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# Active infrared scanner LT2-8-HS-2000/49/115



- Mode selectable: background suppression or evaluation
- Mechanical adjustable detection range
- Adjustable timer functions
- DC voltage version
- Version with test input

Precision sensor for long detection ranges up to 2 m



### **Function**

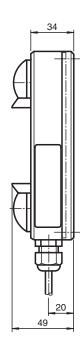
Diffuse mode sensors LT(K)2 are used when people, objects, or vehicles are to be detected in a precisely defined area. The devices are extremely sturdy and resistant to mechanical strain. In background evaluation operating mode, the sensors can be used with any background. In background suppression operating mode, the background serves as a reference area. This enables highly reflective objects to be reliably detected as well. In addition, this operating mode offers an option for testing.

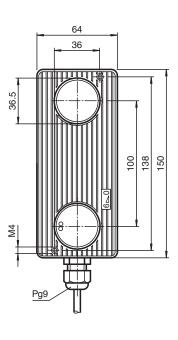
### **Application**

- · Opening impulse sensor and protection mechanism for closing edges on automatic doors and industrial doors
- · Opening impulse sensor for automatic doors
- · Vehicle detection in traffic technology (e.g., individual parking space monitoring)
- Height measurement at entrances
- Anti-collision protection on automated guided systems



### **Dimensions**





### **Technical Data**

General specifications		
Detection range min.		0 500 mm by background evaluation, 350 500 mm by background suppression
Detection range max.		0 2000 mm by background evaluation, 350 2500 mm by background suppression
Light source		IRED
Light type		modulated infrared light
Operating mode		switching between background suppression/evaluation
Diameter of the light spot		50 mm at 2000 mm sensor range
Functional safety related parameters		
MTTF <sub>d</sub>		730 a
Mission Time (T <sub>M</sub> )		20 a
Diagnostic Coverage (DC)		60 %
Indicators/operating means		
Function indicator		LED green: power on LED yellow: object detection
Control elements		Sensing range setting, programming switch for time functions, time setting
Electrical specifications		
Operating voltage	$U_B$	15 35 V DC
Ripple		10 %
No-load supply current	$I_0$	100 mA
Input		
Test input		emitter deactivation with +Ub

**Technical Data** 

CE conformity

Connection

Optical face

Material Housing

Mass

**Ambient conditions** 

Ambient temperature

Mechanical specifications

Degree of protection

### Output Switching type light/dark on selectable programmable, Factory setting: light on 1 NPN, 1 PNP, short-circuit protected, open collectors Signal output Switching voltage 35 V DC Switching current 200 mA 50 ms Response time De-energized delay 100 ms $t_{\text{off}}$ Timer function Programmable on/off delay, adjustable 0.1 ... 10 s Conformity Product standard EN 60947-5-2 Compliance with standards and directives Standard conformity Emitted interference EN 61000-6-3 EN 61000-6-2 without EN 61000-4-5, EN 61000-4-11 Standards Approvals and certificates

-20 ... 60 °C (-4 ... 140 °F)

yes

IP65

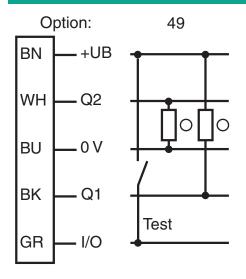
320 g

5 m fixed cable

Makrolon GV30

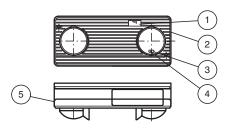
hardened plastic lens

## **Connection Assignment**

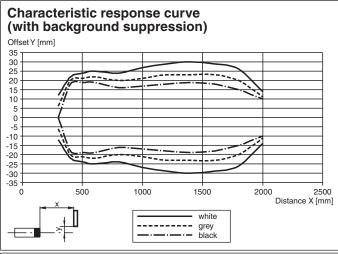


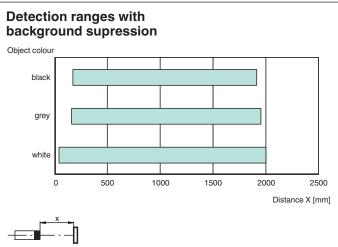
- O = Light on
- = Dark on

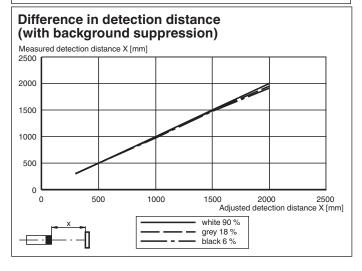
### **Assembly**

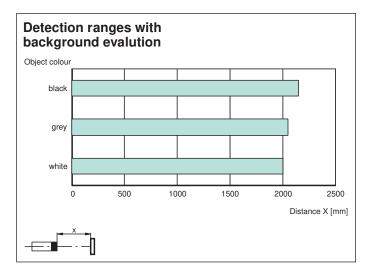


1	Detection range indicator		
2	Detection range adjuster		
3	Operation display	Green	
4	Function display Yello		
5	Programming switch under cover		









### **Application**



### **Function Principle**

The active infrared scanners of the LT2 and LTK2 series operate with the background suppression and background evaluation operating modes. The emitter and receiver are aligned at a certain angle in relation to one another. This angle can be changed and is used to determine the maximum detection range.

The LT2 series operates with direct-current voltage and features transistor outputs; the LTK2 series operates with direct-current voltage and alternating-current voltage and features a relay output.

**Background Suppression Operating Mode (Factory Setting)** 

The sensor switches state when an object moves into or out of the detection range and is detected by the light beam. The background and/or base is ignored during this process. The sensitivity of the sensor can be adjusted, so that objects beyond a certain distance are ignored. Sensors that feature this operating mode can be mounted for mobile use.

**Background Evaluation Operating Mode** 

The sensor switches state when an object moves into or out of the detection range and is detected by the light beam. However, where background evaluation is used, some form of background, such as the floor or a wall, must be present as a point of reference. The sensor continues to switch, even if no light is received from the background. Sensors with background evaluation do not have foreground suppression. This means that they can also detect objects directly in front of the lens (detection range = 0), making them particularly suited for detecting objects that are difficult to detect, especially highly reflective objects.

### **Alignment/Setting Instructions**

Always use the object with the lowest reflection value (darkest color) for alignment purposes.

1. 1. Align the sensor to the target objects

Turn the detection range controller all the way to the right end stop (-)

(CAUTION! The controller is not protected from overturning—handle with care)

Turn the detection range controller to the left (+) until the yellow LED starts to light up

2. 2. Remove the target objects; the LED goes out (note background influences).

If the background (floor, wall) is permanently or occasionally reflective and shiny, due to moisture for example, the device must be installed in such a manner that it is rotated through  $> 5^{\circ}$  along its longitudinal axis to prevent a mirror effect.

### Selecting the appropriate operating mode

The devices are supplied in background suppression operating mode.

The background evaluation mode should be used if:

- Objects close to the optics are detected (detection range = 0 mm)
- Reflective, shiny objects must be detected (e.g. vehicles)
- A device function test is performed by means of test input

**CAUTION!** When in background evaluation operating mode, the sensor must always be aligned with a background that remains as constant as possible. Where this is not guaranteed, background suppression operating mode must be used. The background must be located within the stipulated maximum detection range.

### **Programming functions**

The four programming functions are set using a DIP switch, which is located on the rear of the printed circuit board. To operate, simply remove the housing cover.

The functions described can be programmed as follows:

Switch	Description	ON	OFF
1	Operating mode	Background evaluation	Background suppression
2	Switching mode	Light on (L)	Dark on (D)
3	Timer function	ON delay (GAN)	-
4	Timer function	OFF delay (GAB)	-



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Use the potentiometer to the left of the switches to set the GAN and GAB times steplessly from 0.1 s ... 10 s.