1 mm	
Mechanical specifications			
Connection type		Connector plug M12 x 1 , 5-pin	
Degree of protection		IP65	
Material			
Housing		PBT	
Transducer		epoxy resin/hollow glass sphere mixture; polyurethane foam	
Installation position		any position	

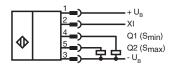
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Connection



Connection Assignment

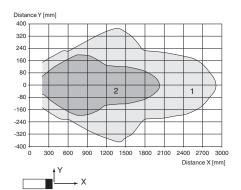


Wire colors in accordance with EN 60947-5-2

1	BN	(brown)
2	WH	(white)
3	BU	(blue)
4	BK	(black)
5	GY	(gray)

Characteristic Curve

Characteristic response curve



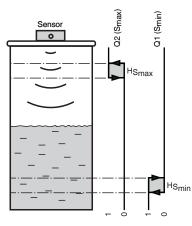
Curve 1: flat surface 100 mm x 100 mm Curve 2: round bar, Ø 25 mm

Refer to "General Notes Relating to Pepperl+Fuchs Product Information"

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Characteristic Curve

Function of the switching outputs



Accessories

ø /	V15-G-2M-PUR	Female cordset single-ended M12 straight A-coded, 5-pin, PUR cable grey
ø /	V15-G-2M-PVC	Female cordset single-ended M12 straight A-coded, 5-pin, PVC cable grey
«	V15-W-2M-PVC	Female cordset single-ended M12 angled A-coded, 5-pin, PVC cable grey
	3RX4000-PF	PC interface

Refer to "General Notes Relating to Pepperl+Fuchs Product Information"

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Additional Information

Applications

The design and functionality makes this sensor best suitable for level detection applications in small containers or tanks. The device provides 2 switching outputs Q1 (S_{min}) and Q2 (S_{max}). Special distances can be assigned to each of them - e. g. the minimum and maximum levels in a tank can be evaluated and displayed. The parameters can be programmed with SONPROG or with an automatic setup (Teach-In).

Mounting and Connection

All parts are accommodated in a fully enclosed housing. The ultrasonic transducer is set back in the housing, so it is protected. Because of the built-in sealing the sensor can be used as a closure with integrated level detection. The opening of the tank must have a diameter of 26 mm. The sensor is fixed by means of two M5 screws. The sensor has a 5 pin M12 x 1 connector. The BERO has built-in polarity reversal as well as short-circuit and overload protection. Where there is electrical interference, shielded cables are recommended.

Setup

The two ranges, the associated hysteresis and the average value are preset at the factory (see technical data). The parameters can be programmed with SONPROG or with an automatic setup (teach-in). Teach-in can be done by means of the keys of the interface (accessories) or the function input XI.

Automatic Setup (Teach-in)

With this function the minimum level S_{min} can be set. The following steps must be performed in the correct order:

- 1. Fill the tank up to the required minimum level or place an object at the required distance.
- Apply "low" signal (0 to 3 V) to the function input XI e.g. connect XI via a key to 0 V, or connect it via a PLC to "LOW"). The LED "S_{min}" flashes, then. The sensor is disabled; it's learning the distance. The signal duration must be at least 150 ms.
- 3. Remove signal from XI e.g. disconnect it from the function input XI, connect it to +UB or connect it via a PLC to "HIGH").
- Important! As long as the function input XI is connected to "low", the sensor is disabled.

SONPROG

With SONPROG the following parameters can be programmed:

- Start or end of both switching ranges S_{min} and S_{max}
- Hysteresis (HS_{max}, HS_{min})
- Blind zone
- Sensing range
- Average value
- Switching output S_{min} NC / NO

Customer specific programming is available on request.

Operation

The level of liquid inside a tank is detected within the sensing range. If the level reaches one of the two switching levels (S_{min} , S_{max}), then the corresponding output will be set active. Both switching levels are equipped with a switching hysteresis (HS_{min} , HS_{max}). The switching status of each output is indicated by the corresponding yellow LED. If the filling level is in between the 2 switching levels, both of the outputs are in off state. Objects inside the blind zone will cause error signals. Therefore the user has to mount the sensor that way that the level cannot be inside the blind zone.