LGM Series

Measuring Automation Light Grid

Brief Instructions



e IO-Link CE



Your automation, our passion.



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1 Introduction

1.1 Purpose of These Brief Instructions

These brief instructions contains basic instructions for operating the device. However, the manual takes priority over the brief instructions.

1.2 Product documentation on the internet

You can view all the relevant documentation and additional information on your product at http://www.pepperl-fuchs.com. Simply enter the product name or model number in the **Product/Key word search** box and click **Search**.

| EPPPERL+FUCHS Your automation, our passion. | | | | | |
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Select your product from the list of search results. Click on the information you require in the product information list, e.g., **Technical documents**.

Datasheet Documents CAD+CAE Approvals+Certificates Associated Products

A list of all available documents is displayed.

1.3 Intended Use

The measuring LGM light grid consists of an emitter and receiver strip. Located between the strips is the measuring range consisting of infrared light beams. When an object enters the measurement field, one of several selectable measuring methods sends out data on the interrupted beams via I/O-Link. The reading is in mm.

Application areas

Warehousing and material handling, packaging industry



Caution!

Not a safety component

The light grid is not a certified safety light grid in accordance with EN 61496. It is also not a safety component under the terms of the EU Machinery Directive 2006/42/EC. The light grid must therefore not be used for the purpose of preventing risk to individuals or parts of the body.

Always operate the device as described in these instructions to ensure that the device and connected systems function correctly. The protection of operating personnel and plant is guaranteed only if the device is operated in accordance with its intended use.

The device and its input and output circuits must be operated from a power supply that fulfills the requirements of PELV/SELV systems.

Only use recommended original accessories.

The operating company bears responsibility for observing locally applicable safety regulations.

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Installation and commissioning of all devices may be performed only by trained and qualified personnel.

It is dangerous for the user to make changes and/or repairs. Additionally, doing so voids the warranty and excludes the manufacturer from any liability. In the event of any serious errors, stop using the device. Secure the device against unintended operation. To have the device repaired, return it to your local Pepperl+Fuchs representative or your sales center.



Note

Repairs

If the light grid requires repair, please send the emitter **and** receiver together to Pepperl+Fuchs.

2 Product Description

2.1 Indicators and Control elements

Emitter unit



Figure 2.1 Function indicator on the emitter unit

(2) Operation indicator: indicates power-on or power-save mode

(3) Status indicator: indicates transmission power, fault state, or active test mode

Operation indicator and status indicator on the emitter

| Function | Diagnostic description | | |
|--------------------------------------|--------------------------|--|--|
| Operation indicator (green LED) | | | |
| Green LED on | Power-on | | |
| Green LED off Yellow LED flashing | Power-save mode | | |
| Status indicator (yellow LED) | | | |
| Yellow LED off | Power of emitter is low | | |
| Yellow LED is on | Power of emitter is high | | |
| Yellow LED flashing | Fault state | | |
| Yellow LED changes state | Test mode is active | | |

Receiver unit



Figure 2.2 Function indicator on the receiver unit

Operation indicator: indicates power-on, power-save mode, IO-Link mode aktive, or fault state

3 Status indicator: indicates detection field status, functional reserve, or fault state



| Function | Diagnostic Description | | | |
|--|---|--|--|--|
| Operation indicator (green LED) | | | | |
| Green LED permanently on | Power-on | | | |
| Green LED permanently off | Power-save mode | | | |
| Green LED flashes with short interrup- tion | Active IO-Link mode, receiver's operat- ing panel locked | | | |
| Green LED flashes with 4 Hz | Fault status: short circuit at the outputs | | | |
| Status indicator (yellow LED) | | | | |
| Yellow LED permanently on | Detection field interrupted | | | |
| Yellow LED permanently off | Detection field vacant | | | |
| Yellow LED flashes (approx. 4 Hz) | Insufficient functional reserve | | | |
| Yellow LED flashes (approx. 8 Hz) | Fault state: fault during signal measure- ment | | | |

Operation indicator and status indicator on the receiver

The control panel on the receiver unit consists of 12 indicator elements. The two outer two symbols act as control elements (touch buttons). The receiver unit can be parametrized via menu selection on the control panel (see chapter 5.1).



Figure 2.3

Controls on the Receiver unit

| Number | Symbol | Parameter | Description | | |
|--------|--------|-------------|-----------------------|--|--|
| 1 | | Menu button | Function selection | | |
| (12) | | OK button | Function confirmation | | |

For a detailed description of the function status indicators, please see see chapter 5.1.

2.2 Interfaces and Connections

Use two M12 plugs for the electrical connection. The emitter unit has a cable with a 4-pin plug and the receiver unit a cable with an 8-pin plug.

Emitter unit



4 Test (In)

Receiver unit





Figure 2.5 Receiver unit connection layout

- 1 + UB
- 2 SC (Stability Control, Out)
- 3 0 V DC
- 4 C/Q (IO-Link / Out)
- 5 Q (Out)
- 6 not connected
- 7 not connected
- 8 Teach-In (In)

IO-Link communication is established via the C/Q (Pin 4) connection.

2.3 Scope of Delivery

The scope of delivery includes:

- Emitter unit and receiver unit
- Quick start guide
- Cable lug and housing screw as spare part

Brackets and cables are not included in the scope of delivery. See the appendix or visit http://www.pepperl-fuchs.com for a selection of compatible mounting brackets and recommended cables.

3 Installation

3.1 Mounting

Make sure the detection field is free from obstacles. The first and last beams within the detection field are used for optical synchronization of emitter and receiver units. If both beams are blocked, synchronization is lost and the measurement is inhibited. The system is preconfigured for operation with cable outlet upwards. For installation with cable outlet outwards, the receiver unit can be configured via IO-Link for the zero-point reference on the cable side.



Figure 3.1 Light Grid Dimension Drawing

To mount the slim panels, use customized bore holes (d = 4.5 mm for M4 screws) or a rear, continuous groove (for flat M6 nuts in accordance with ISO 4035).

Various brackets are available for mounting the light grid .

Mounting Using the Rear Groove

There is a continuous groove located on the rear of the strip on the light grid. Standard flat M6 nuts (in accordance with DIN 4035) fit into this groove. You can mount the light grid using these inserted nuts.

Mounting Using Customized Bore Holes

You can mount the light grid using user-defined holes. The maximum screw size is M4. Make sure to follow the instructions when positioning the hole. Improper handling can damage internal electronics.







Preparation

- 1. Mark the position of the holes. Focus on the lateral continuous line on the light grid
- 2. Mark the position of the holes.
- 3. Using a 4.5 diameter drill, drill right through the housing.
- **4.** Deburr the hole.
- 5. Repeat the first steps to drill all the holes.
- 6. Make sure that the aluminum chippings do not scratch the optical surface.

Secure the light grid in its final position with the holes you made.



Figure 3.2

Position the center point of the installation holes.



Figure 3.3



Installation

- 1. Align the emitter and receiver units so they are parallel to one another and at the same height.
- 2. The units must be aligned with an accuracy of approximately ± 5°.
- 3. During installation, ensure that the two units are the same way up. (Both units with the cable outlet either up or down).
- 4. Do not exceed the maximum range.





Figure 3.4 Maximum offset between emitter and receiver

3.2 Connecting the Sensor Units



Caution!

Electrical connection

Wiring work that requires the opening and closing of electrical connections must always be performed with the power disconnected.

Use a Class 2 power supply to supply the power (certified according to UL 1310).

Connecting the Emitter unit

Connect the emitter unit as described in the section Interfaces and Connections (see chapter 2.2). Insulate unused wires. See circuit example on the following page.

| Connection | Description | | |
|----------------------|---|--|--|
| Range input Pin 2 | The emitter power can be ing ranges according to a Reducing emitter power is interference with other set | adjusted for specific sens- oplication requirements. s useful for avoiding optical nsors. | |
| | Input open | Max. 1.6 m | |
| | +U _B | Max.6 m | |
| | 0 V | Max. 6 m | |



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Installation

| Connection | Description | | |
|---------------------|--|---|--|
| Test input Pin 4 | The emitter unit features a test input with two func- tionalities: • test mode • power safe mode These functionalities can be activated by connection of the test input to either $+U_B$ or 0 V. The functions are inactive if the test pin is left open (high imped- ance) | | |
| | Test mode: | Activate the test input for max. 1.2 seconds. The emitter beams are turned off. The receiver unit will detect this the same way as a beam interruption by an object. | |
| | Power save mode: | Test input is active for more than 1.2 seconds: The emitter unit enters the power save mode. The receiver unit will change to power save mode if optically synchro- nized with the emitter. The measurement is inhibited in this mode and power consumption is reduced to minimum. Test input set to to inactive: Emitter and receiver units resume to normal opera- tion. Note: The receiver unit as well resumes to normal operation if the optical synchronization is lost. | |

Connecting the Receiver unit

Connect the receiver unit as described in the section Interfaces and Connections (see chapter 2.2). All outputs are short-circuit proof. Insulate unused wires. See circuit example shown below.



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| Connection | Description |
|--|---|
| Stability control (SC) output Pin 2 | The SC output gets active with a delay of 5 seconds, if the receiver unit detects signals below stability control thresh- old (functional reserve). The status indi- cator flashes at 4 Hz. The SC output returns immediately to normal opera- tion (inactive state) with receiver sig- nals above the stability control threshold. |
| Switching output (C/Q) Pin 4 | This connection has 2 functions. (By default, the switching output is active once the device is powered on; SIO mode) Switching output: This signal output is active (active with dark ON, inactive with light ON) if an object is detected or identified according to parameter settings. This means that the output is always active when status indicator 4 (Q) is on. IO-Link interface: When the light grid is running in IO-Link mode, it communicates with the master via this connection. |
| Remote control (Teach-in input) Pin 8 | The receiver unit features a Teach-in input. This input can be used to remotely stimulate the functions of the two control buttons: • Menu button (input connected to $+U_B$) • OK button (input connected to 0 V) (see circuit example below) Note: The Teach-in input functionality can be inhibited by connecting this terminal permanently to $+U_B$. |

Circuit Example

The LEDs on the outputs are optional.





Figure 3.5

Circuit example LGM

4

Commissioning the Light Grid



- 1. Check that the power supply and signal lines to the light grid are connected correctly. When using an IO-Link Master, make sure that the C/Q communication line is connected to the corresponding port on the IO-Link master.
- 2. Check that the light grid is in the correct position and orientation.
- Turn on the power supply. The green operation indicators on emitter and receiver units are on.
- 4. If the emitter and receiver units are aligned, the status indicator is off. The status indicator lights up when the device is misaligned or an object is detected.

→ The two units are perfectly aligned and can now be configured .

For commissioning and operation of the light grid in IO-Link mode, please refer see chapter 5.2.



Operation

5 Operation

5.1 Operating the Light Grid Using the Programming Interface

The Receiver Strip Can Be Manually Configured and Parameterized Using the Programming Interface

- Standard operation in accordance with configuration and parameterized values
- Functions of first parameterization level
- Functions of second parameterization level

Displays and Operating Elements



Figure 5.1

Function indicators on the receiver strip

| Number | Symbol | Function | Description |
|--------|------------|--------------------------|--|
| 1 | | Menu key | Press the Menu key once to switch the device to parameterization mode. |
| 2 | | Operating indi- cator | Indicator for operating state and power save mode |
| 3 | \bigcirc | Status indica- tor | Indicator for detection field status, oper- ating reserve status, and fault status |
| 4 | Q | Q display | Display for object identification status and, in general, for detection field sta- tus |

| Number | Symbol | Function | Description |
|---|--------|----------|--|
| (12) | | OK key | Press OK once to display the parame- terization status. (First-level functions) |
| The other indicators have no function in standard operation | | | |

Table 5.1 Display and function in standard operation

When you select a function, the current status of this function is displayed within parameterization mode. The indicator flashes at approx. 1 Hz according to the following pattern:

| Display mode | Display pattern |
|--------------|--------------------|
| Active | Long on, short off |
| Inactive | Long off, short on |

The following table shows the indicators and functions of the programming interface in parameterization mode.

| Number | Sym- bol Parameter | | Display mode | Description |
|------------|-----------------------|---------------------------------|-----------------|--|
| | \mathbb{Z} | Menu key | | Repeatedly press the Menu key to select the required parameterization function |
| (12) | | OK key | | Press OK to modify a value or to initi- ate the selected function |
| | Q | Q display | | Object identification function selected |
| (4) | | Inactive | Inactive | Reset parameters for object identification |
| | | Active | Active | Teach-in parameters for object identi- fication |
| (8) | С С Д | Object identifica- tion type | | Object identification type function selected |
| | ~ | Stationary | Inactive | Identification of stationary objects selected |
| | | Moving | Active | Identification of moving objects selected |
| \bigcirc | | Beam mode | | Beam mode function selected |
| 9 | M. | Single-beam scan- ning | Inactive | Simple resolution Corresponds to the beam spacing |
| | | Three-way beam crossover | Active | Double resolution |

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| Number | Sym- bol | Parameter | Display mode | Description |
|--------|-------------|---------------------------------|-----------------|--|
| 10 | | Tolerance field | | Tolerance field function selected (applies to object field, gaps, and suppression area) |
| | | Off | Inactive | No tolerance applied |
| | | Simple resolution | Active | Tolerance corresponds to resolution set |
| (11) | F2 | 2. Level (Skip/Select) | | Second-level functions selected In the second level, the F2 indicator lights up in combination with the selected function |
| (1) | F2Q | Suppression area | | Suppression areas function selected |
| \cup | | Inactive | Inactive | Suppression areas are deactivated |
| 4 | | Active | Active | Suppression area corresponds to taught-in values |
| (11) | F2H1 | Object identifica- tion mode | | Object identification function selected |
| | | Object detection | Inactive | Object identification in accordance with taught-in parameters |
| (5) | | Gap detection | Active | Gap detection in accordance with taught-in parameters |
| (11) | F2H2 | Switching signal polarity | | Switching signal polarity function selected |
| | | Not inverted – dark- on | Inactive | Output Q is activated if an object/gap is detected |
| 6 | | Inverted – light-on | Active | Output Q is activated if no object/gap is detected |
| (1) | F2H3 | Default settings | | Default settings function selected |
| \cup | | Skip | Inactive | The function is not executed |
| (7) | | Restore | Active | The default settings are restored |

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| Number | Sym- bol | Parameter | Display mode | Description |
|---------|--------------------|-----------------|-----------------|--|
| 11 8 | F2 ^Û ↓○ | Signal tracking | | Signal tracking function selected In non-stable ambient conditions, e.g., soiling and temperature changes, signal tracking ensures that the response threshold remains con- stant. Reflective objects that are occasionally present along the detec- tion field can distort signal tracking and cause switching faults. In the worst-case scenario, permanent detection is signaled even though there is no object in the monitoring field. In this case, the function must be disabled. Signal tracking is inac- tive in the factory setting. Parameterization via IO-Link: Parameterization via IO-Link allows the response threshold and signal tracking to be defined independently of each other. => Without tracking: The response threshold can be selected in 10 % increments between 0 = minimum threshold, 1 = 10 %, and 9 = 90 %. • 0 = minimum threshold, no tracking, maximum gain, default value • 1 = 10 % of value of response thresh- old, no tracking |
| | | | | 9 = 90 % of value of response threshold, no tracking > With tracking: The response threshold that can be freely selected, with trackingld can be freely selected between 10 % 90 %. This allows customized configuration between fine resolution (high threshold) and high immunity to reflective objects (low threshold). 10 % 90 % = value for response threshold that can be freely selected, with tracking |
| | | Inactive | Inactive | Pressing the OK button again dis- ables signal tracking. When signal tracking is disabled, the lowest switching threshold is configured. The optical resolution is increased by \leq 4 mm. |
| | | Active | Active | Pressing the OK button enables sig- nal tracking. When signal tracking is enabled, the specified resolution is reached. The value of the switching threshold is set to \geq 60 %. |





Operation

| | Sym- | 2 | Display | |
|-----------|---------------------------------|---|--|---|
| Number | bol | Parameter | mode | Description |
| Table 5.2 | Parar | meterization and displays | for first-level and s | second-level functions |
| | 0 | nation Common o | | |
| | Ope | rating Sequence | | |
| | Pres flash | es the menu H nes to signal active para | key to activate p ameterization. | parameterization. The Q object symbol |
| | Pres to th | s the menu k e previous table. The c | ey repeatedly to orresponding in | o select the required function according idicator begins to flash. |
| | _ | | | |
| | Pres selee | s the OK key 议 to cted function, e.g., to te | each in parame | n permitted values or to start the ters or to reset to default settings. |
| | Befo locat seleo devio | ore object or suppression ted in the detection fiel cted function are reset. ce switches to LGM mo | on area teach-in d. Without locat On selecting th ode (light grid m | the corresponding object must be ing an object, the parameters of the ne object identification function, the node) see chapter 5.2.2. |
| | lf the para | e subsequent function i meters and values are | s selected or pa saved permane | arameterization mode is exited, the ently. |
| | lf the mod withi para | menu key is e is exited. The indicate in a period of 30 secon meters are retained. | F s pressed with or stops flashing ds, parameteriz | ⁷² display selected, parameterization g. If no operating buttons are pressed ation automatically ends. Modified |
| | The | current parameterized | status can be d | isplayed by briefly pressing the OK key |
| | five s | . The activated functi seconds. | ions of the first p | parameterization level are displayed for |
| | | Symbol dimly lit: fund | ction is not conf | igured or has been disabled |
| | E ar i | Symbol brightly lit: fu | inction is param | leterized or activated |
| | FULL | mormation on operatin | y via an externa | a connection, see see chapter 3.2. |
| | Fac | tory Sottings | | |
| | Tore | store the factory settin | ias proceed as | follows: |
| | 1010 | | | lollows. |
| | 1. Pres | s the Menu button | to enter p | parameterization mode. |
| | 2. Pres | s the Menu button | | lly until the "F2" icon starts flashing. |
| | 3. Pres | ss the Menu button 🕅 | . This will tak | e you to the 2 nd parameterization level. |
| | 4. Pres | s the Menu button | | lly until the "H3" icon starts flashing. |

└→ If you now press the OK button , the light grid will be restored to its factory settings..



There are no parameterized objects or functions on delivery.

| Number | Symbol | Parameter | Status |
|--------|-------------------|----------------------------|--------------------------|
| 8 | Ŷ ₽ | Object identification type | Moving |
| 9 | | Beam mode | Three-way beam crossover |
| 10 | 0 | Tolerance field | Simple resolution |
| 4 | F _{2Q} | Suppression area | Inactive |
| 5 | F2H1 | Object identification mode | Object detection |
| 6 | F2H2 | Switching signal polarity | Not inverted (dark-on) |
| 8 | F2 ^Û ∪ | Signal tracking | Inactive |

Default settings

Table 5.3 Default settings

Commissioning and Operating the Light Grid with IO-Link



5.2

Commissioning with IO-Link

To activate the sensor via the IO-Link, proceed with the following steps:

- 1. Set the corresponding port on the IO-Link master to which the sensor is connected to IO-Link status.
- 2. When communication is successfully established, the green operating indicator flashes with short interruptions every second.
 - → The sensor now transmits process data and can be parametrized or diagnosis can be run.



Use preset parameters to configure, parameterize, and diagnose the sensors. To parameterize the sensors with an engineering tool, use the device description (IODD), which can be loaded into all system environments with IO-Link support. To operate the sensor in an FDT environment, you can also use a DTM.

See the device description and software, e.g., the IODD, DTM, and the FDT master application within the product at www.pepperl-fuchs.com/io-link.

5.2.1 Process Data

The process data is transmitted as a 16-bit word.

The following illustration shows the data structure using bit offsets:

| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------|----|----|----|----|----|---|-----|------|------|---------|-------|---|---|---|---|
| measurement value | | | | | | | | 0 | bina | ary sig | jnals | | | | |
| ADC1[11:0] | | | | | | | res | BDC3 | BDC2 | BDC1 | | | | | |

Assignment of process data:

BDC1 - binary data channel 1: switching signal

| The switching signal bit indicates if an object is in the beam path, or if an object has been detected | | | | |
|--|--|--|--|--|
| Data type: boo Bit offset: 0 | I | | | |
| BDC1 = 0 | No object in the beam path or no object detected | | | |
| BDC1 = 1 | One or more objects in the beam path, or an object has been detected | | | |

BDC2 - binary data channel 2: synchronization

The synchronization bit indicates if either of the two synchronization beams was detected by the receiver

| Data type: bool Bit offset: 1 | | | |
|----------------------------------|-----------------------------|--|--|
| BDC2 = 0 | Light grid not synchronized | | |
| BDC2 = 1 | Light grid synchronized | | |

BDC3 - binary data channel 3: functional reserve

The functional reserve bit indicates if the light grid is running in the stable operating range, or if it is already in the functional reserve (above or below the functional reserve threshold)

| Data type: boo Bit offset: 2 | 1 |
|---------------------------------|--|
| BDC3 = 0 | Stability control inactive (stable operation range) |
| BDC3 = 1 | Stability control active (signal below functional resreve threshold) |

res: reserved

This bit is not used. The value is always "0". Bit offset: 2

ADC1 - analog data channel 1: measurement value

| Output of measurement value (in mm) | | | | |
|---|--|--|--|--|
| Data type: unsigned integer Length: 12 bits Bit offset: 4 | | | | |
| ADC1 = 0 3200 | Measured value depends on the selected measurement value mode (the value range depends on the length of the detection field) | | | |
| ADC1 = 3201 4094 | Not permitted | | | |
| ADC1 = 4095 | Invalid measurement value, no synchronization | | | |

5.2.2 Programmable Functions of the Light Grid

Measurement Value Mode

The light grid can be parametrized to different measurement value modes via IO-Link.

The followings diagram shows an overview of all measurement value modes.



Figure 5.2 Overview of all the Light Grid's Measurement Value Modes

The measured values are based on the zero point reference in unit of millimeteres (mm). For operation with cable outlet downwards, the receiver unit can be configured via IO-Link for the zero-point reference on the cable side.

List of Abbreviations

| Abbrevia | tion | Description | | | | |
|-----------|--|--|--|--|--|--|
| Object me | easurement | | | | | |
| FBB | First beam blocked | Lowest object position (based on the zero point reference) | | | | |
| LBB | Last beam blocked | Highest object position (based on the zero point reference) | | | | |
| NBB | Number of beams blocked | Object height from lowest to highest position, NBB = LBB - FBB | | | | |
| ТВВ | Total beams blocked | Total object height of all partial objects | | | | |
| NCBB | Number of consecutive beams blocked | Height of the largest partial object | | | | |
| CBB | Central beam blocked | Middle object position of the largest partial object (based on the zero point) | | | | |
| CFBB | Contiguous first beam blocked | Lowest position of the largest contiguous partial object | | | | |
| CLBB | Contiguous last beam blocked | Highest position of the largest contiguous partial object | | | | |
| MBB | Middle beam blocked | Middle object position across all partial objects (based on the zero point) | | | | |
| Gap meas | urement | | | | | |
| FBM | First beam made | Lowest gap position, across all partial objects, on the upper edge of the lowest partial object | | | | |
| LBM | Last beam made | Highest gap position, across all partial objects, on the lowest edge of the highest partial object | | | | |
| NBM | Number of beams made | Gap height within all partial objects, across all par- tial objects, NBM = LBM – FBM | | | | |
| ТВМ | Total beams made | Gap height as the sum of all gap areas within the upper object limits | | | | |
| NCBM | Number of consecutive beams made | Gap height of the largest contiguous gap area, within the outer object limits | | | | |
| СВМ | Central beam made | Middle gap position of the largest contiguous gap area, within the outer object limits | | | | |
| Additiona | I functions | | | | | |
| TRN | Number of TRraNsitions | Number of status transitions from "interrupted beam" to "uninterrupted beam" and vice versa. If the number is odd, one of the two synchronous beams has been interrupted by an object. The value is a unitless number. | | | | |



Object identification

The light grid can identify solid objects or object with gaps by evaluation of interrupted beams. The switching signal Q is active if a object is detected or identified.





List of Abbreviations

| Abbrevia | tion | Description |
|----------|--------------------------------|--|
| LGM | Light grid mode | Any object is detected if at least one beam is inter- rupted within the detection field and outside te blanking fields. |
| OBJF | Floating object identification | A floating object is detected if the height corre- sponds to the distance of the parametrized posi- tions of the object field. |
| OBJS | Static object identification | An object is detected if the upper and lower limits match the parametrized positions of the object field. |
| GAPF | Floating gap identification | An object is detected if the gap height matches the distance of the parametrized positions of the gap field. |
| GAPS | Static gap identification | An object is detected if the upper and lower limits of a gap match the parametrized positions of the gap field. |
| DDF | Defined detec- tion field | Any object is detected if at least one beam is inter- rupted within the parametrized positions of the object field and outside of the blanking fields. |

Blanking fields

You can parametrize up to 2 blanking fields in the light grid. These fields are parameterized and activated independently. The object identification and evaluation of measurement values functions are not possible within blanking fields.

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6 Appendix

6.1 Technical Data

General specifications

| Effective detection range | Standard : 0.3 6 m |
|---------------------------|--|
| Threshold detection range | 7.5 m |
| Light source | IRED |
| Light type | modulated infrared light, 850 nm |
| Detection field | |
| Beam mode | Factory setting: three beam crossing, deactivateable |
| Blanking fields | max. 2 blanking fields, adjustable |
| Beam spacing | LGM8 = 8.33 mm; LGM17 = 16.67 mm; LGM25 = 25 mm; LGM50 = 50 mm |
| Number of beams | |
| Operation mode | Emitter: Emitter power adjustable in two ranges |
| Optical resolution | With single beam scan: see beam spacing With three beam crossing: 4/8.5/12.5/25/50 mm. Only in the range of 25 $\%$ 75 $\%$ of the detection field |
| Angle of divergence | 10 ° |
| Ambient light limit | > 50000 Lux (if external light source is outside the open- ing angle) |

Functional safety related parameters

| | LGM8 | LGM17 | LGM25 | LGM50 |
|-----------------------------|------|-------|-------|-------|
| MTTF _d | 21 a | 25 a | 34 a | 56 a |
| Mission Time (T_M) | 20 a | 20 a | 20 a | 20 a |
| Diagnostic Coverage (DC) | 60 % | 60 % | 60 % | 60 % |

Indicators/operating means

| Operation indicator | LED green: constantly on - power-on double pulse flashing (0.8 Hz) - undervoltage |
|---------------------|---|
| | flashing with short interruptions (1 Hz) - IO-Link mode |
| Status indicator | Emitter: LED yellow constantly on - high emitter power constantly off - low emitter power flashing (8 Hz) - error message Receiver: LED yellow: constantly on - object detected constantly off - no object detected flashing (4 Hz) - below stability control limit flashing (8 Hz) - error message |
| Control elements | Receiver: 2 touch buttons for programming |

Electrical specifications

| Operating voltage | 18 30 V DC |
|------------------------|--|
| Ripple | 10 % |
| No-load supply current | Emitter ≤: 50 mA Receiver: ≤ 150 mA (without outputs) |
| Time delay hofers | |

Time delay before availability

Interface

| Interface type | IO-Link (pin 4) |
|--------------------|-------------------------------------|
| IO-Link revision | 1.0 |
| COM-Mode | COM 2 (38.4 kBaud) |
| Min. cycle time | 2.3 ms |
| Process data width | 16 bit |
| SIO mode support | yes |
| Device ID | 1050369 1050400 (0x100701 0x100720) |

Input

| Test input | Emitter switch-off with +UB or 0 V at pin 4 (emitter) |
|----------------|--|
| Function input | Range input activation from 1.6 m with +UB or 0 V on pin 2 (emitter) Teach-In input for parameterization on pin 8 (receiver) |

Output

| Pre-fault indication output | Stability Control (SC) 1 PNP, short-circuit protected, reverse polarity protected on pin 2 (receiver) |
|-----------------------------|---|
| Switching type | Factory setting: dark on , Switchable to light-on mode |





LGM Series Appendix

| Signal output | Command interface: Pin 4 IO-Link interface C or used as switching output Q; 1 short-circuit proof reverse polarity protected push-pull output (receiver) Switch output: Pin 5 switching output Q; 1 short-circuit proof reverse polarity protected push-pull output (receiver) synchronized with pin 4 |
|---------------------|---|
| Switching threshold | Factory setting: The signal tracking for the threshold value is deactivated, increasing the optical resolution by a maximum of 4 mm; switchable to active signal tracking |
| Switching voltage | max. 30 V DC |
| Switching current | max. 100 mA |
| Voltage drop | ≤2VDC |
| Switching frequency | |
| Response time | |
| Timer function | Off-delay programmable from 0 1.25 s in 5 ms steps (adjustment via IO-Link only) |

Conformity

| Communication inter- face | IEC 61131-9 |
|------------------------------|--------------|
| Product standard | EN 60947-5-2 |

Approvals and certificates

| Protection class | III (IEC 61140) |
|------------------|--|
| UL approval | cULus Listed |
| CCC approval | CCC approval / marking not required for products rated ${\leq}36~\text{V}$ |

Ambient conditions

| Ambient temperature | -30 60 °C (-22 140 °F) |
|---------------------|------------------------|
| Storage temperature | -30 70 °C (-22 158 °F) |

Mechanical specifications

| - | |
|------------------------------|---|
| Conductor cross sec- tion | min. 0.25 mm ² |
| Housing length L | |
| Degree of protection | IP67 |
| Connection | Emitter: connecting cable with 4-pin, M12 x 1 connector , 330 mm total length Receiver: connecting cable with 8-pin, M12 x 1 connec- tor , 350 mm total length |
| Material | 120 |

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LGM Series

Appendix

| Housing | extruded aluminum section , Silver anodized |
|--------------|---|
| Optical face | Plastic pane, Polycarbonate |
| Mass | |
| Cable length | max. 30 m |

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Explosion Protection

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- Signal Conditioners
- FieldConnex[®] Fieldbus
- Remote I/O Systems
- Electrical Ex Equipment
- Purge and Pressurization
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- Mobile Computing and Communications
- HART Interface Solutions
- Surge Protection
- Wireless Solutions
- Level Measurement

Industrial Sensors

- Proximity Sensors
- Photoelectric Sensors
- Industrial Vision
- Ultrasonic Sensors
- Rotary Encoders
- Positioning Systems
- Inclination and Acceleration Sensors
- Fieldbus Modules
- AS-Interface
- Identification Systems
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