

Ultrasonic sensor UC10000-F260-UE8R2

- Large sensing range
- Adjustable Bracket
- Programmable by means of Interface (see accessories) and SONPROG
- 1 analog output, 0-10 V voltage source
- 2 switch outputs
- Synchronization options
- Temperature compensation

Single head system

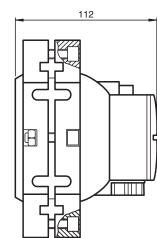


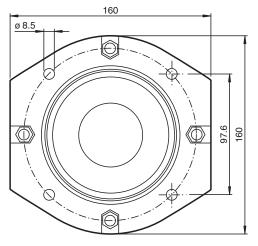
Function

This ultrasonic sensor is a contactless distance sensor based on the echo run time principle. It is suitable for the detection of solid, liquid or powder sound-reflecting objects. The unique sensor design allows easy movement of the direction of sound radiation in all spatial directions by up to 10° without additional an

The unique sensor design allows easy movement of the direction of sound radiation in all spatial directions by up to 10° without additional an additional assembly device.

Dimensions





Technical Data

General specifications	
Sensing range	800 10000 mm
Adjustment range	800 10000 mm
Dead band	0 800 mm
Standard target plate	100 mm x 100 mm

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Ultrasonic sensor

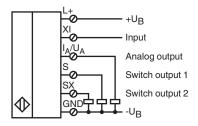
Technical Data

UC10000-F260-UE8R2

Transitive approx. 60 WHz Nominal ratings 280 ms Time delay before availability L 280 ms Permissible cable length max. 300 m Indicators/operating means Edit witching state availeh output Electrical specifications Beding missible means Filed operating voltage U, 24 V DC Operating voltage U, 24 V DC Operating voltage U, 24 V DC No-load supply current U, 24 V DC No-load supply current U, 24 V DC No-load supply current U, 24 V DC Input/Output 15 30 V including ripple) Input/Output 53 V 30 V including ripple Input impedance 15 30 V max. 10 Switching output 2 switch outputs PNP, NO Real at 51 mm Operating current L, 300 ms Analeg output 53 V Sold control Output type 1 voltage output: 0 10 V fining ramp Output type 1 voltage output: 0 10 V fining ramp	l'oonnou bata		
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Mass 1800 g			

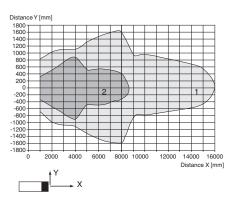
Refer to "General Notes Relating to Pepperl+Fuchs Product Information".

Connection



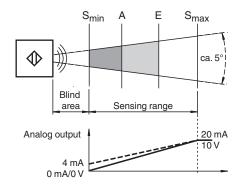
Characteristic Curve

Characteristic response curve



Curve 1: flat surface 100 mm x 100 mm Curve 2: round bar, Ø 25 mm

Area definitions



Release date: 2023-02-13 Date of issue: 2023-02-13 Filename: 250794_eng.pdf

3RX4000-PF PC interface V15S-G-2M-PVC Male cordset single-ended M12 straight A-coded, 5-pin, PVC cable grey V1-M20-80 Receptacles, M12/M20; plastic version	Accessories			
J		3RX4000-PF	PC interface	
V1-M20-80 Receptacles, M12/M20; plastic version	<i>d</i> /	V15S-G-2M-PVC	Male cordset single-ended M12 straight A-coded, 5-pin, PVC cable grey	
	\$	V1-M20-80	Receptacles, M12/M20; plastic version	

Additional Information



This product must not be used in applications in which the safety of persons depends on the device function. This product is not a safety component in accordance with the EU Machinery Directive.

Assembly and connection

Danger!

When installing the sensor, make sure that the space filled by the sound cone is free from interfering objects. Objects in the blind zone cause cause false signals. Implement suitable measures to ensure that objects cannot enter the blind zone.

The electrical connection is made via screw terminals. The connections are protected against reverse polarity, short circuits and overloads. Shielded cables are recommended if there is electrical interference.

Setting

The detection range limits S_{min} and S_{max} are fixed (see Technical data). Within these limits, the switch points A and E are set using a potentiometer. Switch point A must be smaller than switch point E. If this is not the case, the LED flashes and correct switching is not possible.

Parameterisation via SONPROG

The following parameters can be changed via the SONPROG parameterisation software:

- Measuring range limits S_{min} and S_{max}
- Switch-on and switch-off points E and A
- Blind zone
- Averaging
- Analogue limits
- Analogue characteristic, rising/falling

Operation

Within the detection range, which is restricted by the detection range limits S_{min} and S_{max} , the object distance is detected. Objects with an even, smooth surface can have a maximum inclination of 3° to the direction of sound propagation. With rough, uneven surfaces the angular deviation can be bigger. The actual value depends significantly on the object finish and should be obtained experimentally if necessary.

Behaviour of the switch outputs:

- If the object is at a distance > E, both switch outputs are in standby mode.
- If the object is between E and A, switch output S is activated and switch output SX is in standby mode.
- If the object is at a distance < A, switch output SX is activated and switch output S is in standby mode.

Behaviour of the analogue output:

The object distance between the detection range limits (S_{min} , S_{max}) are displayed in the form of an analogue output signal at the analogue output. The analogue output delivers its minimum value at distance S_{min} and its maximum value at distance S_{max} . The characteristic between the two measuring range limits is linear. Outside of S_{max} the analogue output retains its maximum value.

Display:

The sensor has an LED. It lights up continuously when the output terminal S is carrying a voltage. It flashes when switch points A and E are set incorrectly (see Setting).

Function input XI

The sensor is placed in standby mode by connecting a low level at the function input XI (blocked release). The sensors then performs no measurements. The switch outputs retain the most recent status. As soon as function input XI is disconnected from the low level or a high level is connected (release), the sensor resumes its normal function after the release period has expired.

The function input XI can be used during operation for the synchronisation of multiple sensors in the event of mutual interefence. The following synchronisation modes are possible:

- Triggering of each individual sensor with a separate control signal, e.g. by a PLC (external synchronisation).
- Connection of the function inputs XI of all sensors and joint triggering with an external control signal, e.g. by a PLC (external synchronisation, common-mode operation).
- Connection of the function inputs XI of all sensors and without triggering with an external signal (internal synchronisation, multiplex mode).

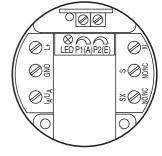
Maintenance

The ultrasonic sensor is maintenance-free. However, the converter surface must not be wet, damaged, painted or covered with material deposits..

Connection Assignment

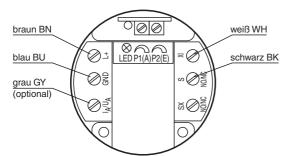
Connecting the PC interface 3RX4000-PF to use SONPROG

This sensor can be parameterised using SONPROG for an optimum adaptation to the application. Therefore the sensor provides communication with the 3RX4000-PF PC interface. To connect to the 3RX4000-PF PC interface a 4- or 5-pin M12 male cable connector is reqired. We recommend e. g. an adapter V1-M20-80 or a cable connector V15S-G-2M-PVC. Please connect the wires to the sensors terminals as shown, below.





Ultrasonic sensor



The terminals I_A/U_A (analog output) and SX (2nd switching output) are not needed for programming.

Refer to "General Notes Relating to Pepperl+Fuchs Product Information"

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