

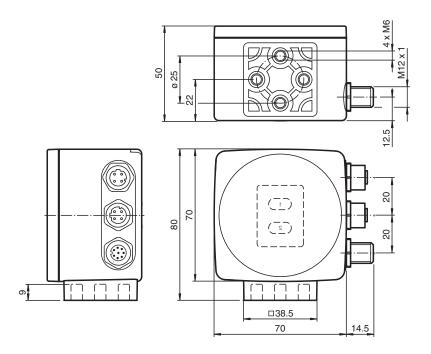
# Optical reading head PCV100-F200-B17-V1D-6011-8203

- Traverse distance up to 100 km
- Non-contact positioning on Data Matrix code tape
- Mechanically rugged: no wearing parts, long operating life, maintenance-free
- High resolution and precise positioning, especially for facilities with curves and switch points as well as inclines and declines.
- PROFINET interface
- Integrated switch

Read head for incident light positioning system



## **Dimensions**



# **Technical Data**

General specifications		
Passage speed	V	≤ 6 m/s
Measuring range		max. 100000 m
Light type		Integrated LED lightning (red)
Scan rate		40 s <sup>-1</sup>
Read distance		100 mm
Depth of focus		± 40 mm
Reading field		60 mm x 35 mm
Ambient light limit		100000 Lux
Accuracy		± 0.2 mm

#### Technical Data **Nominal ratings** Camera Type CMOS, Global shutter Processor Clock pulse frequency 600 MHz Speed of computation 4800 MIPS Digital resolution 32 Bit Functional safety related parameters $MTTF_d$ 99 a 20 a Mission Time (T<sub>M</sub>) Diagnostic Coverage (DC) 0 % Indicators/operating means LED indication 7 LEDs (communication, alignment aid, status information) **Electrical specifications** Operating voltage $U_B$ 15 ... 30 V DC, PELV No-load supply current $I_0$ max. 400 mA 6 W Power consumption $P_0$ Interface Interface type 100 BASE-TX Protocol PROFINET IO Real-Time (RT) Conformance class B Netload Class II Transfer rate 100 MBit/s Interface 2 Interface type **USB Service** Input Input type 1 funtion input 0-level: -U<sub>B</sub>or unwired 1-level: +8 V ... +U<sub>B</sub> , programmable Input impedance ≥ 27 kΩ Output Output type 1 to 3 switch outputs, programmable, short-circuit protected Switching voltage Operating voltage Switching current 150 mA each output Conformity Shock resistance EN 60068-2-27:2009 Vibration resistance EN 60068-2-6:2008 EN 61000-6-4:2007+A1:2011 **Emitted interference** Noise immunity EN 61000-6-2:2005 Photobiological safety exempt group according to EN 62471:2008

pprovals	and	certificates	

CE CE conformity

CCC approval / marking not required for products rated ≤36 V CCC approval

**Ambient conditions** 

Storage temperature

Degree of protection

 $0 \dots 60~^{\circ}\text{C}$  (32 ... 140  $^{\circ}\text{F})$  , ~ -20 ... 60  $^{\circ}\text{C}$  (-4 ... 140  $^{\circ}\text{F})$  (noncondensing; prevent icing on the lens!) Operating temperature

-20 ... 85 °C (-4 ... 185 °F)

Relative humidity 90 %, noncondensing

**Mechanical specifications** 

8-pin, M12x1 connector, standard (supply+IO) 4-pin, M12x1 socket, D-coded (LAN) 4-pin, M12x1 socket, D-coded (LAN) Connection type

IP67

Material

PC/ABS Housing approx. 200 g

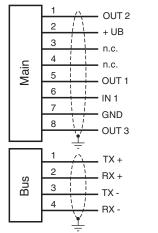
**Dimensions** 

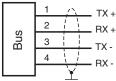
Refer to "General Notes Relating to Pepperl+Fuchs Product Information

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Technical Data	
Height	70 mm
Width	70 mm
Depth	50 mm
Factory settings	
X resolution (protocol)	1 mm
Y resolution (protocol)	1 mm
Code tape orientation	0 °
Address	0
"No Position" X value	0
"No Position" Y value	0
"No Position" speed value	127
Overspeed threshold (protocol)	12.5 m/s
X value in case of error	Error number
Y value in case of error	Error number
Speed value in case of error	Error number
Code tape width	two-rowed
X positon offset	0 mm
Function input/output	inactive

# Connection



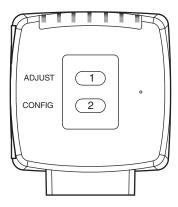


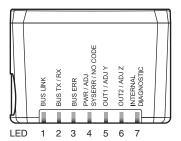
# **Connection Assignment**





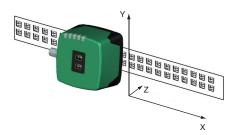
# Indication





# **Characteristic Curve**

## Coordinates



## **Additional Information**

#### General

The reading head is part of the positioning system in the method for measurement by Pepperl+Fuchs. It consists of a camera module and an integrated illumination unit among other things. The reading head detects position marks, which are put on an adhesive code band in the form of Data Matrix code. The mounting of the code band is as a rule stationary on a firm part of the plant (elevator shaft, overhead conveyor mounting rails...); that of the reading head is parallel on the moving "vehicle" (elevator car, overhead conveyor chassis...).

## Mounting and commissioning

Mount the reading head such that its optical surface captures the optimal read distance to the code band (see Technical Data). The stability of the mounting and the guidance of the vehicle must be provided such that the depth of field of the reading head is not closed during operation. All reading heads can be optimally customized by parameterization for specific requirements.

#### **Displays and Controls**

The reading head allows visual function check and fast diagnosis with 7 indicator LEDs. The reading head has 2 buttons on the reverse of the device to activate the alignment aid and parameterization mode.

## **LEDs**

LED	Color	Label	Meaning
1	green	BUS LINK	PROFINET communication active
2	yellow	BUS TX / RX	Data transfer
3	red	BUS ERR	PROFINET communication Error
4	red / green	PWR / ADJ SYSERR / NO CODE	Code recognized / not recognized, Error
5	yellow	OUT1/ADJ Y	Output 1, Alignment aid Y
6	yellow	OUT2/ADJ Z	Output 2, Alignment aid Z
7	red/green/yellow	INTERNAL DIAGNOSTIC	Internal diagnostics

## Alignment aid for the Y and Z coordinates

The activation of the alignment aid is only possible within 10 minutes of switching on the reading head. The switchover from normal operation to "alignment aid operating mode is via button 1 on the reverse of the reading head.

- Press the button 1 for longer than 2 s. LED4 flashes green for a recognized code band. LED4 flashes red for an unrecognized code band.
- Z coordinate: If the distance of the camera to the code band too small, the yellow LED6 lights up. If the distance of the camera to the code
  band too large, the yellow LED6 lights up. Within the target range, the yellow LED6 flashes at the same time as the green LED4.
- Y coordinate: If the optical axis of the camera is too deep in relation to the middle of the code band, the yellow LED5 lights up. If the optical axis is too high, the yellow LED5 extinguishes. Within the target range, the yellow LED5 flashes at the same time as the green LED4.
- A short press on button 1 ends the alignment aid and the reading head changes to normal operation.