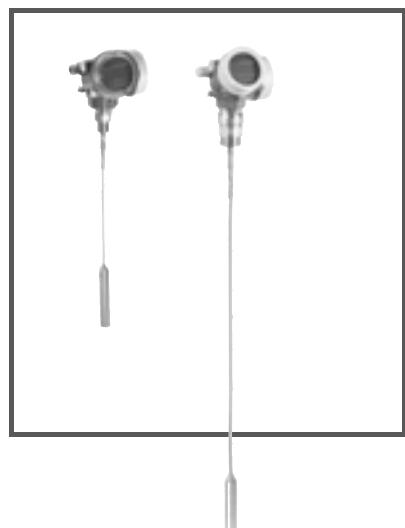


## MANUAL

# Pulscon LTC57 HART Guided Level Radar

### Level measurement in bulk solids



**SIL3**





With regard to the supply of products, the current issue of the following document is applicable:

The General Terms of Delivery for Products and Services of the Electrical Industry,  
published by the Central Association of the Electrical Industry (Zentralverband Elektrotechnik und  
Elektroindustrie (ZVEI) e.V.) in its most recent version as well as the supplementary clause:  
"Expanded reservation of proprietorship"



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## 1 Important document information

### 1.1 Document function

These Operating Instructions contain all the information that is required in various phases of the life cycle of the device: from product identification, incoming acceptance and storage, to mounting, connection, operation and commissioning through to troubleshooting, maintenance and disposal.

### 1.2 Symbols

#### 1.2.1 Symbols used

This document contains information that you must read for your own personal safety and to avoid property damage. Depending on the risk level, the warning messages are displayed in descending order as follows:

##### Safety-relevant symbols



###### **Danger!**

This symbol indicates an imminent danger.

Non-observance will result in personal injury or death.



###### **Warning!**

This symbol indicates a possible fault or danger.

Non-observance may cause personal injury or serious property damage.



###### **Caution!**

This symbol indicates a possible fault.

Non-observance could interrupt the device and any connected systems and plants, or result in their complete failure.

##### Informative symbols



###### **Note!**

This symbol brings important information to your attention.



###### Action

This symbol indicates a paragraph with instructions.



## 1.2.2

### Electrical symbols

Symbol	Meaning
	<b>Direct current</b> A terminal to which DC voltage is applied or through which direct current flows.
	<b>Alternating current</b> A terminal to which alternating voltage is applied or through which alternating current flows.
	<b>Direct current and alternating current</b> <ul style="list-style-type: none"><li>A terminal to which alternating voltage or DC voltage is applied.</li><li>A terminal through which alternating current or direct current flows.</li></ul>
	<b>Ground connection</b> A grounded terminal which, as far as the operator is concerned, is grounded via a grounding system.
	<b>Protective ground connection</b> A terminal which must be connected to ground prior to establishing any other connections.
	<b>Equipotential connection</b> A connection that has to be connected to the plant grounding system: This may be a potential equalization line or a star grounding system depending on national or company codes of practice.

Table 1.1

## 1.2.3

### Tool symbols

Symbol	Meaning
	Torx screwdriver
	Flat blade screwdriver
	Cross-head screwdriver
	Allen key
	Hexagon wrench

Table 1.2



#### 1.2.4

#### Symbols for certain types of information

Symbol	Meaning
	<b>Allowed</b> Indicates procedures, processes or actions that are allowed.
	<b>Preferred</b> Indicates procedures, processes or actions that are preferred.
	<b>Forbidden</b> Indicates procedures, processes or actions that are forbidden.
	<b>Series of steps</b>
	<b>Result of a sequence of actions</b>

Table 1.3

#### 1.2.5

#### Symbols in graphics

Symbol	Meaning
	Item numbers
	Series of steps
	Views
	Sections
	<b>Hazardous area</b> Indicates a hazardous area.
	<b>Safe area (non-hazardous area)</b> Indicates a non-hazardous location.

Table 1.4

#### 1.2.6

#### Symbols at the device

Symbol	Meaning
	<b>Safety instructions</b> Observe the safety instructions contained in the associated Operating Instructions.
	<b>Temperature resistance of the connection cables</b> Specifies the minimum value of the temperature resistance of the connection cables.

Table 1.5

## 1.3

### Supplementary documentation

Document	Purpose and content of the document
Technical Information TI01004O (LTC57)	<b>Planning aid for your device</b> The document contains all the technical data on the device and provides an overview of the accessories and other products that can be ordered for the device.
Brief Operating Instructions KA01061O (LTC57, HART)	<b>Guide that takes you quickly to the 1st measured value</b> The Brief Operating Instructions contain all the essential information from incoming acceptance to initial commissioning.
Description of Device Parameters GP01000O (LTC5X, HART)	<b>Reference for your parameters</b> The document provides a detailed explanation of each individual parameter in the operating menu. The description is aimed at those who work with the device over the entire life cycle and perform specific configurations.

Table 1.6



#### Note!

For an overview of the scope of the associated Technical Documentation, refer to [www.pepperl-fuchs.com](http://www.pepperl-fuchs.com).

#### 1.3.1

### Safety documentation

Depending on the approval, the following Safety instructions (SI) are supplied with the device. They are an integral part of the Operating instructions.

#### Safety instructions (SI)

Feature "Approval"	Approval	Feature "Electrical output"				
		Option IH <sup>a</sup>	Option ID <sup>b</sup>	Option IE <sup>c</sup>	Option PA <sup>d</sup>	Option AH <sup>e</sup> Option DH <sup>f</sup>
E1	ATEX II 1G Ex ia IIC T6-T1 Ga	SI00496O	SI01125O	SI01126O	SI00516O	-
EX	ATEX II 1/2G Ex ia IIC T6-T1 Ga/Gb	SI00496O	SI01125O	SI01126O	SI00516O	-
S3	ATEX II 1D Ex ta IIIC T <sub>500</sub> xx°C Da	SI00501O	SI00501O	SI00501O	SI00521O	SI00501O
S4	ATEX II 1/2D Ex ta IIIC Tx°C Da/Db	SI00501O	SI00501O	SI00501O	SI00521O	SI00501O
E3	ATEX II 3G Ex nA IIC T6-T1 Gc	SI00498O	SI01130O	SI01131O	SI00518O	SI01132O
E4	ATEX II 3G Ex ic IIC T6-T1 Gc	SI00498O	SI01130O	SI01131O	SI00518O	-
SX	ATEX II 1/2G Ex ia IIC T6-T1 Ga/Gb ATEX II 1/2D Ex ia IIIC Tx°C Da/Db	SI00502O	SI00502O	SI00502O	SI00522O	-
EG	ATEX II 1/2G Ex d [ia] IIC T6-T1 Ga/Gb ATEX II 1/2D Ex ta IIIC Tx°C Da/Db	SI00503O	SI00503O	SI00503O	SI00523O	SI01136O



Feature "Approval"	Approval	Feature "Electrical output"				
		Option IH <sup>a</sup>	Option ID <sup>b</sup>	Option IE <sup>c</sup>	Option PA <sup>d</sup>	Option AH <sup>e</sup> Option DH <sup>f</sup>
CD	CSA C/US DIP Cl.II,III Div.1 Gr.E-G	SI00529O	SI00529O	SI00529O	SI00570O	SI00529O
C1	CSA C/US IS Cl.I,II,III Div.1 Gr.A-G, NI Cl.1 Div.2, Ex ia	SI00530O	SI00530O	SI00530O	SI00571O	SI00530O
C2	CSA C/US XP Cl.I,II,III Div.1 Gr.A-G, NI Cl.1 Div.2, Ex d	SI00529O	SI00529O	SI00529O	SI00570O	SI00529O
FI	FM IS Cl.I,II,III Div.1 Gr.A-G, AEx ia, NI Cl.1 Div.2	SI00531O	SI00531O	SI00531O	SI00573O	SI00531O
FN	FM XP Cl.I,II,III Div.1 Gr.A-G, AEx d, NI Cl.1 Div.2	SI00532O	SI00532O	SI00532O	SI00572O	SI00532O
FE	FM DIP Cl.II,III Div.1 Gr.E-G	SI00532O	SI00532O	SI00532O	SI00572O	SI00532O
IA	IECEx Ex ia IIC T6-T1 Ga	SI00496O	SI01125O	SI01126O	SI00516O	-
IB	IECEx Ex ia IIC T6-T1 Ga/Gb	SI00496O	SI01125O	SI01126O	SI00516O	-
IE	IECEx Ex ta IIIC T <sub>500</sub> xx°C Da	SI00501O	SI00501O	SI00501O	SI00521O	SI00501O
IF	IECEx Ex ta IIIC Txx°C Da/Db	SI00501O	SI00501O	SI00501O	SI00521O	SI00501O
IG	IECEx Ex nA IIC T6-T1 Gc	SI00498O	SI01130O	SI01131O	SI00518O	SI01132O
IH	IECEx Ex ic IIC T6-T1 Gc	SI00498O	SI01130O	SI01131O	SI00518O	-

Table 1.7

- <sup>a</sup> Option IH: 2-wire, 4 ... 20 mA, HART
- <sup>b</sup> Option ID: 2-wire, 4 ... 20 mA, HART, switching output
- <sup>c</sup> Option IE: 2-wire, 4 ... 20 mA, HART, 4 ... 20 mA
- <sup>d</sup> Option PA: 2-wire, PROFIBUS PA, switching output
- <sup>e</sup> Option AH: 4-wire, 90 ... 253 V AC, 4 ... 20 mA, HART
- <sup>f</sup> Option DH: 4-wire, 10.4 ... 48 V DC, 4 ... 20 mA, HART



#### Note!

For certified devices the relevant Safety instructions (SI) are indicated on the nameplate.



## 2

# Basic safety instructions

### 2.1

## Requirements for the personnel

The personnel for installation, commissioning, diagnostics and maintenance must fulfill the following requirements:

- Trained, qualified specialists must have a relevant qualification for this specific function and task
- Are authorized by the plant owner/operator
- Are familiar with federal/national regulations
- Before beginning work, the specialist staff must have read and understood the instructions in the Operating Instructions and supplementary documentation as well as in the certificates (depending on the application)
- Following instructions and basic conditions

The operating personnel must fulfill the following requirements:

- Being instructed and authorized according to the requirements of the task by the facility's owner-operator
- Following the instructions in these Operating Instructions

### 2.2

## Designated use

### Application and measured materials

The measuring device described in these Operating Instructions is intended only for level measurement of bulk solids. Depending on the version ordered the device can also measure potentially explosive, flammable, poisonous and oxidizing materials.

Observing the limit values specified in the "Technical data" and listed in the Operating Instructions and supplementary documentation, the measuring device may be used for the following measurements only:

- Measured process variable: Level
- Calculated process variables: Volume or mass in arbitrarily shaped vessels (calculated from the level by the linearization functionality)

To ensure that the measuring device remains in proper condition for the operation time:

- Use the measuring device only for measured materials against which the process-wetted materials are adequately resistant.
- Observe the limit values in "Technical data".

### Incorrect use

The manufacturer is not liable for damage caused by improper or non-designated use.

Verification for borderline cases:

- For special measured materials and cleaning agents, Pepperl+Fuchs is glad to provide assistance in verifying the corrosion resistance of wetted materials, but does not accept any warranty or liability.



## Residual risk

The electronics housing and its built-in components such as display module, main electronics module and I/O electronics module may heat to 80 °C (176 °F) during operation through heat transfer from the process as well as power dissipation within the electronics. During operation the sensor may assume a temperature near the temperature of the measured material.

Danger of burns due to heated surfaces!

- For high process temperatures: Install protection against contact in order to prevent burns.

## 2.3

## Workplace safety

For work on and with the device:

- Wear the required personal protective equipment according to federal/national regulations.

## 2.4

## Operational safety

Risk of injury.

- Operate the device in proper technical condition and fail-safe condition only.
- The operator is responsible for interference-free operation of the device.

## Conversions to the device

Unauthorized modifications to the device are not permitted and can lead to unforeseeable dangers.

- If, despite this, modifications are required, consult with the manufacturer.

## Repair

To ensure continued operational safety and reliability,

- Carry out repairs on the device only if they are expressly permitted.
- Observe federal/national regulations pertaining to repair of an electrical device.
- Use original spare parts and accessories from the manufacturer only.

## Hazardous area

To eliminate a danger for persons or for the facility when the device is used in the hazardous area (e. g. explosion protection, pressure vessel safety):

- Based on the nameplate, check whether the ordered device is permitted for the intended use in the hazardous area.
- Observe the specifications in the separate supplementary documentation that is an integral part of these Instructions.

## 2.5

## Product safety

This measuring device is designed in accordance with good engineering practice to meet state-of-the-art safety requirements, has been tested, and left the factory in a condition in which they are safe to operate.

It meets general safety standards and legal requirements. It also complies with the EC directives listed in the device-specific EC Declaration of Conformity. Pepperl+Fuchs confirms this by affixing the CE mark to the device.



### 3 Product description

#### 3.1 Design

##### 3.1.1 Device

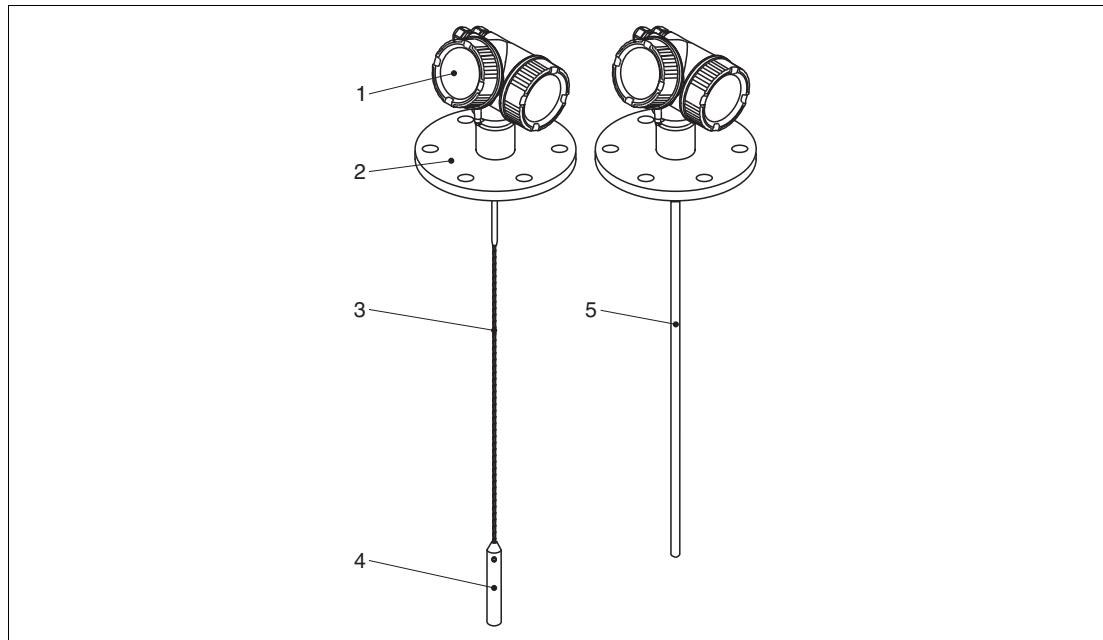


Figure 3.1 Design

- 1 Electronics housing
- 2 Process connection (here as an example: flange)
- 3 Rope probe
- 4 End-of-probe weight
- 5 Rod probe



### 3.1.2

### Electronics housing

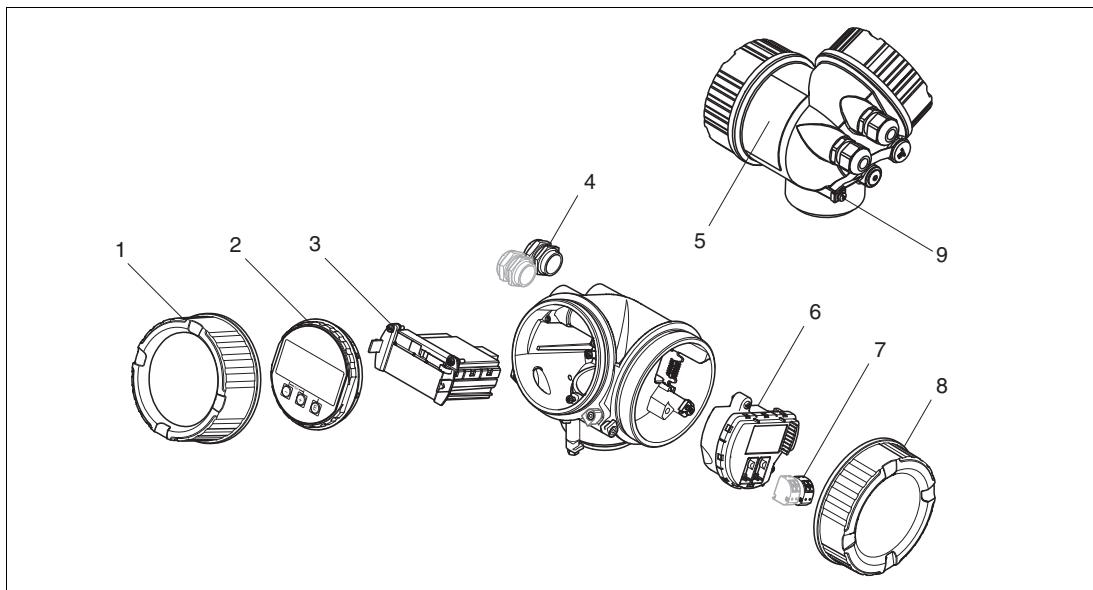


Figure 3.2 Design of the electronics housing

- 1 Electronics compartment cover
- 2 Display module
- 3 Main electronics module
- 4 Cable glands (1 or 2, depending on instrument version)
- 5 Nameplate
- 6 I/O electronics module
- 7 Terminals (pluggable spring terminals)
- 8 Connection compartment cover
- 9 Grounding terminal

### 3.2

### Registered trademarks

HART®

- Registered trademark of the HART Communication Foundation, Austin, USA

PROFIBUS®

- Registered trademark of the PROFIBUS User Organization, Karlsruhe, Germany

KALREZ®, VITON®

- Registered trademark of DuPont Performance Elastomers L.L.C., Wilmington, USA

TEFLON®

- Registered trademark of E.I. DuPont de Nemours & Co., Wilmington, USA

TRI CLAMP®

- Registered trademark of Alfa Laval Inc., Kenosha, USA



## 4 Incoming acceptance and product identification

### 4.1 Incoming acceptance

		Is the order code on the delivery note (1) identical to the order code on the product sticker (2)?
		Are the goods undamaged?
		Do the nameplate data match the ordering information on the delivery note?
		Is the DVD (operating tool) present? If required (see nameplate): Are the Safety Instructions (SI) present?

Table 4.1

**Note!**

If one of the conditions does not comply, contact your Pepperl+Fuchs distributor.



## 4.2

## Product identification

The following options are available for identification of the measuring device:

- Nameplate specifications
- Order code with breakdown of the device features on the delivery note
- Scan the 2-D matrix code (QR code) on the nameplate: all the information for the measuring device is displayed.

### Nameplate

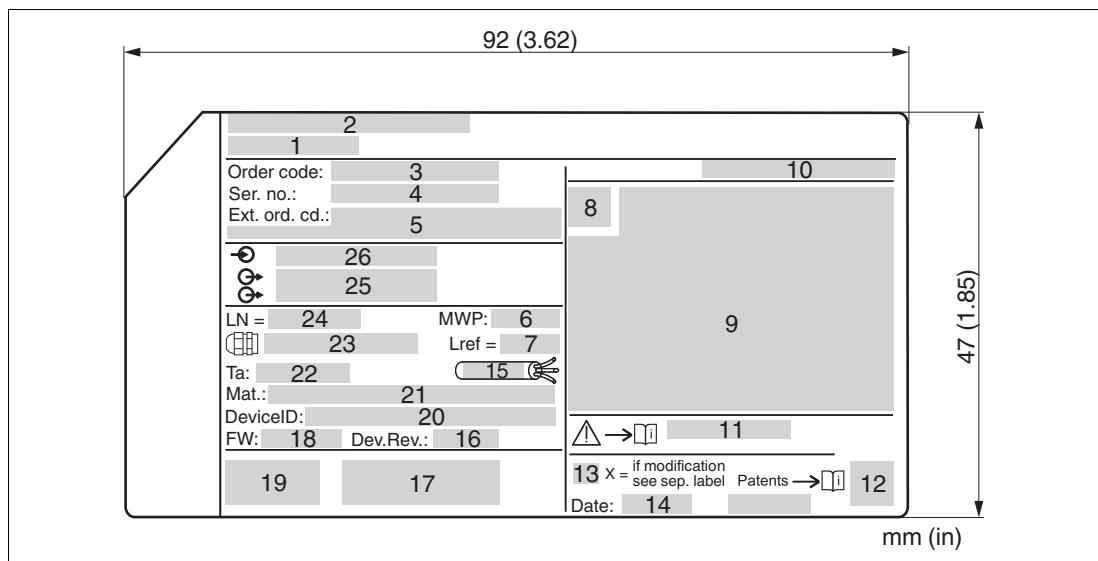


Figure 4.1 Nameplate

- 1 Device name
- 2 Address of manufacturer
- 3 Order code
- 4 Serial number (Ser. no.)
- 5 Extended order code (Ext. ord. cd.)
- 6 Process pressure
- 7 Gas phase compensation: reference distance
- 8 Certificate symbol
- 9 Certificate and approval relevant data
- 10 Degree of protection: e. g. IP, NEMA
- 11 Document number of the Safety Instructions: e. g. SI, ZD, ZE
- 12 2-D matrix code (QR code)
- 13 Modification mark
- 14 Manufacturing date: year-month
- 15 Permitted temperature range for cable
- 16 Device revision (Dev.Rev.)
- 17 Additional information about the device version (certificates, approvals, communication): e. g. SIL, PROFIBUS
- 18 Firmware version (FW)
- 19 CE mark, C-Tick



- 20 Device ID
- 21 Material in contact with process
- 22 Permitted ambient temperature ( $T_{amb}$ )
- 23 Size of the thread of the cable glands
- 24 Length of probe
- 25 Signal outputs
- 26 Operating voltage

**Note!**

Only 33 digits of the extended order code can be indicated on the nameplate. If the extended order code exceeds 33 digits, the rest will not be shown. However, the complete extended order code can be viewed in the operating menu of the device in the **Extended order code 1 to 3** parameter.



## 5 Storage, Transport

### 5.1 Storage conditions

- Permitted storage temperature: -40 ... +80 °C (-40 ... +176 °F)
- Use the original packaging.

### 5.2 Transport product to the measuring point



#### Warning!

Risk of injury!

Housing or probe may be damaged or break away.

- Transport the measuring device to the measuring point in its original packaging or at the process connection.
- Do not fasten lifting devices (hoisting slings, lifting eyes etc.) at the housing or the probe but at the process connection. Take into account the mass center of the device in order to avoid unintended tilting.
- Comply with the safety instructions, transport conditions for devices over 18 kg (39.6 lbs).

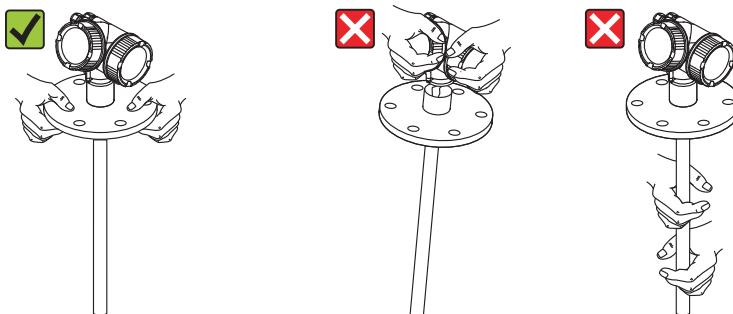


Figure 5.1

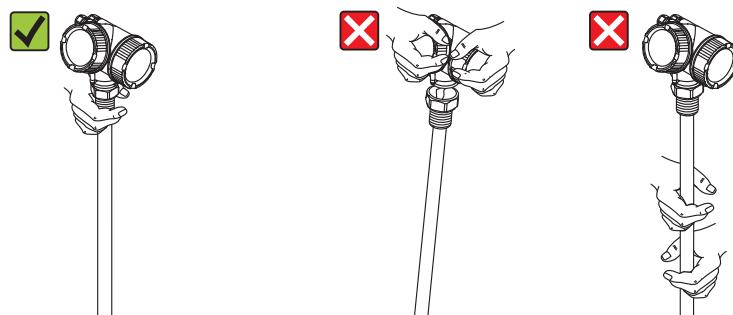


Figure 5.2



## 6

# Mounting

### 6.1

## Mounting requirements

#### 6.1.1

### Suitable mounting position

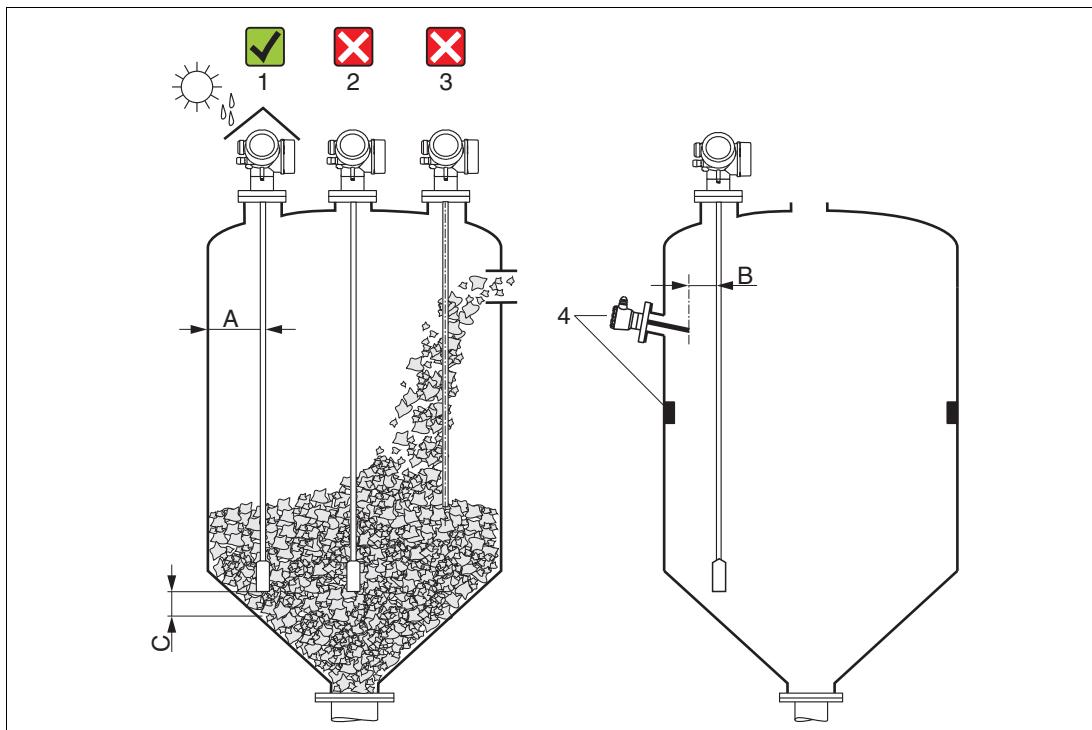


Figure 6.1 Mounting requirements

### Mounting distances

- Distance (A) between wall and rod or rope probe:
  - for smooth metallic walls: > 50 mm (2 in)
  - for plastic walls: > 300 mm (12 in) to metallic parts outside the vessel
  - for concrete walls: > 500 mm (20 in), otherwise the available measuring range may be reduced.
- Distance (B) between rod or rope probe and internal fittings in the vessel: > 300 mm (12 in)
- Distance (C) from end of probe to bottom of the vessel:
  - Rope probe: > 150 mm (6 in)
  - Rod probe: > 10 mm (0.4 in)



## Additional conditions

- When mounting in the open, a weather protection cover (1) may be installed to protect the device against extreme weather conditions.
- In metallic vessels: Preferably do not mount the probe in the center of the vessel (2), as this would lead to increased interference echoes.  
If a central mounting position can not be avoided, it is crucial to perform an interference echo suppression (mapping) after the commissioning of the device.
- Do not mount the probe in the filling curtain (3).
- Avoid buckling the rope probe during installation or operation (e. g. through product movement against silo wall) by selecting a suitable mounting location.
- Check the probe regularly for defects.



### Note!

With suspended rope probes (probe end not fixed at the bottom) the distance between the probe rope and internal fittings in the tank must not fall below 300 mm (12 in) during the entire process. A sporadic contact between the probe weight and the cone of the vessel, however, does not influence the measurement as long as the dielectric constant of the medium is at least DC = 1.8.



### Note!

When mounting the electronics housing into a recess (e. g. in a concrete ceiling), observe a minimum distance of 100 mm (4 in) between the cover of the terminal compartment/electronics compartment and the wall. Otherwise the connection compartment/electronics compartment is not accessible after installation.



## 6.1.2 Applications with restricted mounting space

### Mounting with remote sensor

The device version with a remote sensor is suited for applications with restricted mounting space. In this case the electronics housing is mounted at a separate position from which it is easier accessible.

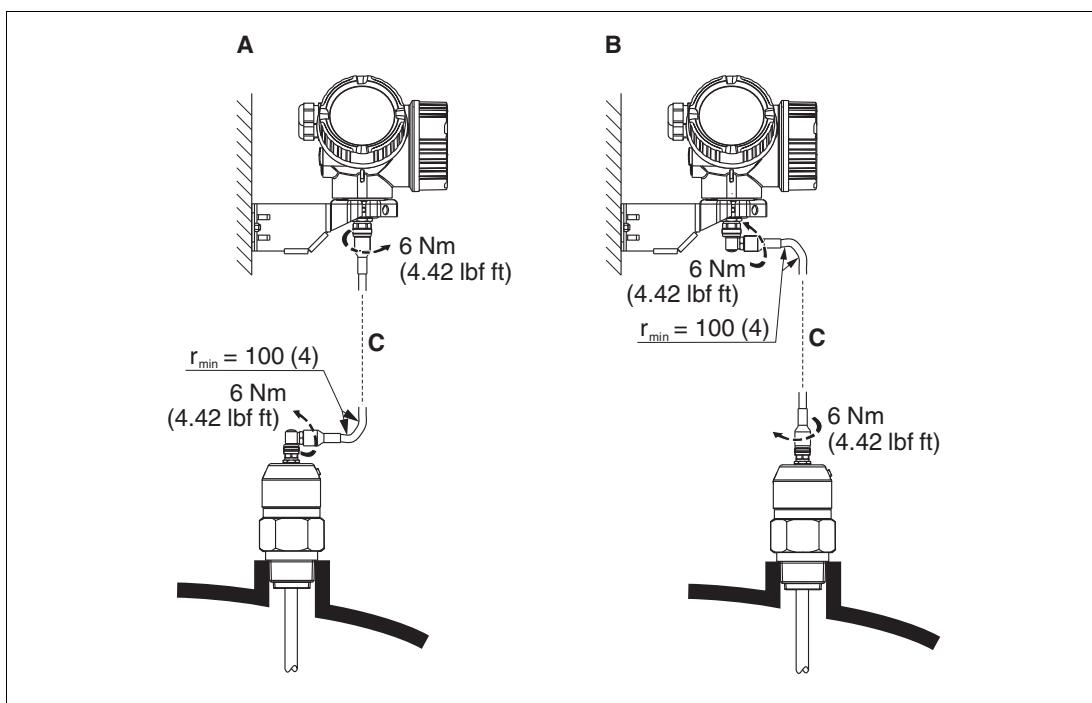


Figure 6.2

- A** Angled plug at the probe
- B** Angled plug at the electronics housing
- C** Length of the remote cable as ordered

- Product structure, feature "Probe design": option B "Sensor remote, 3 m/9 ft cable"
- The remote cable is supplied with these device versions, minimum bending radius: 100 mm (4 in)
- A mounting bracket for the electronics housing is supplied with these device versions. Mounting options:
  - Wall mounting
  - Pipe mounting; diameter: 42 to 60 mm (1-1/4 to 2 in)
- The connection cable has got one straight and one angled plug (90°). Depending on the local conditions the angled plug can be connected at the probe or at the electronics housing.

#### Note!

Probe, electronics and connection cable are adjusted to match each other. They are marked by a common serial number. Only components with the same serial number shall be connected to each other.





### 6.1.3

### Notes on the mechanical load of the probe

#### Tensile load limit of rope probes

Feature "Probe"	Probe	Tensile load limit [kN]	Max. rupture load [kN] <sup>a</sup>
Option 2, 3	Rope 4 mm (1/6 in) 316	12	20
Option M, Q	Rope 6 mm (1/4 in) 316	30	42
Option N, S	Rope 6 mm (1/4 in) PA > Steel	12	20
Option R, T	Rope 8 mm (1/3 in) PA > Steel	30	42

Table 6.1

<sup>a</sup> The ceiling of the silo must be designed to withstand this load.

#### Tensile load

Bulk solids exert tensile forces on rope probes whose height increases with:

- the length of the probe, i. e. max. cover
- the bulk density of the product,
- the silo diameter and
- the diameter of the probe rope

Since the tensile forces are also heavily dependent on the viscosity of the product, a higher safety factor is necessary for highly viscous products and if there is a risk of cornice buildup. In critical cases it is better to use a 6 mm rope instead of a 4 mm one.

The same forces also act on the silo cover. On a fixed rope, the tensile forces are definitely greater, but this can not be calculated. Observe the tensile strength of the probes.

Options for reducing the tensile forces:

- Shorten the probe.
- If the maximum tensile load is exceeded, check whether it would be possible to use a non-contact ultrasonic or level-radar device.

The following diagrams show typical loads for frequently occurring bulk solids as reference values. The calculation is performed for the following conditions:

- Calculation according to DIN 1055, Part 6 for the cylindrical part of the silo.
- Suspended probe (probe end not fixed at the bottom)
- Free-flowing bulk solid, i. e. mass flow. A calculation for core flow is not possible. In the event of collapsing cornices, considerably higher loads can occur.
- The specification for tensile forces contains the safety factor 2 (in addition to the safety factors already taken into account by DIN 1055), which compensates for the normal fluctuation range in pourable bulk solids.

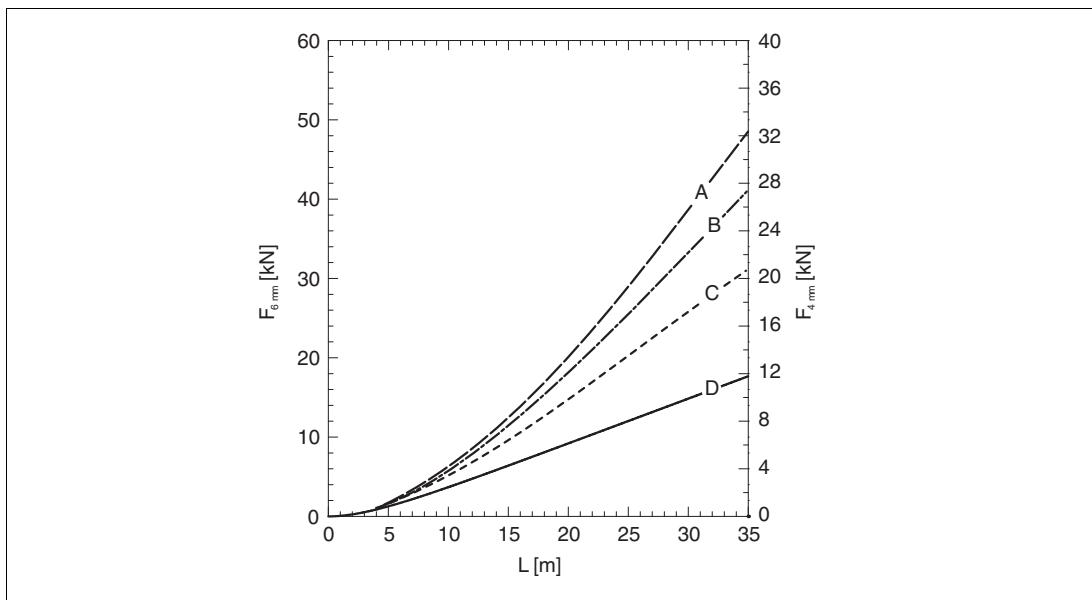


Figure 6.3 Silica sand in silo with smooth metallic walls; tensile load as a function of level L for rope diameters 6 mm (0.24 in) and 4 mm (0.16 in)

- A** Silo diameter 12 m (40 ft)
- B** Silo diameter 9 m (30 ft)
- C** Silo diameter 6 m (20 ft)
- D** Silo diameter 3 m (10 ft)

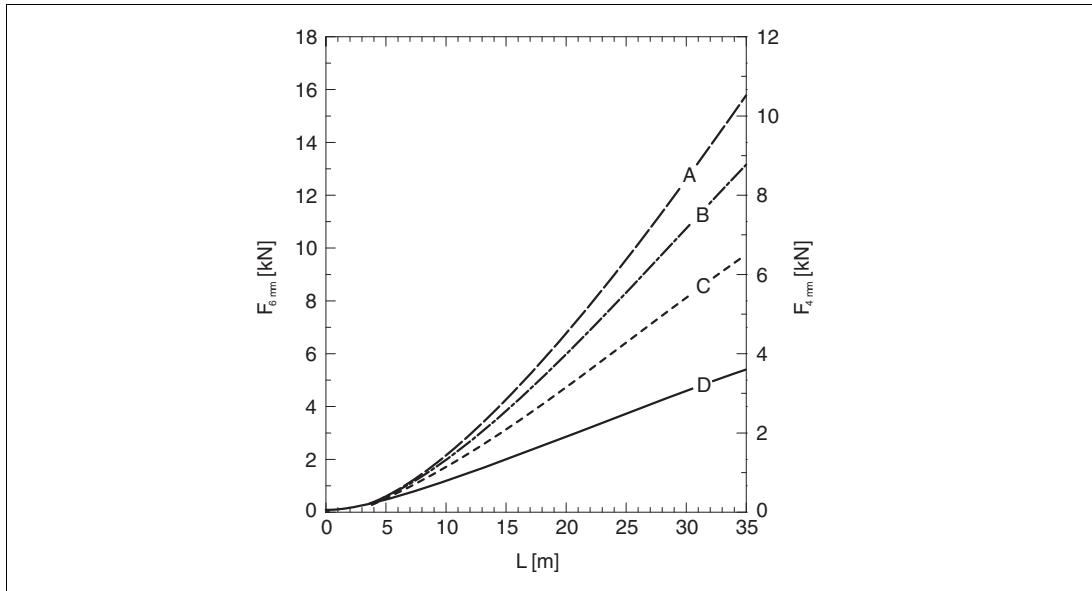


Figure 6.4 Polyethylene pellets in silo with smooth metallic walls; tensile load as a function of level L for rope diameters 6 mm (0.24 in) and 4 mm (0.16 in)

- A** Silo diameter 12 m (40 ft)
- B** Silo diameter 9 m (30 ft)
- C** Silo diameter 6 m (20 ft)
- D** Silo diameter 3 m (10 ft)

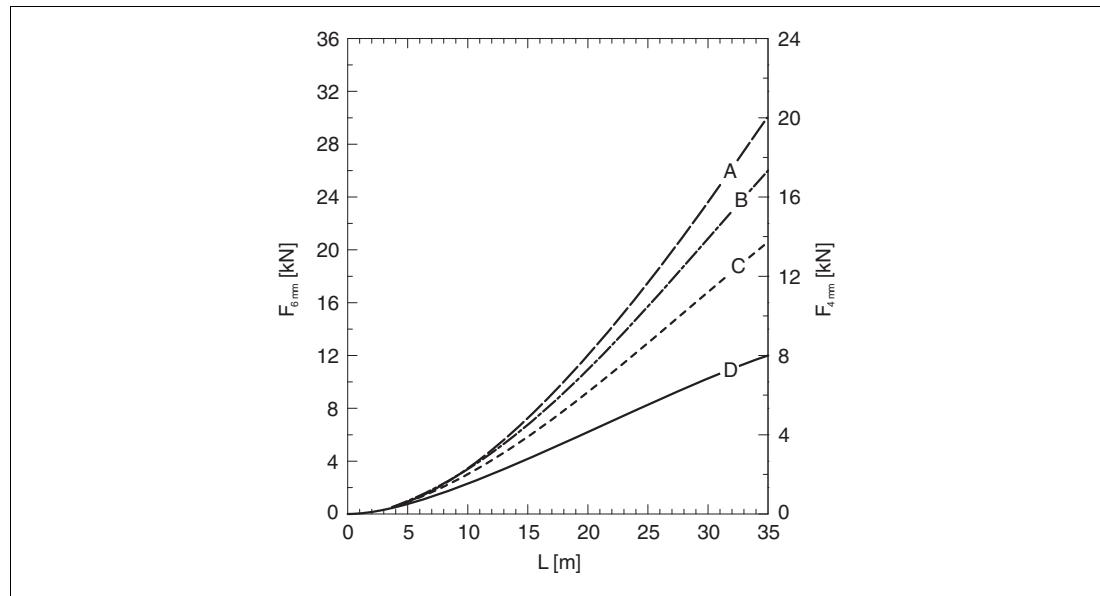


Figure 6.5 Wheat in silo with smooth metallic walls; tensile load as a function of level L for rope diameters 6 mm (0.24 in) and 4 mm (0.16 in)

- A** Silo diameter 12 m (40 ft)
- B** Silo diameter 9 m (30 ft)
- C** Silo diameter 6 m (20 ft)
- D** Silo diameter 3 m (10 ft)

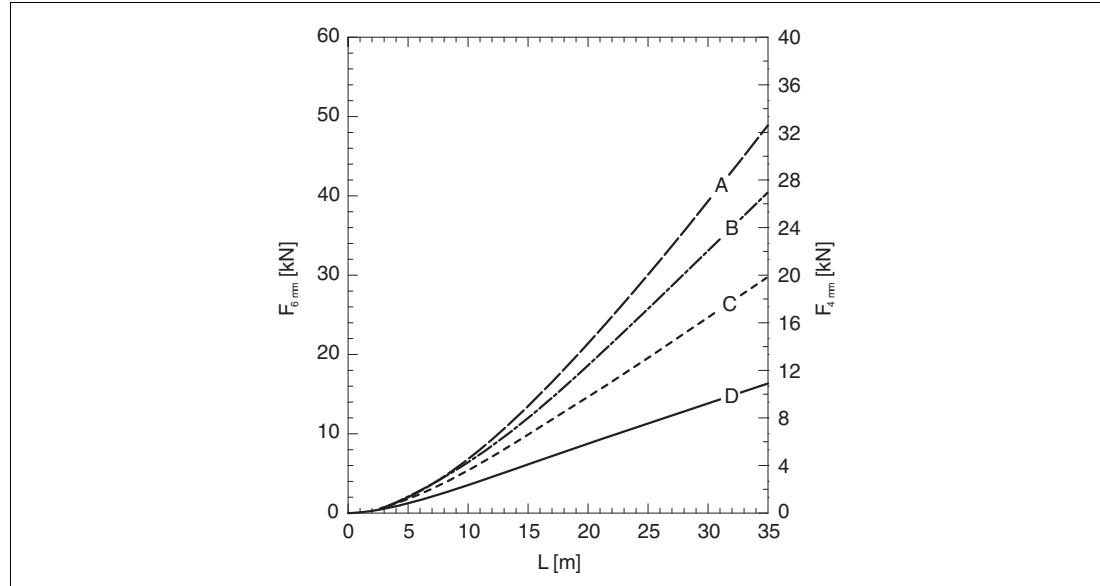


Figure 6.6 Cement in silo with smooth metallic walls; tensile load as a function of level L for rope diameters 6 mm (0.24 in) and 4 mm (0.16 in)

- A** Tank diameter 12 m (40 ft)
- B** Tank diameter 9 m (30 ft)
- C** Tank diameter 6 m (20 ft)
- D** Tank diameter 3 m (10 ft)



## Bending strength of rod probes

Feature "Probe"	Probe	Bending strength [Nm]
Option L, P	Rod 16 mm (0.63 in) 316L	30

Table 6.2

### 6.1.4 Notes on the process connection

Probes are mounted to the process connection with threaded connections or flanges. If during this installation there is the danger that the probe end moves so much that it touches the tank floor or cone at times, the probe must, if necessary, be shortened and fixed down.

#### Threaded connection

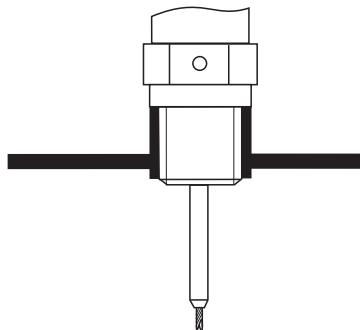


Figure 6.7 Mounting with threaded connection; flush with the container ceiling

#### Seal

The thread as well as the type of seal comply to DIN 3852 part 1, screwed plug form A.

They can be sealed with the following types of sealing rings:

- Thread G3/4: according to DIN 7603 with the dimensions 27 x 32 mm
- Thread G1-1/2: According to DIN 7603 with the dimensions 48 x 55 mm

Please use a sealing ring according to this standard in the form A, C or D and of a material that is resistant to the application.



## Nozzle mounting

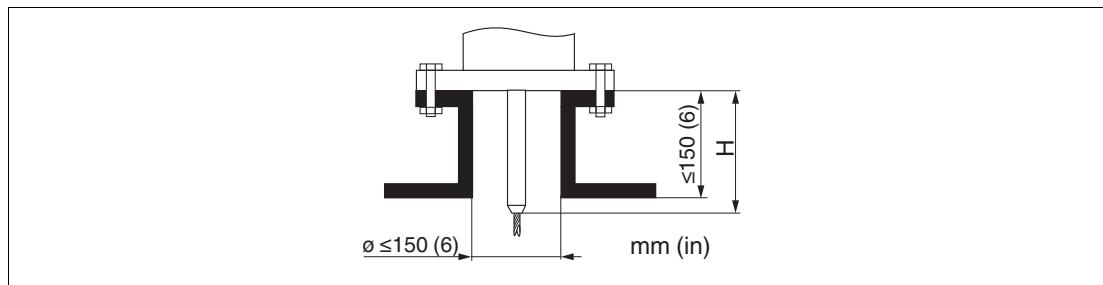


Figure 6.8

Length H of the rigid part of the rope probe

Probe	H
Rope Ø4 mm (0.16 in)	120 mm (4.7 in)
Rope Ø6 mm (0.24 in)	135 mm (5.3 in)

Table 6.3

- Permissible nozzle diameter:  $\leq 150$  mm (6 in).  
For larger diameters the near range measuring capability may be reduced.  
For nozzles  $\geq$  DN300: see next section.
- Permissible nozzle height <sup>1</sup>:  $\leq 150$  mm (6 in).  
For a larger height the near range measuring capability may be reduced.  
Larger nozzle heights may be possible in special cases: see next section.



### Note!

With thermally insulated vessels the nozzle should also be insulated in order to prevent condensate formation.

## Rod extension/centering

For devices with rope probes a rod extension/centering is available on request. It has to be used if otherwise the probe rope comes into contact with the lower edge of the nozzle.



### Note!

Centering disks with small diameters (DN40 and DN50) may only be used if there is no significant build-up in the nozzle above the disk. The nozzle must not become clogged by the product.

<sup>1</sup> Larger nozzle heights on request.



### Installation in nozzles $\geq$ DN300

If installation in  $\geq 300$  mm/12 in nozzles is unavoidable, installation must be carried out in accordance with the following sketch.

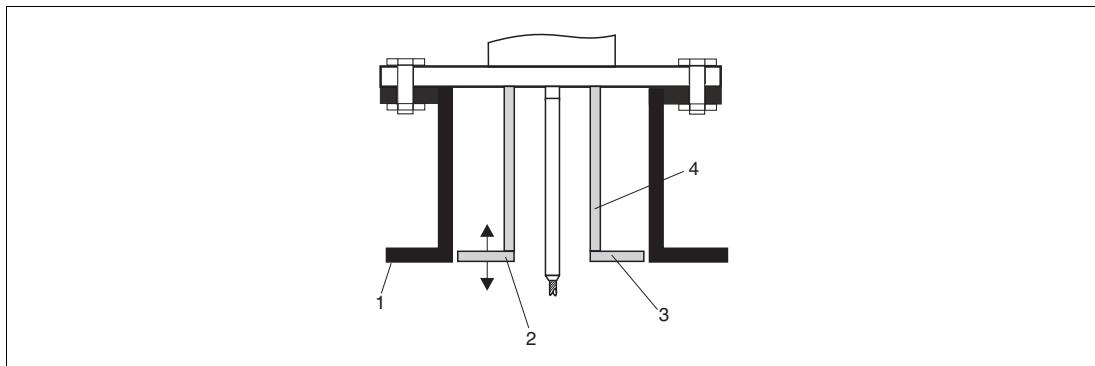


Figure 6.9

- 1 Lower edge of the nozzle
- 2 Approx. flush with the lower edge of the nozzle ( $\pm 50$  mm/2 in)
- 3 Plate
- 4 Pipe diameter 150 to 180 mm (6 to 7 in)

Nozzle diameter	Plate diameter
300 mm (12 in)	280 mm (11 in)
$\geq 400$ mm (16 in)	$\geq 350$ mm (14 in)

Table 6.4



## 6.1.5

### Securing the probe

#### Securing rope probes

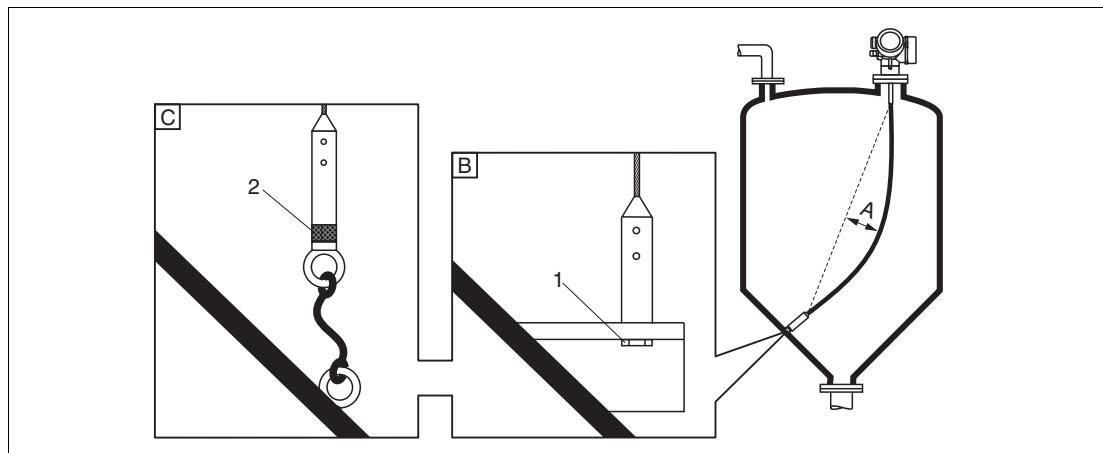


Figure 6.10

- A** Sag of the rope:  $\geq 1 \text{ cm per } 1 \text{ m of the probe length (0.12 in per } 1 \text{ ft of the probe length)}$
- B** Reliably grounded end of probe
- C** Reliably isolated end of probe
- 1** Mounting and contact with a bolt
- 2** Mounting kit isolated

- The end of the probe needs to be secured under the following conditions:
  - if otherwise the probe sporadically comes into contact with the wall of the vessel, the outlet cone, internal fittings or other parts of the installation.
  - if otherwise the probe sporadically gets close to a concrete wall (minimum distance 0.5 m/20 in).
- The end of probe can be secured at its internal thread
  - rope 4 mm (1/6 in), 316: M14
  - rope 6 mm (1/4 in), 316: M20
  - rope 6 mm (1/4 in), PA > steel: M14
  - rope 8 mm (1/3 in), PA > steel: M20
- Preferably use the 6 mm (1/4 in) rope probe due to the higher tensile strength when fixing a rope probe.
- The fixing must be either reliably grounded or reliably insulated. If it is not possible to mount the probe weight with a reliably insulated connection, it can be secured using an isolated eyelet, which is available as an accessory.
- In the case of a grounded fixing the search for a positive end-of-probe signal must be activated. Otherwise an automatic probe length correction is impossible.  
Navigation: Expert → Sensor → EOP evaluation → EOP search mode  
Setting: **Positive EOP** option
- In order to prevent an extremely high tensile load (e. g. due to thermal expansion) and the risk of rope crack, the rope has to be slack. Make the rope longer than the required measuring range such that there is a sag in the middle of the rope that is  $\geq 1 \text{ cm/(1 m rope length)}$  [0.12 in/(1 ft rope length)].



## Securing rod probes

- For Ex-approvals: For probe lengths  $\geq 3$  m (10 ft) a support is required.
- In general, rod probes must be supported if there is a horizontal flow (e. g. from an agitator) or in the case of strong vibrations.
- Rod probes may only be supported at the end of the probe.

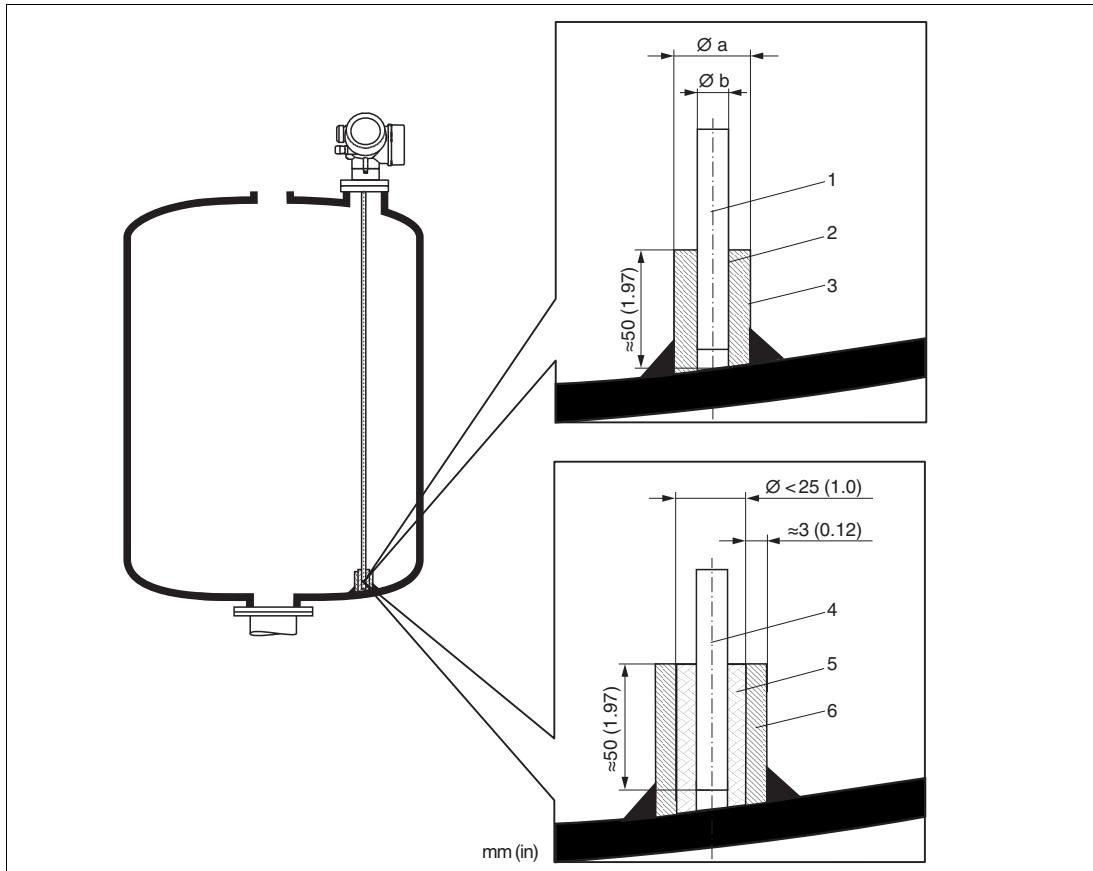


Figure 6.11

- 1 Probe rod, uncoated
- 2 Sleeve bored tight to ensure electrical contact between the rod and sleeve!
- 3 Short metal pipe, e. g. welded in place
- 4 Probe rod, coated
- 5 Plastic sleeve, e. g. PTFE, PEEK or PPS
- 6 Short metal pipe, e. g. welded in place



### Warning!

Poor grounding of the end of probe may cause measuring errors.

- Apply a narrow sleeve which has good electrical contact to the probe.



### Warning!

Welding may damage the main electronics module.

- Before welding: Ground the probe and dismount electronics.



## 6.1.6 Special mounting conditions

### Concrete silos

Installation, for example, into a thick concrete ceiling should be made flush with the lower edge. Alternatively, the probe can also be installed into a pipe that must not protrude over the lower edge of the silo ceiling. The pipe should be kept at a minimum length. Installation suggestions see diagram.

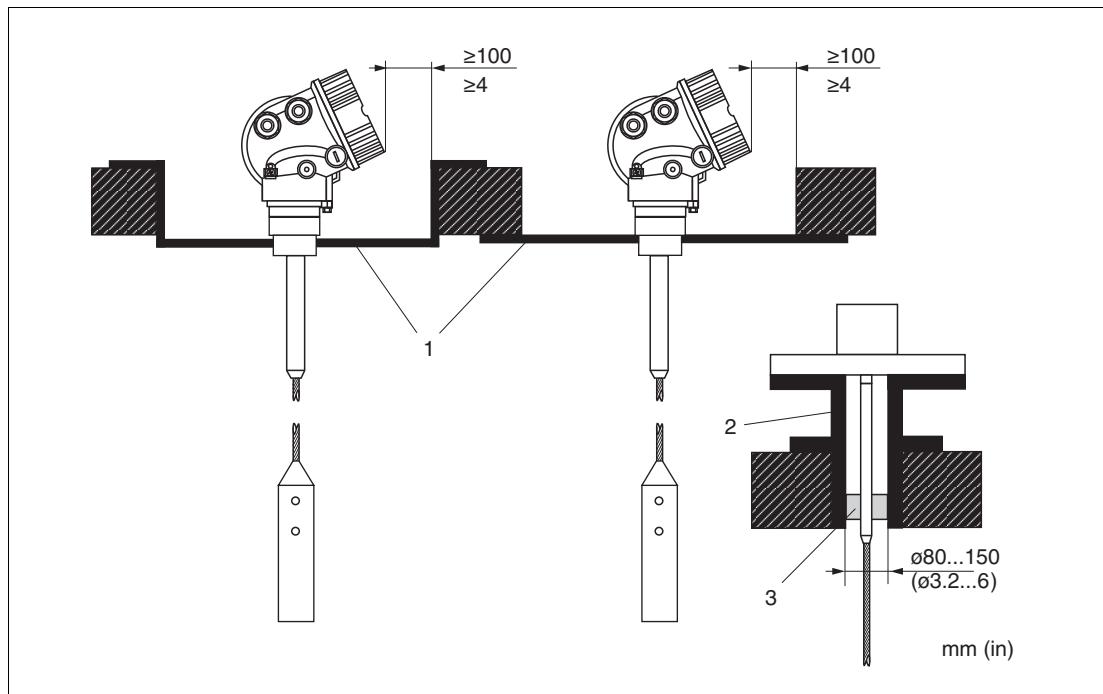


Figure 6.12

- 1 Metal sheet
- 2 Metal tube
- 3 Extension rod/centering

Note for installations with rod extension/center washer (on request): Strong dust generation can lead to build-up behind the center washer. This can cause an interference signal. For other installation possibilities please contact Pepperl+Fuchs.



### Installation from the side

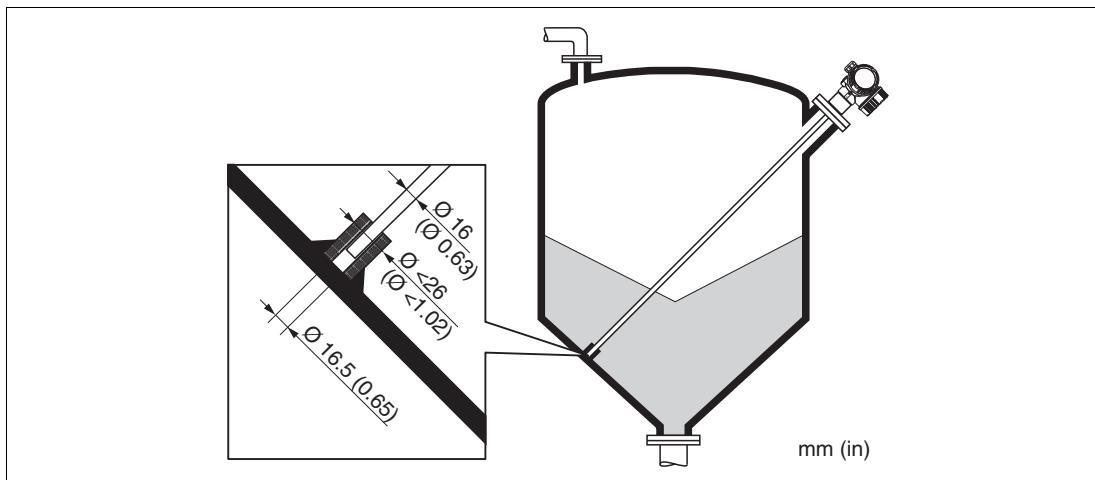


Figure 6.13

- If installation from above is not possible, the device can also be mounted from the side.
- In this case, always fix the rope probe.
- Support rod probe if the lateral load bearing capacity is exceeded. Only fix rod probes at the probe end.

### Non-metallic vessels

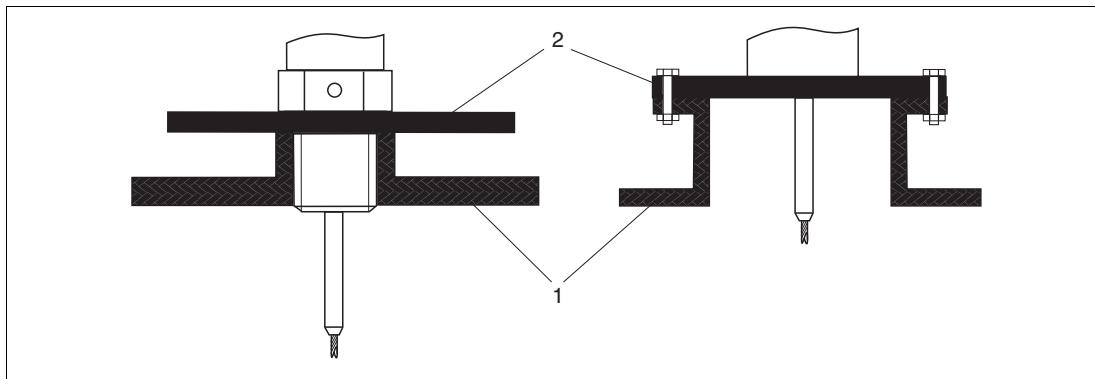


Figure 6.14

- 1 Non-metallic vessel
- 2 Metal sheet or metal flange

To measure, device with a rod probe needs a metallic surface at the process connection. Therefore:

- Select an instrument version with metal flange (minimum size DN50/2 in).
- Or: mount a metal sheet with a diameter of at least 200 mm (8 in) to the probe at the process connection. Its orientation must be perpendicular to the probe.



## Vessels with heat insulation



### Note!

If process temperatures are high, the device must be included in normal tank insulation to prevent the electronics heating up as a result of heat radiation or convection. The insulation may not exceed beyond the points labeled "MAX" in the drawings.

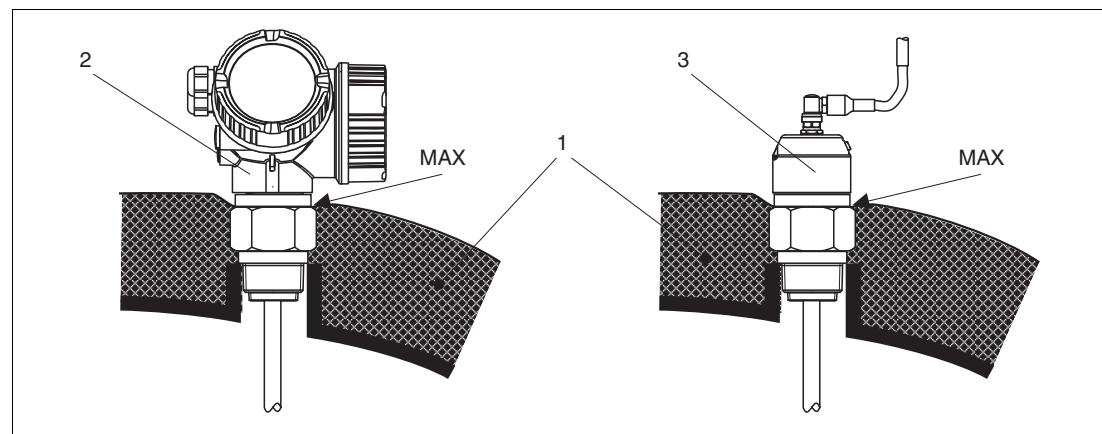


Figure 6.15      Process connection with thread

- 1    Tank insulation
- 2    Compact device
- 3    Sensor remote (feature "Probe design")

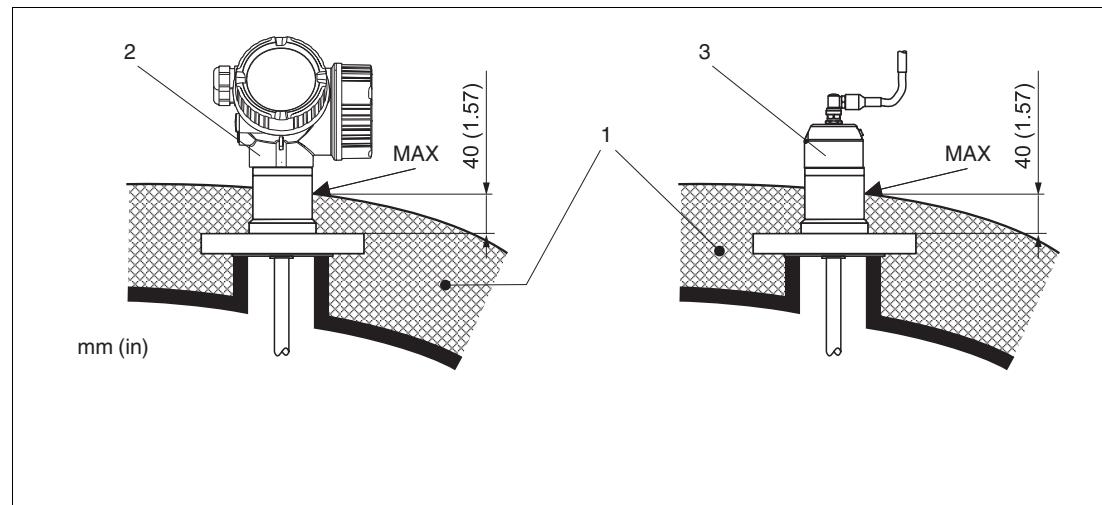


Figure 6.16      Process connection with flange

- 1    Tank insulation
- 2    Compact device
- 3    Sensor remote (feature "Probe design")



## 6.2 Mounting the device

### 6.2.1 Required mounting tools

- For mounting thread 3/4 in: Hexagonal wrench 36 mm
- For mounting thread 1-1/2 in: Hexagonal wrench 55 mm
- To shorten rod probes: Saw
- To shorten rope probes:
  - Allen key AF3 mm (for 4 mm ropes) or AF4 mm (for 6 mm ropes)
  - Saw or bolt cutter
- For flanges and other process connections: appropriate mounting tools
- To turn the housing: Hexagonal wrench 8 mm

### 6.2.2 Shortening the probe



**Note!**

When shortening the probe: Enter the new length of probe into the Quick Start Guide which can be found in the electronics housing behind the display module.

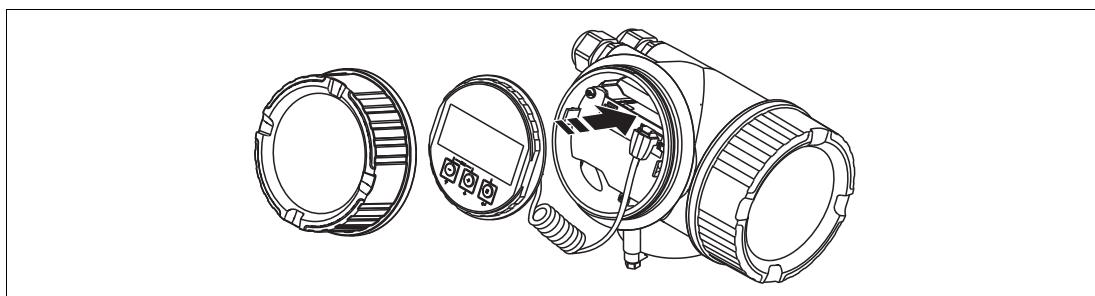


Figure 6.17

### Shortening rod probes

Rod probes must be shortened if the distance to the container floor or outlet cone is less than 10 mm (0.4 in). The rods of a rod probe are shortened by sawing at the bottom end.



## Shortening rope probes

Rope probes must be shortened if the distance to the container floor or outlet cone is less than 150 mm (6 in).

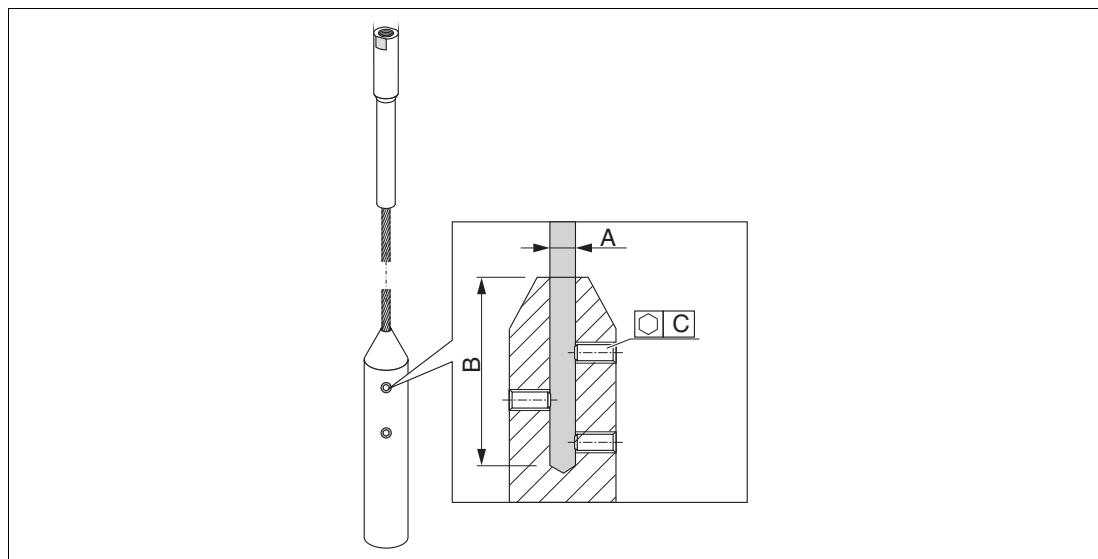


Figure 6.18

Rope material	A	B	C	Torque for set screws
316	4 mm (0.16 in)	40 mm (1.6 in)	3 mm	5 Nm (3.69 lbf ft)
316	6 mm (0.24 in)	55 mm (2.2 in)	4 mm	15 Nm (11.06 lbf ft)
PA > steel	6 mm (0.24 in)	40 mm (1.6 in)	3 mm	5 Nm (3.69 lbf ft)
PA > steel	8 mm (0.31 in)	55 mm (2.2 in)	4 mm	15 Nm (11.06 lbf ft)

Table 6.5



## Shortening rope probes

1. Using an Allen key, loosen the set screws at the end-of-probe weight.  
**Note:** The set screws have got a clamping coating in order to prevent accidental loosening. Thus an increased torque might be necessary to loosen them.
2. Remove released rope from the weight.
3. Measure off new rope length.
4. Wrap adhesive tape around the rope at the point to be shortened to prevent it from fanning out.
5. Saw off the rope at a right angle or cut it off with a bolt cutter.
6. Insert the rope completely into the weight.
7. Screw the set screws into place. Due to the clamping coating of the setscrews application of a screw locking fluid is not necessary.



### 6.2.3

### Mounting the device

#### Mounting devices with thread

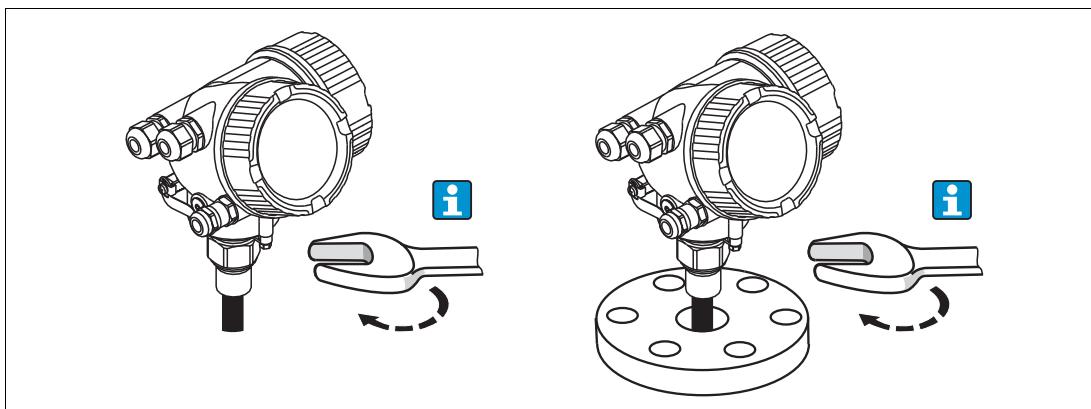


Figure 6.19

Devices with mounting thread are screwed into a welding boss or a flange and are usually also secured with these.



#### Note!

- Tighten with the hexagonal nut only:
  - Thread 3/4 in: Hexagonal wrench 36 mm
  - Thread 1-1/2 in: Hexagonal wrench 55 mm
- Maximum permissible torque:
  - Thread 3/4 in: 45 Nm
  - Thread 1-1/2 in: 450 Nm
- Recommended torque when using the supplied aramid fibre seal and a process pressure of 40 bar (580 psi):
  - Thread 3/4 in: 25 Nm
  - Thread 1-1/2 in: 140 Nm
- When installing in metal containers, take care to ensure good metallic contact between the process connection and container.

#### Flange mounting

If a seal is used, be sure to use unpainted metal bolts to ensure good electrical contact between probe flange and process flange.



## Mounting rope probes



### Warning!

Electrostatic discharges may damage the electronics.

- Earth the housing before lowering the rope into the vessel.

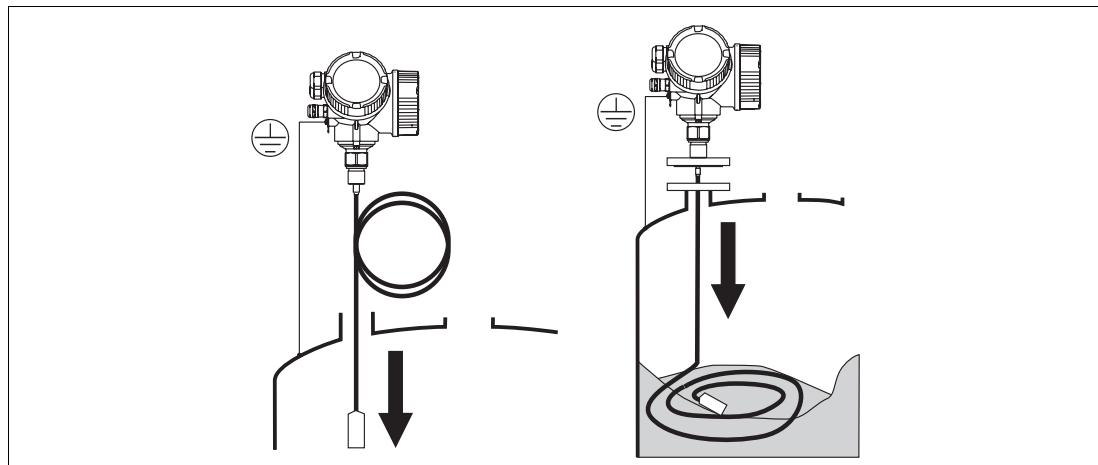


Figure 6.20

When lowering the rope probe into the vessel, observe the following:

- Uncoil rope and lower it slowly and carefully into the vessel.
- Do not kink the rope.
- Avoid any backlash, since this might damage the probe or the vessel fittings.



### Note!

#### Mounting rope probes in a partially full silo

It is not always possible to empty a silo which is already in operation. If a minimum of 2/3 of the silo is empty, it is possible to install the probe into the partially filled silo. If possible, make a visual check after the installation to see that the rope has not tangled or is lying such that it can knot when the level falls. Before full accuracy is obtained the probe rope must hang fully extended.



## 6.2.4

### Mounting the "Sensor remote" version



#### Note!

This section is only valid for devices of the version "Probe design" = "Sensor remote" (feature "Probe design", option B).

For the version "Probe design = Sensor remote" the following is supplied:

- The probe with the process connection
- The electronics housing
- The mounting bracket for wall or pipe mounting of the electronics housing
- The connection cable (length as ordered). The cable has got one straight and one angled plug (90°). Depending on the local conditions the angled plug can be connected at the probe or at the electronics housing.



#### Warning!

The plugs of the connection cable may be damaged by mechanical stress.

- Mount the probe and the electronics housing tightly before connecting the cable.
- Lay the cable such that it is not exposed to mechanical stress. Minimum bending radius: 100 mm (4 in).
- When connecting the cable: Connect the straight plug before the angled one. Torque for both coupling nuts: 6 Nm.



#### Note!

If the measuring point is exposed to strong vibrations, an additional locking compound (e. g. Loctite 243) can be applied at the plug connectors.

### Mounting the electronics housing

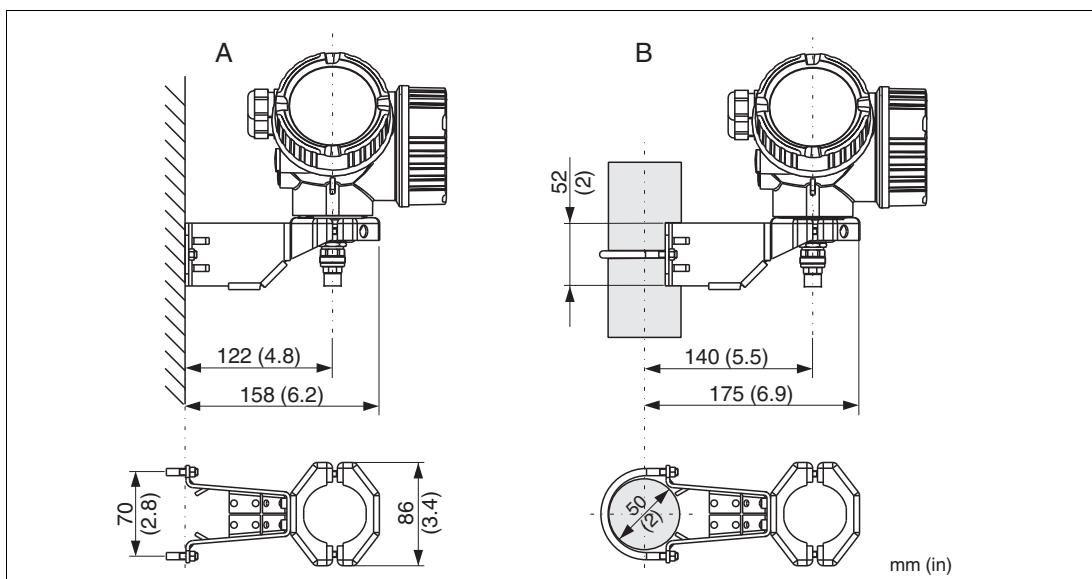


Figure 6.21

- A** Wall mounting  
**B** Pipe mounting



## Connecting the cable

Required tools: open-end wrench AF18

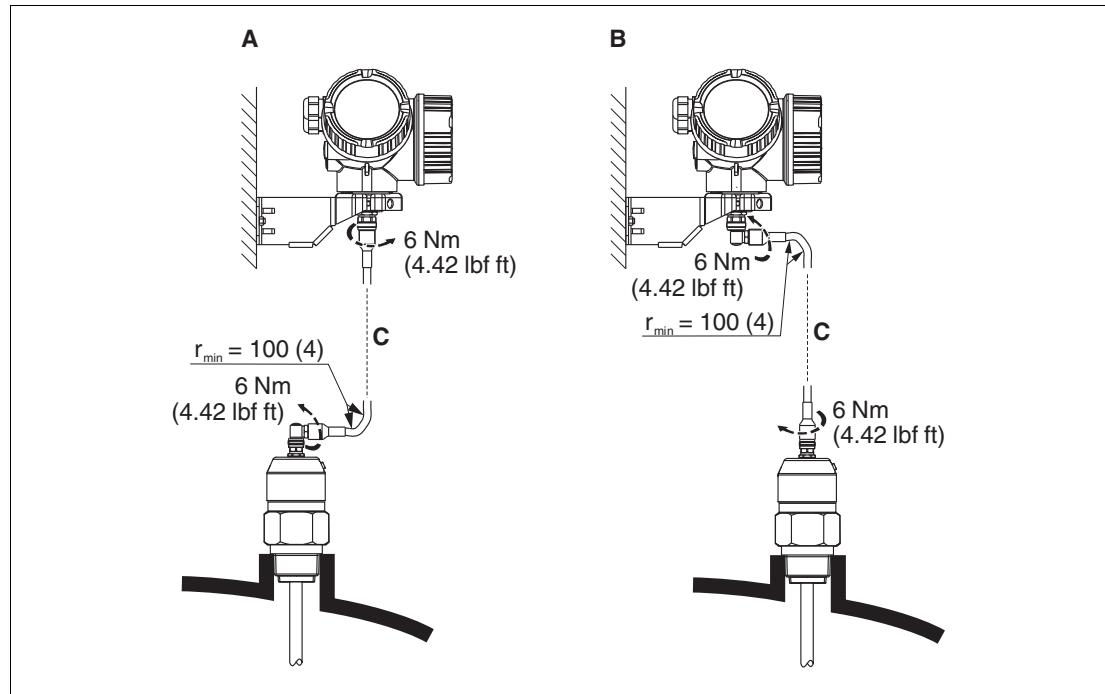


Figure 6.22

- A**    Angled plug at the probe
- B**    Angled plug at the electronics housing
- C**    Length of the remote cable as ordered



## 6.2.5

### Turning the transmitter housing

To provide easier access to the connection compartment or display module, the transmitter housing can be turned:

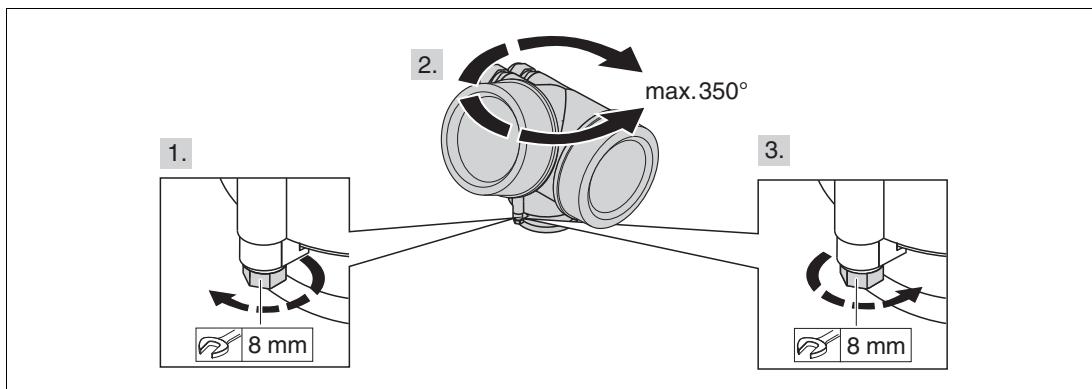


Figure 6.23

#### Turning the transmitter housing

1. Unscrew the securing screw using an open-ended wrench.
2. Rotate the housing in the desired direction.
3. Tighten the securing screw (1.5 Nm for plastics housing; 2.5 Nm for aluminium or stainless steel housing).

## 6.2.6

### Turning the display module

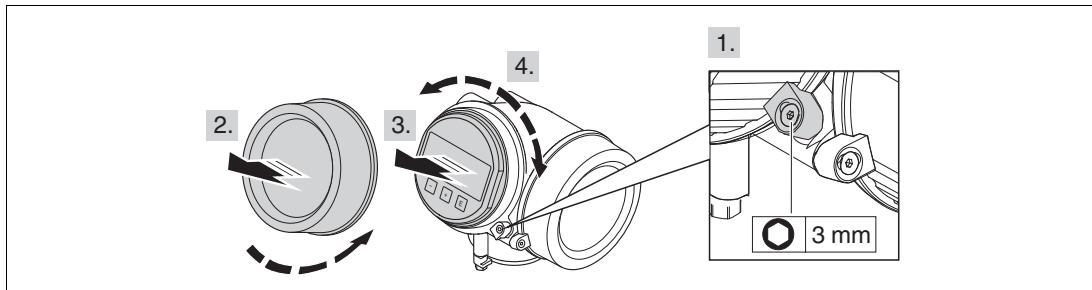


Figure 6.24

#### Turning the display module

1. If present: Loosen the screw of the securing clamp of the electronics compartment cover using an Allen key and turn the clamp 90° counterclockwise.
2. Unscrew cover of the electronics compartment from the transmitter housing.
3. Pull out the display module with a gentle rotation movement.
4. Rotate the display module into the desired position: Max. 8 x 45° in each direction.
5. Feed the spiral cable into the gap between the housing and main electronics module and plug the display module into the electronics compartment until it engages.
6. Screw the cover of the electronics compartment firmly back onto the transmitter housing.
7. Tighten the securing clamp again using the Allen key (torque: 2.5 Nm).



## 6.3

### Post-installation check

- Is the device undamaged (visual inspection)?
- Does the device conform to the measuring point specifications?  
For example:
  - Process temperature
  - Process pressure
  - Ambient temperature range
  - Measuring range
- Are the measuring point identification and labeling correct (visual inspection)?
- Is the device adequately protected from precipitation and direct sunlight?
- Are the securing screw and securing clamp tightened securely?



## 7

# Electrical connection

### 7.1

## Connection conditions

#### 7.1.1

### Terminal assignment

#### 2-wire: 4 ... 20 mA HART

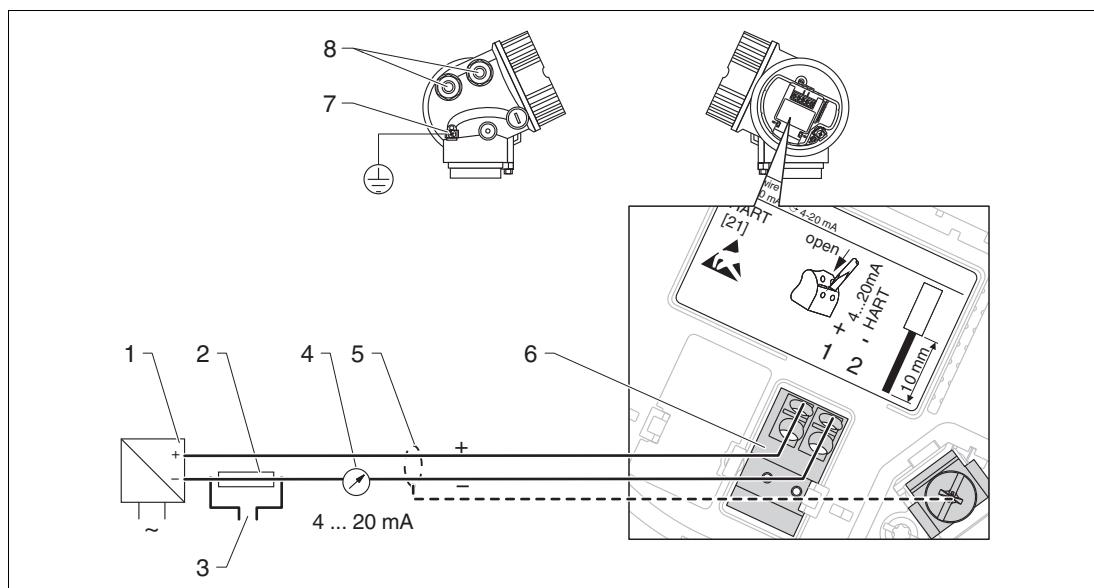


Figure 7.1 Terminal assignment 2-wire; 4 ... 20 mA HART

- 1 Active barrier with power supply (e. g. KCD2-STC-Ex1): observe terminal voltage
- 2 HART communication resistor ( $\geq 250 \Omega$ ): observe maximum load
- 3 Connection for optional field communicator
- 4 Analog display device: observe maximum load
- 5 Cable screen; observe cable specification
- 6 4 ... 20 mA HART (passive): terminals 1 and 2
- 7 Terminal for potential equalization line
- 8 Cable entry



### 2-wire: 4 ... 20 mA HART, switch output

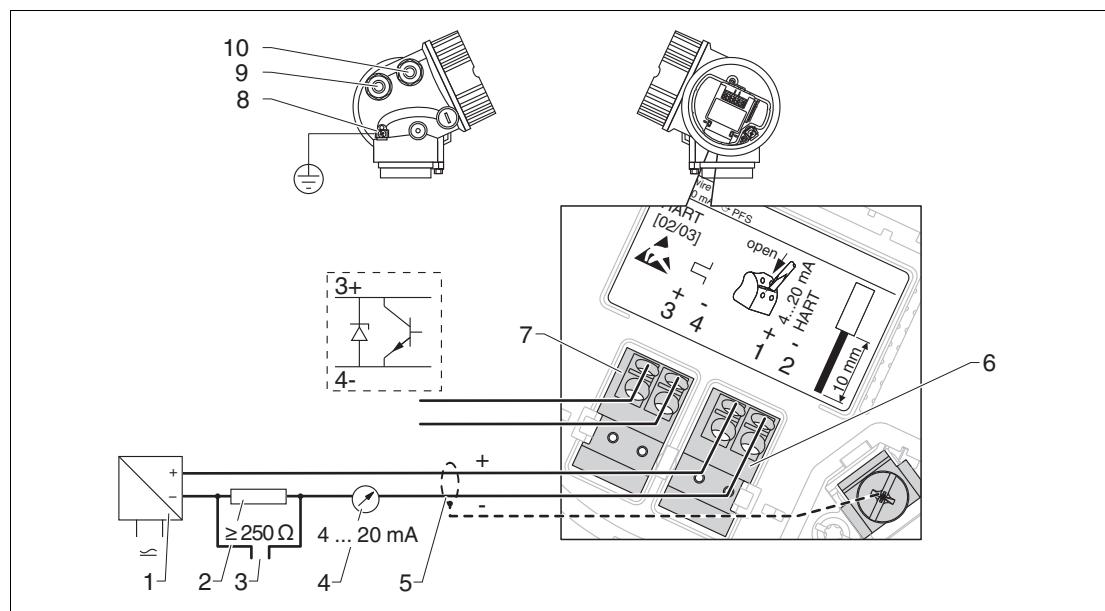


Figure 7.2 Terminal assignment 2-wire; 4 ... 20 mA HART, switch output

- 1 Active barrier with power supply (e. g. KCD2-STC-Ex1): observe terminal voltage
- 2 HART communication resistor ( $\geq 250 \Omega$ ): observe maximum load
- 3 Connection for optional field communicator
- 4 Analog display device: observe maximum load
- 5 Cable screen; observe cable specification
- 6 4 ... 20 mA HART (passive): terminals 1 and 2
- 7 Switch output (open collector): terminals 3 and 4
- 8 Terminal for potential equalization line
- 9 Cable entry for 4 ... 20 mA HART line
- 10 Cable entry for switch output line



**2-wire: 4 ... 20 mA HART, 4 ... 20 mA**

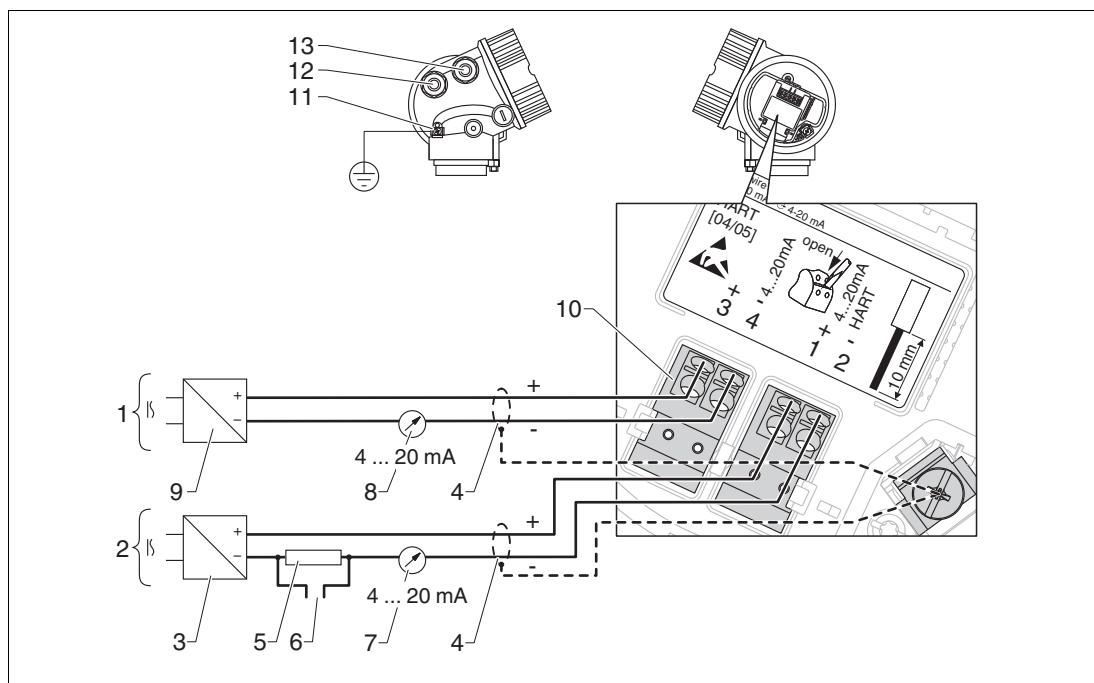


Figure 7.3 Terminal assignment 2-wire, 4 ... 20 mA HART, 4 ... 20 mA

- 1 Connection current output 2
- 2 Connection current output 1
- 3 Supply voltage for current output 1 (e. g. KCD2-STC-Ex1); observe terminal voltage
- 4 Cable screen; observe cable specification
- 5 HART communication resistor ( $\geq 250 \Omega$ ): observe maximum load
- 6 Connection for optional field communicator
- 7 Analog display device; observe maximum load
- 8 Analog display device; observe maximum load
- 9 Supply voltage for current output 2 (e. g. KCD2-STC-Ex1); observe terminal voltage
- 10 Current output 2: terminals 3 and 4
- 11 Terminal for the potential equalization line
- 12 Cable entry for current output 1
- 13 Cable entry for current output 2

**Note!**

This version is also suited for single-channel operation. In this case, current output 1 (terminals 1 and 2) must be used.



### 4-wire: 4 ... 20 mA HART (10.4 ... 48 V DC)

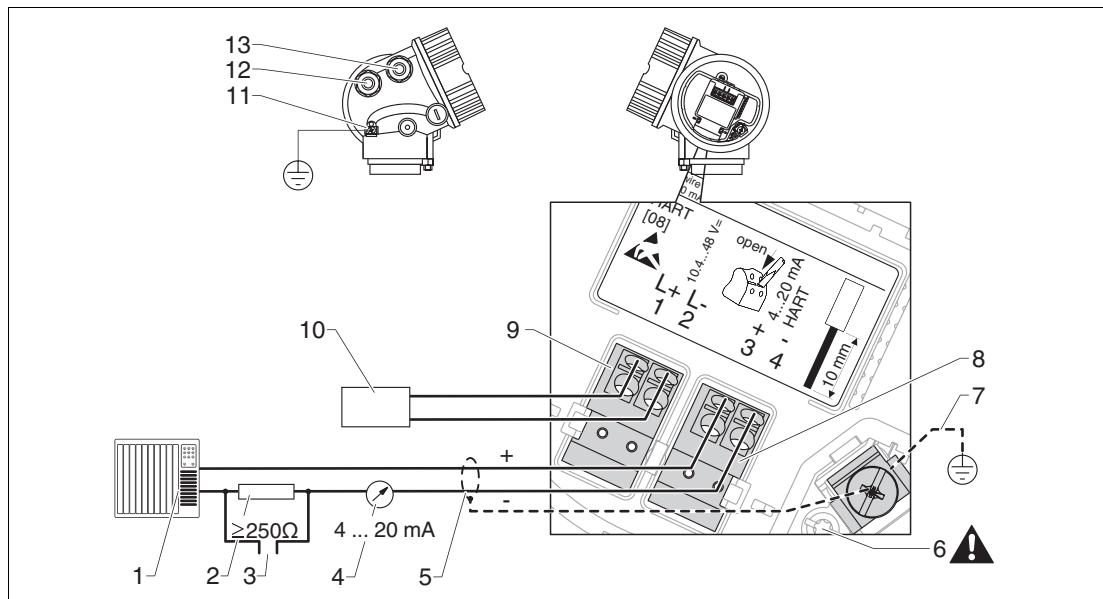


Figure 7.4 Terminal assignment 4-wire; 4 ... 20 mA HART (10.4 ... 48 V DC)

- 1 Evaluation unit, e. g. PLC
- 2 HART communication resistor ( $\geq 250 \Omega$ ): observe maximum load
- 3 Connection for optional field communicator
- 4 Analog display device: observe maximum load
- 5 Signal cable including screening (if required), observe cable specification
- 6 Protective connection; do not disconnect!
- 7 Protective earth, observe cable specification
- 8 4 ... 20 mA HART (active): terminals 3 and 4
- 9 Supply voltage: terminals 1 and 2
- 10 Supply voltage: Observe terminal voltage, observe cable specification
- 11 Terminal for potential equalization
- 12 Cable entry for signal line
- 13 Cable entry for power supply



#### **Warning!**

To ensure electrical safety:

- Do not disconnect the protective connection (6).
- Disconnect the supply voltage before disconnecting the protective earth (7).



#### **Note!**

Connect protective earth to the internal ground terminal (7) before connecting the supply voltage. If necessary, connect the potential matching line to the external ground terminal (11).



**Note!**

In order to ensure electromagnetic compatibility (EMC): Do **not** only ground the device via the protective earth conductor of the supply cable. Instead, the functional grounding must also be connected to the process connection (flange or threaded connection) or to the external ground terminal.



**Note!**

An easily accessible power switch must be installed in the proximity of the device. The power switch must be marked as a disconnector for the device (IEC/EN 61010).

### 4-wire: 4 ... 20 mA HART (90 ... 253 V AC)

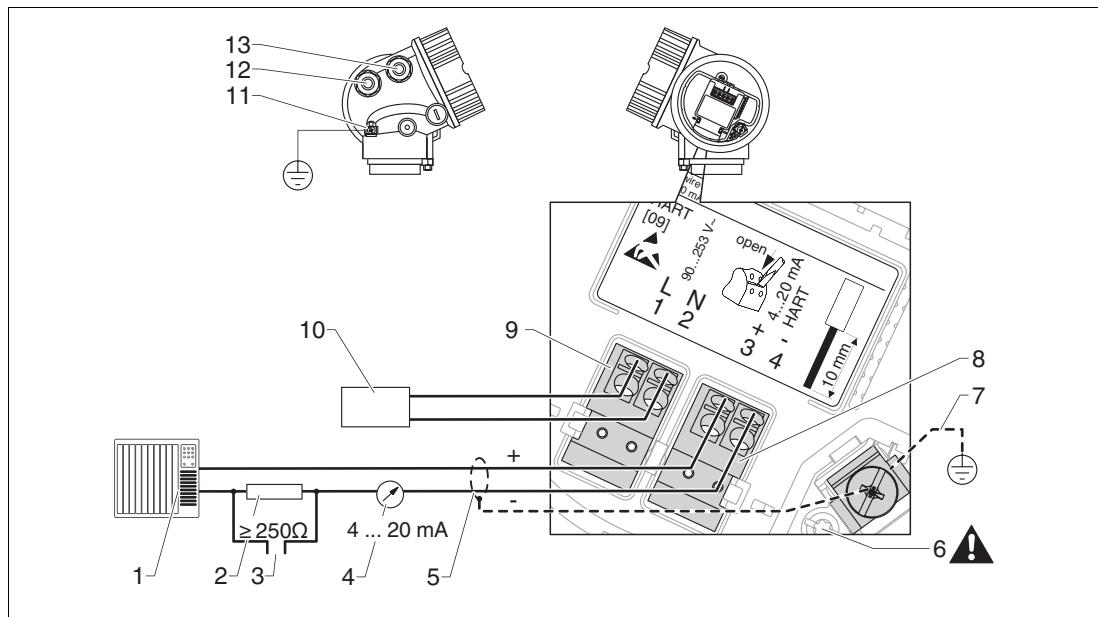


Figure 7.5 Terminal assignment 4-wire; 4 ... 20 mA HART (90 ... 253 V AC)

- 1 Evaluation unit, e. g. PLC
- 2 HART communication resistor ( $\geq 250 \Omega$ ): observe maximum load
- 3 Connection for optional field communicator
- 4 Analog display device: observe maximum load
- 5 Signal cable including screening (if required), observe cable specification
- 6 Protective connection; do not disconnect!
- 7 Protective earth, observe cable specification
- 8 4 ... 20 mA HART (active): terminals 3 and 4
- 9 Supply voltage: terminals 1 and 2
- 10 Supply voltage: observe terminal voltage, observe cable specification
- 11 Terminal for potential equalization
- 12 Cable entry for signal line
- 13 Cable entry for power supply



#### **Warning!**

To ensure electrical safety:

- Do not disconnect the protective connection (6).
- Disconnect the supply voltage before disconnecting the protective earth (7).



#### **Note!**

Connect protective earth to the internal ground terminal (7) before connecting the supply voltage. If necessary, connect the potential matching line to the external ground terminal (11).



**Note!**

In order to ensure electromagnetic compatibility (EMC): Do **not** only ground the device via the protective earth conductor of the supply cable. Instead, the functional grounding must also be connected to the process connection (flange or threaded connection) or to the external ground terminal.



**Note!**

An easily accessible power switch must be installed in the proximity of the device. The power switch must be marked as a disconnector for the device (IEC/EN 61010).



### Connection examples for the switch output

<p>Connection of a relay Suitable relays (examples):</p> <ul style="list-style-type: none"><li>• Solid-state relay: Phoenix Contact OV-24DC/480AC/5 with mounting rail connector UMK-1 OM-R/AMS</li><li>• Electromechanical relay: Phoenix Contact PLC-RSC-12DC/21</li></ul>	<p>Connection of a digital input</p> <p>1 Pull-up resistor 2 Digital input</p>

Table 7.1



#### Note!

For optimum interference immunity we recommend to connect an external resistor (internal resistance of the relay or Pull-up resistor) of < 1000 Ω.



## 7.1.2

### Cable specification

- Minimum cross-section: See the terminal specification in the Technical Information for the device.
- For ambient temperature  $T_{amb} \geq 60^{\circ}\text{C}$  ( $140^{\circ}\text{F}$ ): use cable for temperature  $T_{amb} + 20\text{ K}$ .

### HART

- A normal device cable suffices if only the analog signal is used.
- A shielded cable is recommended if using the HART protocol. Observe grounding concept of the plant.
- For 4-wire devices: Standard device cable is sufficient for the power line.



### 7.1.3

### Device plug connectors



#### Note!

For the versions with fieldbus plug connector (M12 or 7/8 in), the signal line can be connected without opening the housing.

Pin assignment of the M12 plug connector

Pin	Meaning
1	Signal +
2	not connected
3	Signal -
4	Ground

Table 7.2

Pin assignment of the 7/8 in plug connector

Pin	Meaning
1	Signal -
2	Signal +
3	not connected
4	Screen

Table 7.3



#### 7.1.4

#### Power supply

##### 2-wire, 4 ... 20 mA HART, passive<sup>1</sup>

Approval <sup>a</sup>	Terminal voltage U at the device	Maximum load R, depending on the supply voltage U <sub>0</sub> at the supply unit										
<ul style="list-style-type: none"> <li>• Non-Ex</li> <li>• Ex nA</li> <li>• CSA GP</li> </ul>	11.5 ... 35 V <sup>b</sup>	<table border="1"> <caption>Data points for Graph 1</caption> <thead> <tr> <th>Supply voltage U₀ [V]</th> <th>Maximum load R [Ω]</th> </tr> </thead> <tbody> <tr><td>11.5</td><td>0</td></tr> <tr><td>22.5</td><td>500</td></tr> <tr><td>30</td><td>500</td></tr> <tr><td>35</td><td>750</td></tr> </tbody> </table>	Supply voltage U₀ [V]	Maximum load R [Ω]	11.5	0	22.5	500	30	500	35	750
Supply voltage U₀ [V]	Maximum load R [Ω]											
11.5	0											
22.5	500											
30	500											
35	750											
• Ex ic	11.5 ... 32 V <sup>c</sup>											
• Ex ia/IS	11.5 ... 30 V <sup>d</sup>											
<ul style="list-style-type: none"> <li>• Ex d/XP</li> <li>• Ex ic(ia)</li> <li>• Ex tD/DIP</li> </ul>	13.5 ... 30 V <sup>e</sup>	<table border="1"> <caption>Data points for Graph 2</caption> <thead> <tr> <th>Supply voltage U₀ [V]</th> <th>Maximum load R [Ω]</th> </tr> </thead> <tbody> <tr><td>13.5</td><td>0</td></tr> <tr><td>24.5</td><td>500</td></tr> <tr><td>30</td><td>500</td></tr> <tr><td>30</td><td>0</td></tr> </tbody> </table>	Supply voltage U₀ [V]	Maximum load R [Ω]	13.5	0	24.5	500	30	500	30	0
Supply voltage U₀ [V]	Maximum load R [Ω]											
13.5	0											
24.5	500											
30	500											
30	0											

Table 7.4

<sup>a</sup> Feature "Approval" of the product structure

<sup>b</sup> For ambient temperatures  $T_{\text{amb}} \leq -30^{\circ}\text{C}$  (-22 °F) a minimum voltage of 14 V is required for the startup of the device at the MIN error current (3.6 mA). The startup current can be parametrized. If the device is operated with a fixed current  $I \geq 4.5 \text{ mA}$  (HART multidrop mode), a voltage of  $U \geq 11.5 \text{ V}$  is sufficient throughout the entire range of ambient temperatures.

<sup>c</sup> For ambient temperatures  $T_{\text{amb}} \leq -30^{\circ}\text{C}$  (-22 °F) a minimum voltage of 14 V is required for the startup of the device at the MIN error current (3.6 mA). The startup current can be parametrized. If the device is operated with a fixed current  $I \geq 4.5 \text{ mA}$  (HART multidrop mode), a voltage of  $U \geq 11.5 \text{ V}$  is sufficient throughout the entire range of ambient temperatures.

<sup>d</sup> For ambient temperatures  $T_{\text{amb}} \leq -30^{\circ}\text{C}$  (-22 °F) a minimum voltage of 14 V is required for the startup of the device at the MIN error current (3.6 mA). The startup current can be parametrized. If the device is operated with a fixed current  $I \geq 4.5 \text{ mA}$  (HART multidrop mode), a voltage of  $U \geq 11.5 \text{ V}$  is sufficient throughout the entire range of ambient temperatures.

<sup>e</sup> For ambient temperatures  $T_{\text{amb}} \leq -20^{\circ}\text{C}$  (-4 °F) a minimum voltage of 16 V is required for the startup of the device at the MIN error current (3.6 mA).

<sup>1</sup> Feature "Electrical Output" of the product structure, option IH

**2-wire; 4 ... 20 mA HART, switch output<sup>1</sup>**

Approval <sup>a</sup>	Terminal voltage U at the device	Maximum load R, depending on the supply voltage U <sub>0</sub> at the supply unit										
<ul style="list-style-type: none"> <li>• Non-Ex</li> <li>• Ex nA</li> <li>• Ex nA(ia)</li> <li>• Ex ic</li> <li>• Ex ic(ia)</li> <li>• Ex d(ia)/XP</li> <li>• Ex ta/DIP</li> <li>• CSA GP</li> </ul>	12 ... 35 V <sup>b</sup>	<table border="1"> <caption>Data points from the graph</caption> <thead> <tr> <th>Supply voltage U₀ [V]</th> <th>Maximum load R [Ω]</th> </tr> </thead> <tbody> <tr><td>12</td><td>0</td></tr> <tr><td>23</td><td>500</td></tr> <tr><td>30</td><td>500</td></tr> <tr><td>35</td><td>0</td></tr> </tbody> </table>	Supply voltage U₀ [V]	Maximum load R [Ω]	12	0	23	500	30	500	35	0
Supply voltage U₀ [V]	Maximum load R [Ω]											
12	0											
23	500											
30	500											
35	0											
<ul style="list-style-type: none"> <li>• Ex ia/IS</li> <li>• Ex ia + Ex d(ia)/IS + XP</li> </ul>	12 ... 30 V <sup>c</sup>											

Table 7.5

a Feature "Approval" of the product structure

b For ambient temperatures  $T_{\text{amb}} \leq -30^{\circ}\text{C}$  (-22 °F) a minimum voltage of 14 V is required for the startup of the device at the MIN error current (3.6 mA).

c For ambient temperatures  $T_{\text{amb}} \leq -30^{\circ}\text{C}$  (-22 °F) a minimum voltage of 14 V is required for the startup of the device at the MIN error current (3.6 mA).



**2-wire; 4 ... 20 mA HART, 4 ... 20 mA<sup>1</sup>**

Approval <sup>a</sup>	Terminal voltage U at the device	Maximum load R, depending on the supply voltage U <sub>0</sub> at the supply unit								
all	<b>Channel 1:</b> 13.5 ... 30 V <sup>b</sup>	<table border="1"> <caption>Data points for Channel 1 graph</caption> <thead> <tr> <th>Supply voltage U₀ [V]</th> <th>Maximum load R [Ω]</th> </tr> </thead> <tbody> <tr><td>13.5</td><td>0</td></tr> <tr><td>24.5</td><td>500</td></tr> <tr><td>30</td><td>500</td></tr> </tbody> </table>	Supply voltage U₀ [V]	Maximum load R [Ω]	13.5	0	24.5	500	30	500
Supply voltage U₀ [V]	Maximum load R [Ω]									
13.5	0									
24.5	500									
30	500									
<b>Channel 2:</b> 12 ... 30 V	<table border="1"> <caption>Data points for Channel 2 graph</caption> <thead> <tr> <th>Supply voltage U₀ [V]</th> <th>Maximum load R [Ω]</th> </tr> </thead> <tbody> <tr><td>12</td><td>0</td></tr> <tr><td>23</td><td>500</td></tr> <tr><td>30</td><td>500</td></tr> </tbody> </table>	Supply voltage U₀ [V]	Maximum load R [Ω]	12	0	23	500	30	500	
Supply voltage U₀ [V]	Maximum load R [Ω]									
12	0									
23	500									
30	500									

Table 7.6

a Feature "Approval" of the product structure

b For ambient temperatures  $T_{\text{amb}} \leq -30^{\circ}\text{C}$  (-22 °F) a minimum voltage of 16 V is required for the startup of the device at the MIN error current (3.6 mA).

Polarity reversal protection	yes
Admissible residual ripple at $f = 0$ to 100 Hz	$U_{\text{SS}} < 1 \text{ V}$
Admissible residual ripple at $f = 100$ to 10000 Hz	$U_{\text{SS}} < 10 \text{ mV}$

Table 7.7

<sup>1</sup> Feature "Electrical output" of the product structure, option IE



#### 4-wire, 4 ... 20 mA HART, active

Electrical Output <sup>a</sup>	Terminal voltage U	Maximum load R <sub>max</sub>
<b>AH:</b> 4-wire 90 ... 253 V AC; 4 ... 20 mA HART	90 ... 253 V AC (50 ... 60 Hz), overvoltage category II	500 Ω
<b>DH:</b> 4-wire 10.4 ... 48 V DC; 4 ... 20 mA HART	10.4 ... 48 V DC	

Table 7.8

<sup>a</sup> Feature "Electrical Output" the product structure

#### 7.1.5 Overvoltage protection

If the measuring device is used for level measurement in flammable liquids which requires the use of overvoltage protection according to DIN EN 60079-14, standard for test procedures 60060-1 (10 kA, pulse 8/20 μs), overvoltage protection has to be ensured by an external overvoltage protection module.

#### External overvoltage protection

For detailed information please refer to [www.pepperl-fuchs.com](http://www.pepperl-fuchs.com)



## 7.2

## Connecting the device



### Warning!

Explosion hazard!

- Comply with the relevant national standards.
- Observe the specifications in the Safety Instructions (SI).
- Only use the specified cable glands.
- Check whether the supply voltage matches the specifications on the nameplate.
- Before connecting the device: Switch the supply voltage off.
- Before switching on the supply voltage: Connect the potential bonding line to the exterior ground terminal.

Required tools and accessories:

- For instruments with safety pin for the lid: AF3 Allen key
- Wire stripping pliers
- When using stranded wires: wire end sleeves.

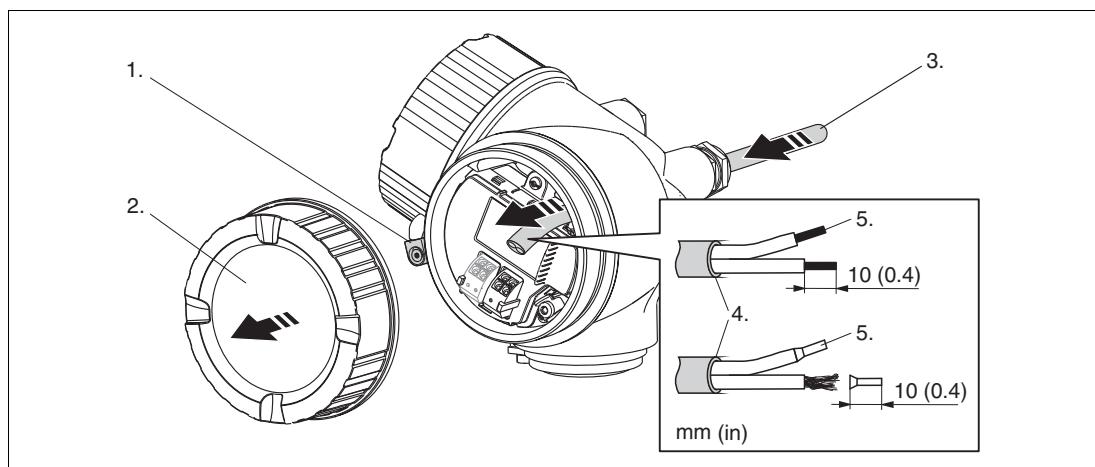


Figure 7.6

### Connecting the device

1. Loosen the screw of the securing clamp of the connection compartment cover and turn the clamp 90° counterclockwise.
2. Unscrew the connection compartment cover.
3. Push the cable through the cable entry. To ensure tight sealing, do not remove the sealing ring from the cable entry.
4. Strip the cable.
5. Strip the cable ends 10 mm (0.4 in). For stranded cables, also attach wire end ferrules.
6. Firmly tighten the cable glands.



7. Connect the cable in accordance with the terminal assignment. See chapter 7.1.1.

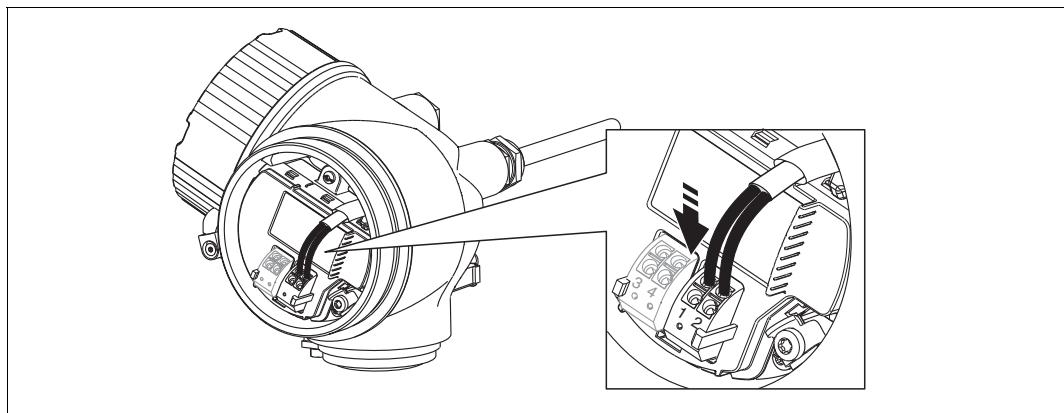


Figure 7.7

8. When using screened cable: Connect the cable screen to the ground terminal.
9. Screw the cover onto the connection compartment.
10. For instruments with safety pin for the lid: Adjust the safety pin so that its edge is over the edge of the display lid. Tighten the safety pin.

### 7.2.1

### Pluggable spring-force terminals

Instruments have pluggable spring-force terminals. Rigid conductors or flexible conductors with cable sleeve can directly be inserted and are contacted automatically.

To remove cables from the terminal: Press on the groove between the terminals using a flat-tip screwdriver  $\leq 3$  mm (0.12 in) while pulling the cables out of the terminals.

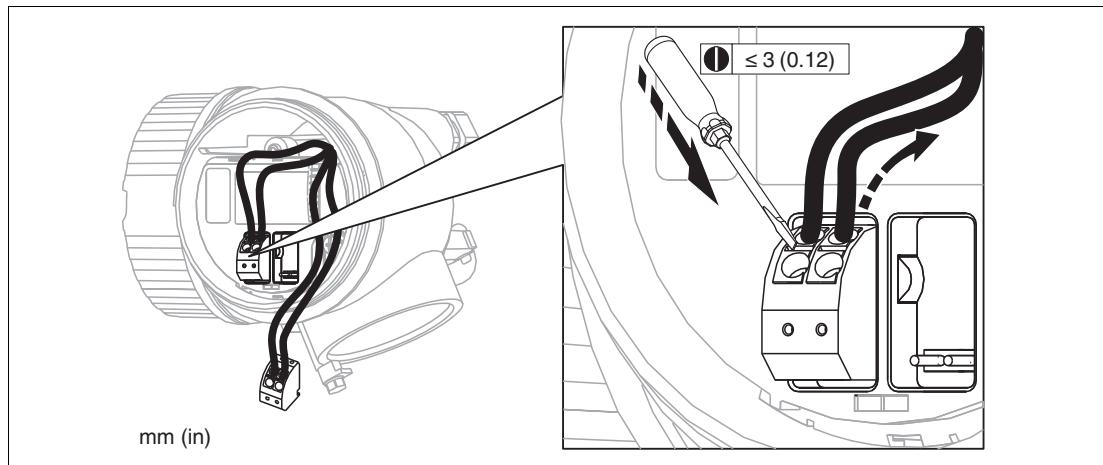


Figure 7.8

## 7.3

### Post-connection check

- Are cables or the device undamaged (visual inspection)?
- Do the cables comply with the requirements?
- Do the cables have adequate strain relief?
- Are all cable glands installed, firmly tightened and correctly sealed?
- Does the supply voltage match the specifications on the transmitter nameplate?
- Is the terminal assignment correct? See chapter 7.1.1.
- If required: Is the protective earth connected correctly? See chapter 7.1.1.
- If supply voltage is present: Is the device ready for operation and do values appear on the display module?
- Are all housing covers installed and firmly tightened?
- Is the securing clamp tightened correctly?

## 8 Operation options

### 8.1 Overview

#### 8.1.1 Local operation

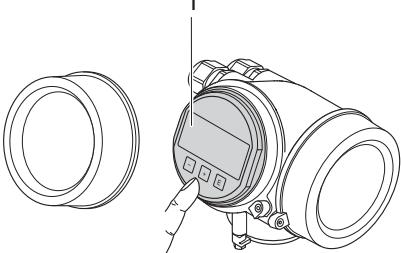
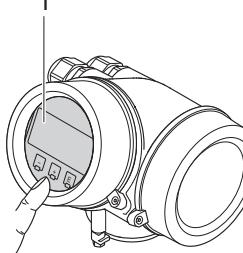
Order code for "Display, operation", option D "SD02"	Order code for "Display, operation", option E "SD03"
	
1 Operation with push buttons	1 Operation with touch control

Table 8.1

#### 8.1.2 Remote operation

##### Via HART protocol

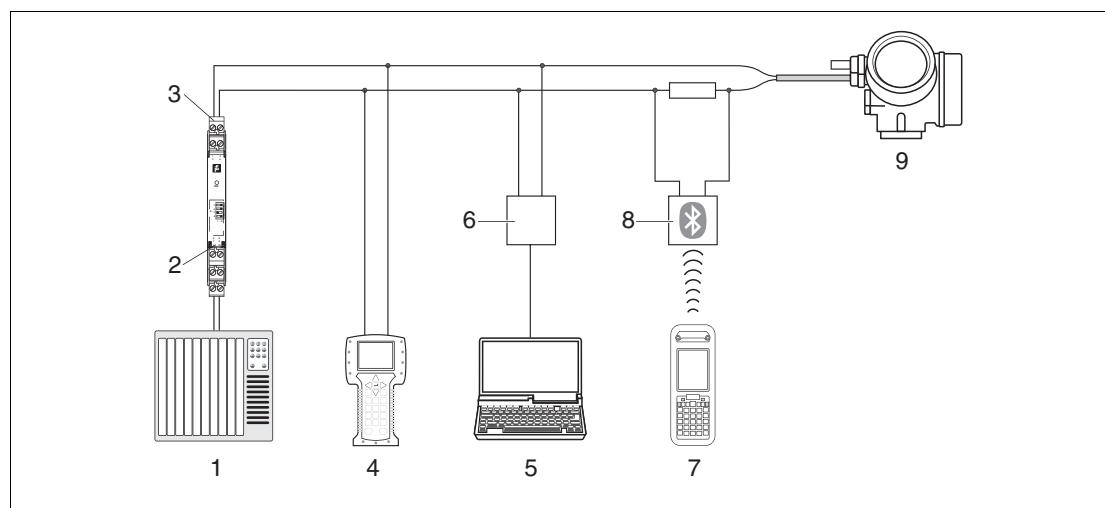


Figure 8.1 Options for remote operation via HART protocol

- 1 PLC (programmable logic controller)
- 2 Transmitter power supply unit, e. g. KFD2-STC-Ex1 (with communication resistor)
- 3 Connection for optional field communicator
- 4 Field communicator
- 5 Computer with operating tool (e. g. PACTware)
- 6 Modem (USB)
- 7 Bluetooth field communicator
- 8 Bluetooth modem with connecting cable
- 9 Transmitter



### Via service interface (CDI)

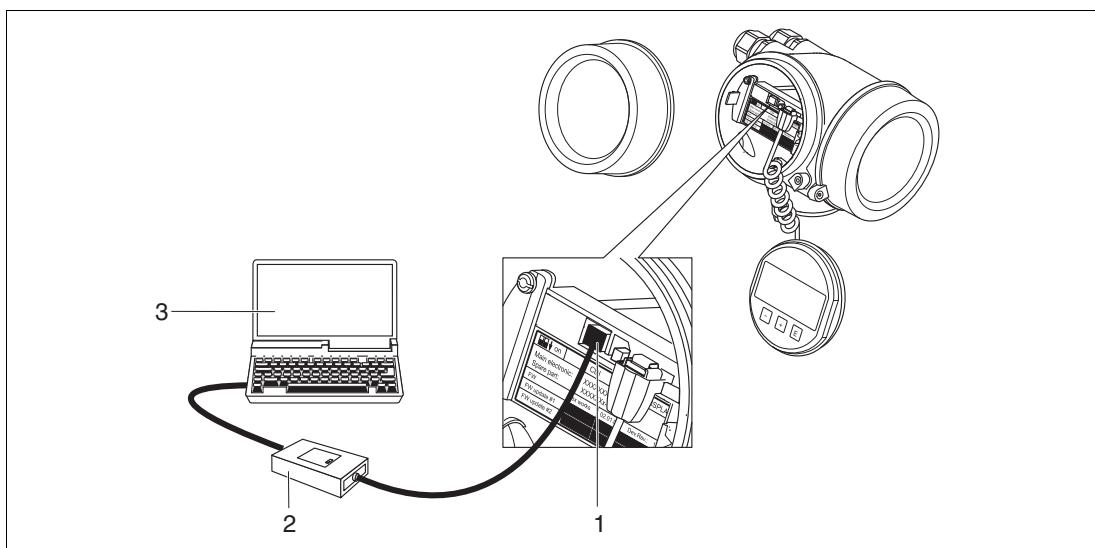


Figure 8.2

- 1 Service interface (CDI) of the measuring device (Common Data Interface)
- 2 Modem
- 3 Computer with PACTware operating tool

## 8.2 Structure and function of the operating menu

### 8.2.1 Structure of the operating menu

Menu	Submenu/parameter	Meaning
	Language <sup>a</sup>	Defines the operating language of the on-site display.
<b>Setup</b>	Parameter 1 ... Parameter N	When all these parameters have been assigned appropriate values, the measured should be completely configured in a standard application.
	<b>Advanced setup</b>	Contains further submenus and parameters: <ul style="list-style-type: none"> <li>• to adapt the device to special measuring conditions.</li> <li>• to process the measured value (scaling, linearization).</li> <li>• to configure the signal output.</li> </ul>
<b>Diagnostics</b>	<b>Diagnostic list</b>	Contains up to 5 currently active error messages.
	<b>Event logbook</b> <sup>b</sup>	Contains the last 20 messages (which are no longer active).
	<b>Device information</b>	Contains information needed to identify the device.
	<b>Measured values</b>	Contains all current measured values.
	<b>Data logging</b>	Contains the history of the individual measuring values.
	<b>Simulation</b>	Used to simulate measured values or output values.
	<b>Device check</b>	Contains all parameters needed to check the measurement capability of the device.
<b>Expert.</b> <sup>c</sup> Contains all parameters of the device (including those which are already contained in one of the above submenus). This menu is organized according to the function blocks of the device.	<b>System</b>	Contains all general device parameters which do not affect the measurement or the communication interface.
	<b>Sensor</b>	Contains all parameters needed to configure the measurement.
	<b>Output</b>	<ul style="list-style-type: none"> <li>• Contains all parameters needed to configure the current output.</li> <li>• Contains all parameters need to configure the switch output (PFS).</li> </ul>
	<b>Communication</b>	Contains all parameters needed to configure the digital communication interface.
	<b>Diagnostics</b>	Contains all parameters needed to detect and analyze operational errors.

Table 8.2

<sup>a</sup> In case of operation via operating tools (e. g. PACTware), the "Language" parameter is located at "Setup → Advanced setup → Display".

<sup>b</sup> Only available for operation via on-site display.

<sup>c</sup> On entering the "Expert" menu, an access code is always requested. If a customer specific access code has not been defined, "0000" has to be entered.



## 8.2.2

### User roles and related access authorization

The two user roles **Operator** and **Maintenance** have different write access to the parameters if a device-specific access code has been defined. This protects the device configuration via the local display from unauthorized access.

#### Access authorization to parameters

User role	Read access		Write access	
	Without access code (from the factory)	With access code	Without access code (from the factory)	With access code
Operator	x	x	x	-
Maintenance	x	x	x	x

Table 8.3

If an incorrect access code is entered, the user obtains the access rights of the **Operator** role.

 **Note!**

The user role with which the user is currently logged on is indicated by the **Access status display** (for display operation) or **Access status tooling** (for tool operation).



### 8.2.3

#### Write protection via access code

Using the device-specific access code, the parameters for the measuring device configuration are write-protected and their values can no longer be changed via local operation.



##### Define access code via local display

1. Navigate to: Setup → Advanced setup → Administration → Define access code → Define access code
2. Define a max. 4-digit numeric code as an access code.
3. Repeat the same code in **Confirm access code** parameters.  
↳ The symbol appears in front of all write-protected parameters.



##### Define access code via operating tool (e. g. PACTware)

1. Navigate to: Setup → Advanced setup → Administration → Define access code
2. Define a max. 4-digit numeric code as an access code.  
↳ Write protection is active.

#### Parameters that can always be changed

The write protection does not include certain parameters that do not affect the measurement. Despite the defined access code, they can always be modified, even if the other parameters are locked.

If no key is pressed for 10 minutes in the navigation and editing mode, the device automatically locks the write-protected parameters. If the user goes from the navigation and editing mode back to the measured value display mode, the device automatically locks the write-protected parameters after 60 s.



##### Note!

- If write access is activated via access code, it can be also be deactivated only via the access code.
- In the "Description of Device Parameters" documents, each write-protected parameter is identified with the symbol.

### 8.2.4

#### Disabling write protection via access code

If the symbol appears on the local display in front of a parameter, the parameter is write-protected by a device-specific access code and its value cannot be changed at the moment using the local display.



##### Disabling write protection

The locking of the write access via local operation can be disabled by entering the device-specific access code.

1. After you press , the input prompt for the access code appears.
2. Enter the access code.  
↳ The symbol in front of the parameters disappears; all previously write-protected parameters are now re-enabled.



## 8.2.5

### Deactivation of the write protection via access code

► Deactivating write protection via local display

1. Navigate to: Setup → Advanced setup → Administration → Define access code → Define access code
2. Enter **0000**.
3. Repeat **0000** in **Confirm access code** parameter.

↳ The write protection is deactivated. Parameters can be changed without entering an access code.

► Deactivating write protection via operating tool (e. g. PACTware)

1. Navigate to: Setup → Advanced setup → Administration → Define access code
  2. Enter **0000**.
- ↳ The write protection is deactivated. Parameters can be changed without entering an access code.

## 8.2.6

### Write protection via lock switch

Unlike write protection via a user-specific access code, this allows write access to the entire operating menu – other than the **Contrast display** parameter – to be locked.

The parameter values are now read only and cannot be edited any more (exception **Contrast display** parameter) via:

- local display
- PROFIBUS PA protocol

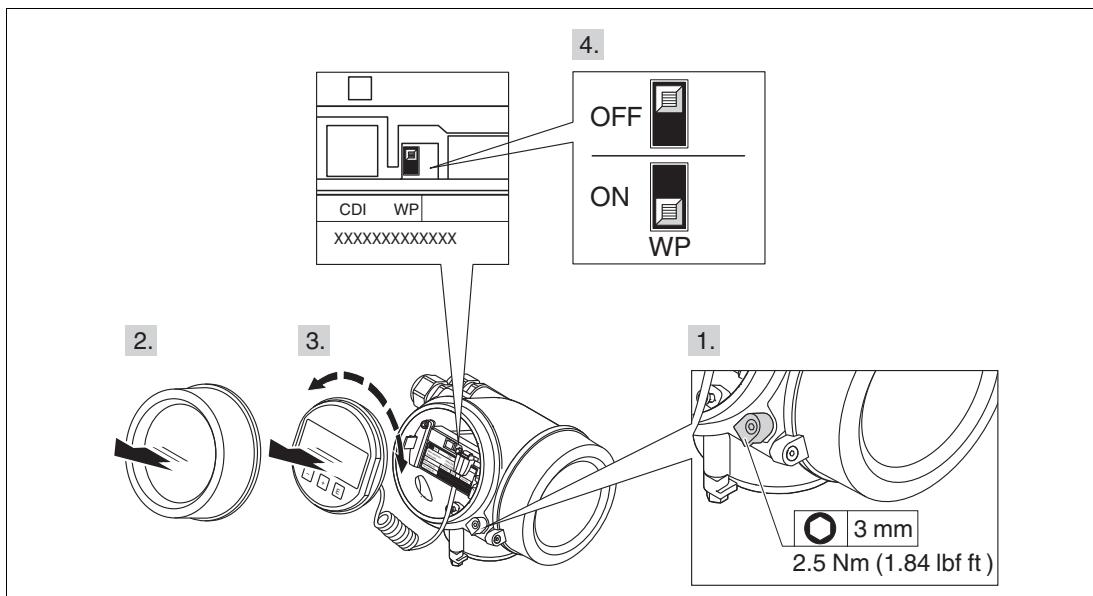


Figure 8.3



### Setting write protection via lock switch

1. Loosen the securing clamp.
2. Unscrew the electronics compartment cover.
3. Pull out the display module with a gentle rotation movement. To make it easier to access the lock switch, attach the display module to the edge of the electronics compartment.

↳ Display module is attached top the edge of the electronics compartment.

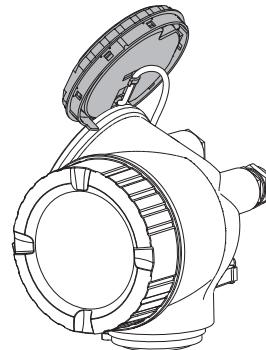


Figure 8.4

4. Set the lock switch (WP) on the main electronics module in the **ON** position enables the hardware write protection. Set the lock switch (WP) on the main electronics module in the **OFF** position (factory setting) disables the hardware write protection.  
↳ If the hardware write protection is enabled: The **Hardware locked** option is displayed in the **Locking status** parameter. In addition to this, the symbol appears in the header of the measured value display and in the navigation view in front of the parameters.  
↳ If the hardware write protection is disabled: No option is displayed in the **Locking status** parameter. The symbol disappears in the header of the measured value display and in the navigation view in front of the parameters

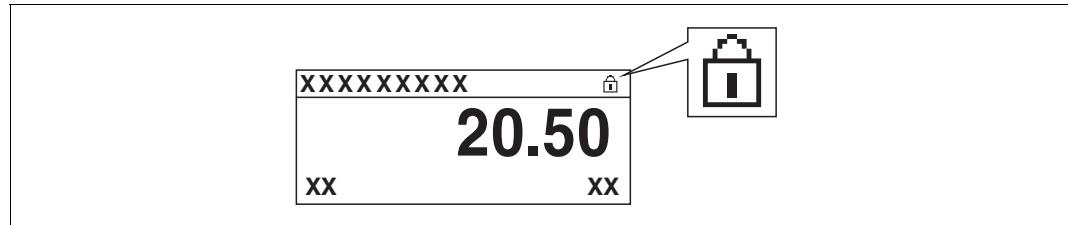


Figure 8.5

5. Feed the spiral cable into the gap between the housing and main electronics module and plug the display module into the electronics compartment in the desired direction until it engages.
6. Screw the electronics compartment cover closed and tighten the securing clamp.



## 8.2.7

### Enabling and disabling the keypad lock

The keypad lock allows you disable access to the entire operating menu via local operation. Thus navigating through the operating menu or modifying the values of individual parameters is no longer possible. Only the measured values on the measured value display can be read off.

#### Keylock via push buttons (SD02 display module)

The keylock is enabled and disabled in the same way.

##### Enabling the keylock

The device is in the measured value display mode.

Press the + + keys simultaneously.

→ The **Keylock on** message appears on the display: The keylock is enabled.

##### *Note!*

When attempting to access the operating menu while the keylock is enabled, the **Keylock on** message appears.

##### Disabling the keylock

The keylock is enabled.

Press the + + keys simultaneously.

→ The **Keylock off** message appears on the display: The keylock is disabled.

#### Keylock via touch-control (SD03 display module)

The keylock is enabled and disabled via a context menu.

##### Enabling the keylock

The device is in the measured value display mode. The keylock is automatically enabled:

- after each restart of the device
- if the device is in the measured value display mode and has not been operated for at least one minute.

1. Press the key for at least two seconds.

→ A context menu appears.

2. Select the **Keylock on** option from the context menu.

→ The keylock is enabled.

##### *Note!*

When attempting to access the operating menu while the keylock is enabled, the **Keylock on** message appears.

##### Disabling the keylock

The keylock is enabled.

1. Press the key for at least two seconds.

→ A context menu appears.

2. Select the **Keylock off** option from the context menu.

→ The keylock is disabled.

## 8.3 Display and operating module

### 8.3.1 Display appearance

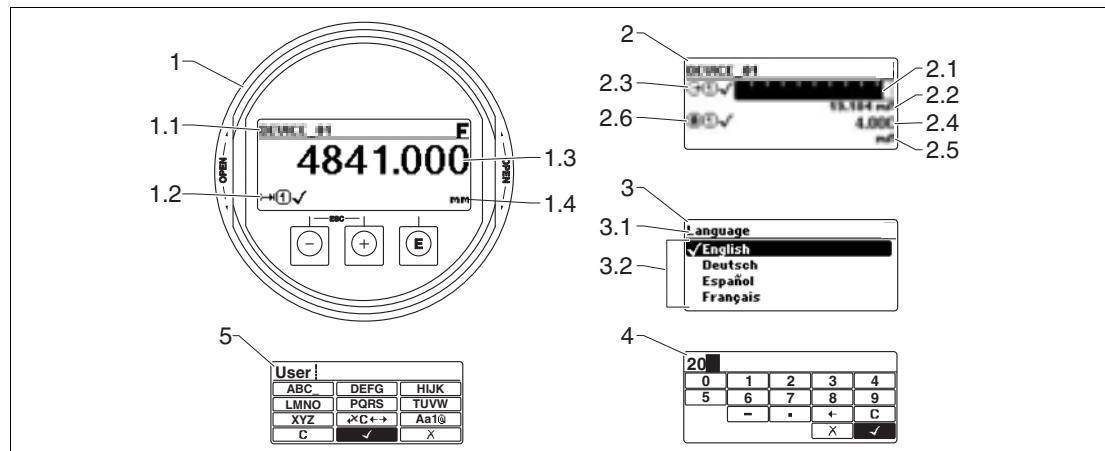


Figure 8.6 Appearance of the display and operation module for on-site operation

- 1** Measured value display (1 value max. size)
- 1.1** Header containing tag and error symbol (if an error is active)
- 1.2** Measured value symbols
- 1.3** Measured value
- 1.4** Unit
- 2** Measured value display (1 bargraph and 1 value)
- 2.1** Bargraph for measured value 1
- 2.2** Measured value 1 (including unit)
- 2.3** Measured value symbols for measured value 1
- 2.4** Measured value 2
- 2.5** Unit for measured value 2
- 2.6** Measured value symbols for measured value 2
- 3** Representation of a parameter (here: a parameter with selection list)
- 3.1** Header containing parameter name and error symbol (if an error is active)
- 3.2** Selection list;  marks the current parameter value.
- 4** Input matrix for numbers
- 5** Input matrix for alphanumeric and special characters



### Display symbols for the submenus

Symbol	Meaning
	<b>Display/operation</b> Is displayed: <ul style="list-style-type: none"><li>• in the main menu next to the selection "Display/operation"</li><li>• in the header, if you are in the "Display/operation" menu</li></ul>
	<b>Setup</b> Is displayed: <ul style="list-style-type: none"><li>• in the main menu next to the selection "Setup"</li><li>• in the header, if you are in the "Setup" menu</li></ul>
	<b>Expert</b> Is displayed: <ul style="list-style-type: none"><li>• in the main menu next to the selection "Expert"</li><li>• in the header, if you are in the "Expert" menu</li></ul>
	<b>Diagnostics</b> Is displayed: <ul style="list-style-type: none"><li>• in the main menu next to the selection "Diagnostics"</li><li>• in the header, if you are in the "Diagnostics" menu</li></ul>

Table 8.4

### Status signals

	<b>Failure (F)</b> A device error is present. The measured value is no longer valid.
	<b>Function check (C)</b> The device is in service mode (e. g. during a simulation).
	<b>Out of specification (S)</b> The device is operated: <ul style="list-style-type: none"><li>• outside of its technical specifications (e. g. during startup or a cleaning)</li><li>• outside of the configuration carried out by the user (e. g. level outside configured span)</li></ul>
	<b>Maintenance required (M)</b> Maintenance is required. The measured value is still valid.

Table 8.5

### Display symbols for the locking state

Symbol	Meaning
	<b>Display parameter</b> Marks display-only parameters which can not be edited.
	<b>Device locked</b> <ul style="list-style-type: none"><li>• In front of a parameter name: The device is locked via software and/or hardware.</li><li>• In the header of the measured value screen: The device is locked via hardware.</li></ul>

Table 8.6



### Measured value symbols

Symbol	Meaning
<b>Measured values</b>	
	<b>Level</b>
	<b>Distance</b>
	<b>Current output</b>
	<b>Measured current</b>
	<b>Terminal voltage</b>
	<b>Temperature of the electronics or the sensor</b>
<b>Measuring channels</b>	
	<b>Measuring channel 1</b>
	<b>Measuring channel 2</b>
<b>Status of the measured value</b>	
	<b>Status "Alarm"</b> The measurement is interrupted. The output assumes the defined alarm value. A diagnostic message is generated.
	<b>Status "Warning"</b> The device continues measuring. A diagnostic message is generated.

Table 8.7



### 8.3.2 Operating elements

Key	Meaning
	<b>Minus key</b> For menu, submenu Moves the selection bar upwards in a picklist. For text and numeric editor In the input mask, moves the selection bar to the left (backwards).
	<b>Plus key</b> For menu, submenu Moves the selection bar downwards in a picklist. For text and numeric editor In the input mask, moves the selection bar to the right (forwards).
	<b>Enter key</b> For measured value display <ul style="list-style-type: none"> <li>Pressing the key briefly opens the operating menu.</li> <li>Pressing the key for 2 s opens the context menu.</li> </ul> For menu, submenu <ul style="list-style-type: none"> <li>Pressing the key briefly Opens the selected menu, submenu or parameter.</li> <li>Pressing the key for 2 s for parameter If present, opens the help text for the function of the parameter.</li> </ul> For text and numeric editor. <ul style="list-style-type: none"> <li>Pressing the key briefly               <ul style="list-style-type: none"> <li>Opens the selected group.</li> <li>Carries out the selected action.</li> </ul> </li> <li>Pressing the key for 2 s confirms the edited parameter value.</li> </ul>
	<b>Escape key combination (press keys simultaneously)</b> For menu, submenu <ul style="list-style-type: none"> <li>Pressing the key briefly               <ul style="list-style-type: none"> <li>Exits the current menu level and takes you to the next higher level.</li> <li>If help text is open, closes the help text of the parameter.</li> </ul> </li> <li>Pressing the key for 2 s returns you to the measured value display ("home position").</li> </ul> For text and numeric editor Closes the text or numeric editor without applying changes.
	<b>Minus/Enter key combination (press and hold down the keys simultaneously)</b> Reduces the contrast (brighter setting).
	<b>Plus/Enter key combination (press and hold down the keys simultaneously)</b> Increases the contrast (darker setting).
	<b>Minus/Plus/Enter key combination (press and hold down the keys simultaneously)</b> For measured value display Enables or disables the keypad lock.

Table 8.8



### 8.3.3

### Entering numbers and text

Numeric editor	Text editor
<p>The diagram shows the Numeric editor interface. It consists of a numeric keypad (labeled 2) with a 2x5 grid of digits (0-9) and four function keys at the bottom: (-), (+), (E), and C. Above the keypad is a display area (labeled 1) showing '20'. A bracket labeled 3 indicates the input mask area below the keypad. A bracket labeled 4 indicates the operating elements at the bottom.</p>	<p>The diagram shows the Text editor interface. It consists of a text keypad (labeled 2) with a 4x3 grid of characters (e.g., ABC, DEF, HIJK, LMNO, PQRS, TUVW, XYZ, Aa1@) and four function keys at the bottom: (-), (+), (E), and C. Above the keypad is a display area (labeled 1) showing 'User'. A bracket labeled 3 indicates the input mask area below the keypad. A bracket labeled 4 indicates the operating elements at the bottom.</p>
<b>1</b> Editing view <b>2</b> Display area of the entered values <b>3</b> Input mask <b>4</b> Operating elements	

Table 8.9

### Input mask

The following input symbols are available in the input mask of the numeric and text editor:

#### Numeric editor

Symbol	Meaning
	Selection of numbers from 0 to 9.
	Inserts decimal separator at the input position.
	Inserts minus sign at the input position.
	Confirms selection.
	Moves the input position one position to the left.
	Exits the input without applying the changes.
	Clears all entered characters.

Table 8.10



### Text editor

Symbol	Meaning
...	Selection of letters from A to Z
	Toggle <ul style="list-style-type: none"><li>• between upper-case and lower-case letters</li><li>• for entering numbers</li><li>• for entering special characters</li></ul>
	Confirms selection.
	Switches to the selection of the correction tools.
	Exits the input without applying the changes.
	Clears all entered characters.

Table 8.11

### Text correction via

Symbol	Meaning
	Clears all entered characters.
	Moves the input position one position to the right.
	Moves the input position one position to the left.
	Deletes one character immediately to the left of the input position.

Table 8.12



### 8.3.4

#### Opening the context menu

Using the context menu, the user can call up the following menus quickly and directly from the operational display:

- Setup
- Conf. backup disp.
- Simulation



#### Calling up and closing the context menu

The user is in the operational display.

1. Press for 2 s.

↳ The context menu opens.

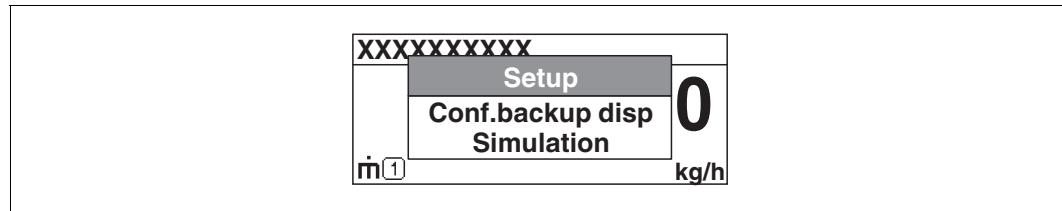


Figure 8.7

2. Press and simultaneously.

↳ The context menu is closed and the operational display appears.



#### Calling up the menu via the context menu

1. Open the context menu.
2. Press to navigate to the desired menu.
3. Press to confirm the selection.

↳ The selected menu opens.

### 8.3.5

### Envelope curve on the display and operating module

In order to assess the measuring signal, the envelope curve and – if a mapping has been recorded – the mapping curve can be displayed:

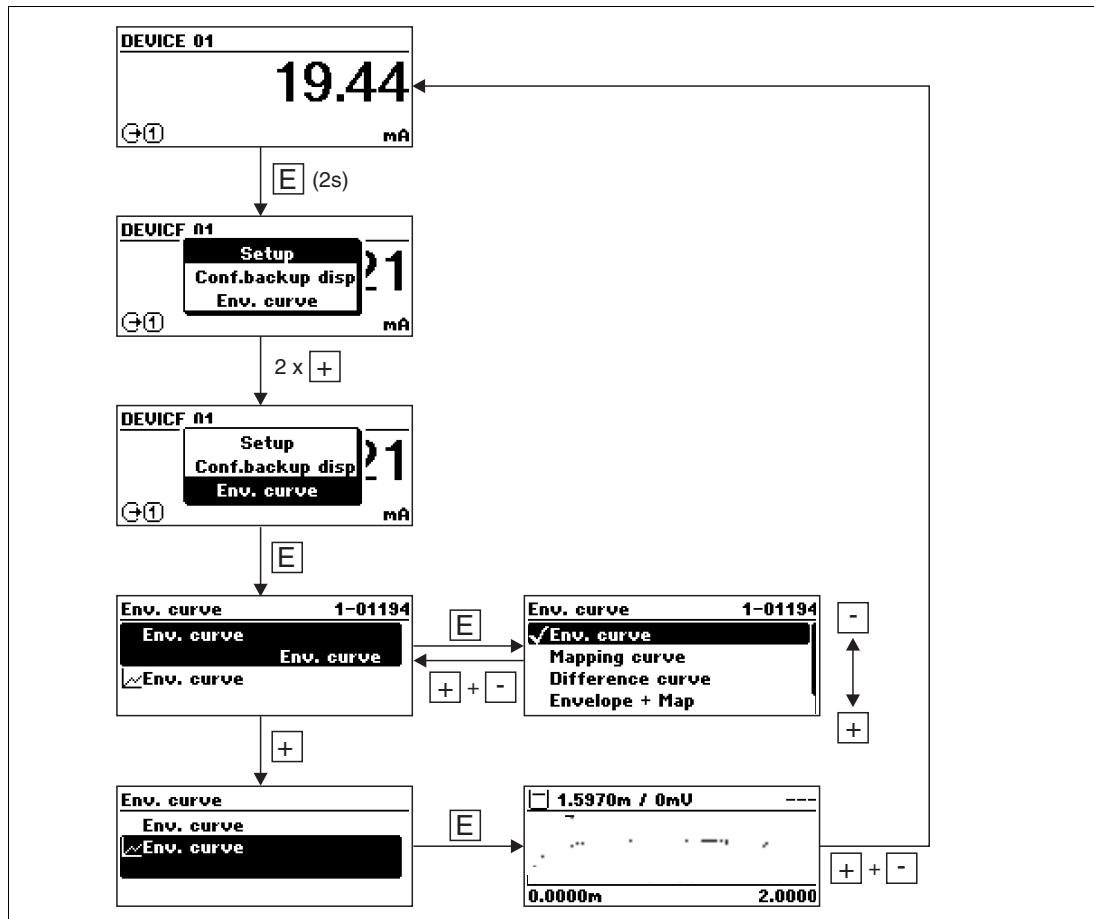


Figure 8.8



## 9

# Device integration via the HART protocol

### 9.1

## Overview of the Device Description files (DD)

### HART

Manufacturer ID	17 (0x11)
Device type	0x34
HART specification	6
DD files	For information and files see: <ul style="list-style-type: none"><li>• <a href="http://www.pepperl-fuchs.com">www.pepperl-fuchs.com</a></li><li>• <a href="http://www.hartcomm.org">www.hartcomm.org</a></li></ul>

Table 9.1

### 9.2

## HART device variables and measuring values

On delivery the following measuring values are assigned to the HART device variables:

Device variable	Measuring value
Primary variable (PV)	Level linearized
Secondary variable (SV)	Unfiltered distance
Tertiary variable (TV)	Absolute echo amplitude
Quaternary variable (QV)	Relative echo amplitude

Table 9.2 Device variables for level measurements



### Note!

The allocation of the measuring values to the device variables can be changed in the following submenu:

Expert → Communication → Output



## 10 Commissioning (via operating menu)

### 10.1 Installation and function check

Make sure that all final checks have been completed before you start up your measuring point:

- Checklist "Post-installation check", see chapter chapter 6
- Checklist "Post-connection check", see chapter chapter 7.2

### 10.2 Setting the operating language

Factory setting: English or ordered local language

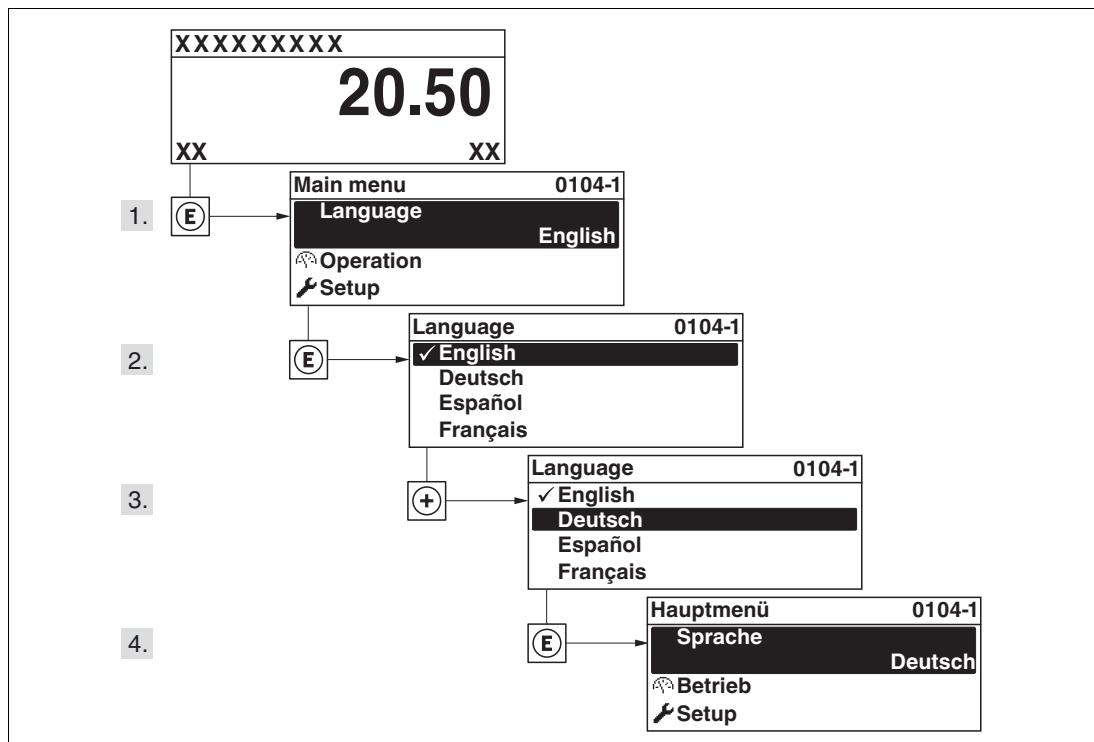


Figure 10.1 Using the example of the local display



### 10.3

### Configuration of a level measurement

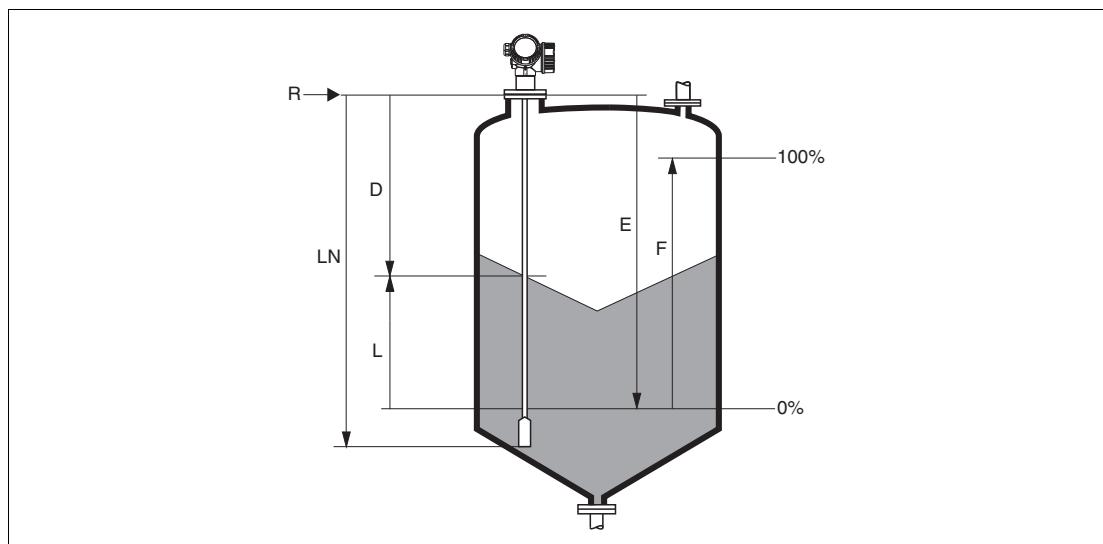


Figure 10.2 Parameters for level measurement with the guided radar

- LN** Probe length
- D** Distance
- L** Level
- R** Reference point of measurement
- E** Empty calibration (= zero)
- F** Full calibration (= span)



**Note!**

If for rope probes the DC value is less than 7, then measurement is not possible in the area of the straining weight. In these cases, the maximum recommended value for the empty calibration E is **LN** – 250 mm (**LN** – 10 in).



#### Configuring level measurement

1. Setup menu → Device tag
  - ↳ Enter tag for measuring point.
2. Navigate to: Setup menu → Distance unit.
  - ↳ Select distance unit.
3. Navigate to: Setup menu → Bin type
  - ↳ Select bin type.
4. Navigate to: Setup menu → Empty calibration
  - ↳ Enter the distance E between the reference point R and the minimum level (0 %).
5. Navigate to: Setup menu → Full calibration.
  - ↳ Enter distance F between the minimum (0 %) and maximum (100 %) level.
6. Navigate to: Setup menu → Level.
  - ↳ Displays the measured level L.
7. Navigate to: Setup menu → Distance.
  - ↳ Displays the distance D between the reference point R and the level L.



8. Navigate to: Setup menu → Signal quality.  
↳ Displays the signal quality of the level echo.
9. For operation via local display:  
Navigate to: Setup menu → Mapping → Mapping → Confirm distance  
↳ Compare the displayed distance to the real distance in order to start the recording of the mapping curve if required.
10. For operation via operating tool:  
Navigate to: Setup menu → Mapping → Confirm distance  
↳ Compare the displayed distance to the real distance in order to start the recording of the mapping curve if required.

## 10.4

### Recording the reference curve

After the configuration of the measurement it is recommended to record the current envelope curve as a reference curve. The reference curve can be used later on in the process for diagnostic purposes. To record the reference curve use the **Save reference curve** parameter.

**Navigation:** Expert → Diagnostics → Envelope diagnostics → Save reference curve

#### Meaning of the options

- No  
No action
- Yes  
The current envelope curve is saved as reference curve.



## 10.5

### Configuration of the on-site display

#### 10.5.1

#### Factory settings of the on-site display for level measurements

Parameter	Factory setting for devices with 1 current output	Factory setting for devices with 2 current outputs
Format display	1 value, max. size	1 value, max. size
Value 1 display	Level linearized	Level linearized
Value 2 display	Distance	Distance
Value 3 display	Current output 1	Current output 1
Value 4 display	None	Current output 2

Table 10.1

#### 10.5.2

#### Adjustment of the on-site display

The on-site display can be adjusted in the following menu:

**Navigation:** Setup → Advanced setup → Display



## 10.6 Configuration of the current outputs

### 10.6.1 Factory setting of the current outputs for level measurements

Current output	Allocated measuring value	4 mA value	20 mA value
1	Level linearized	0 % or the corresponding linearized value	100 % or the corresponding linearized value
2 <sup>a</sup>	Distance	0	Empty calibration

Table 10.2

<sup>a</sup> For devices with 2 current outputs.

### 10.6.2 Adjustment of the current outputs

The current outputs can be adjusted in the following submenus:

#### Basic settings

**Navigation:** Setup → Advanced setup → Current output 1 to 2

#### Advanced settings

**Navigation:** Expert → Output 1 to 2 → Current output 1 to 2

See "Description of Device Parameters" GP01000O



## 10.7

## Configuration management

After commissioning, you can save the current device configuration, copy it to another measuring point or restore the previous device configuration. You can do so using the **Configuration management** parameter and its options.

**Navigation:** Setup → Advanced setup → Configuration backup display → Configuration management

Meaning of the options

- **Cancel**

No action is executed and the user exits the parameter.

- **Execute backup**

A backup copy of the current device configuration in the HistoROM (built-in in the device) is saved to the display module of the device. The backup copy comprises the transmitter and sensor data of the device.

- **Restore**

The last backup copy of the device configuration is copied from the display module to the HistoROM of the device. The backup copy comprises the transmitter and sensor data of the device.

- **Duplicate**

The transmitter configuration is duplicated to another device using the transmitter display module. The following parameters, which characterize the individual measuring point are **not** included in the transmitted configuration:

- HART date code
- HART short tag
- HART message
- HART descriptor
- HART address
- Device tag
- Medium type

- **Compare**

The device configuration saved in the display module is compared to the current device configuration of the HistoROM. The result of this comparison is displayed in the **Comparison result** parameter.

- **Clear backup data**

The backup copy of the device configuration is deleted from the display module of the device.



**Note!**

While this action is in progress, the configuration cannot be edited via the local display and a message on the processing status appears on the display.



**Note!**

If an existing backup is restored to a different device using the **Restore** option, it may occur that some device functionalities are no longer available. In some cases even a device reset will not restore the original status.

In order to transmit a configuration to a different device, the **Duplicate** option should always be used.



## 10.8

### Protection of the settings against unauthorized changes

There are two ways to protect the settings against unauthorized changes:

- Via parameter settings (software locking), see chapter chapter 8
- Via locking switch (hardware locking), see chapter chapter 8

## 11 Diagnostics and troubleshooting

### 11.1 General trouble shooting

#### 11.1.1 General errors

Error	Possible cause	Remedial action
Device does not respond.	Supply voltage does not match the value indicated on the nameplate.	Connect the correct voltage.
	The polarity of the supply voltage is wrong.	Correct the polarity.
	The cables do not contact the terminals properly.	Ensure electrical contact between the cable and the terminal.
Values on the display invisible	Contrast setting is too weak or too strong.	<ul style="list-style-type: none"> <li>• Increase contrast by pressing  and  simultaneously.</li> <li>• Decrease contrast by pressing  and  simultaneously.</li> </ul>
	The plug of the display cable is not connected correctly.	Connect the plug correctly.
	Display is defective.	Replace display.
"Communication error" is indicated on the display when starting the device or connecting the display	Electromagnetic interference	Check grounding of the device.
	Broken display cable or display plug.	Exchange display.
Output current < 3.6 mA	Signal cable connection incorrect.	Check connection.
	Electronics is defective.	Replace electronics.
HART communication does not function.	Communication resistor missing or incorrectly installed.	Install the communication resistor ( $250 \Omega$ ) correctly, see chapter 7.1.1.
	Field communicator connected incorrectly.	Connect field communicator correctly, see chapter 8.
	Field communicator not switched to HART mode.	Set the selection switch of the field communicator to the HART position.
CDI communication does not work.	Wrong setting of the COM port on the computer.	Check the setting of the COM port on the computer and change it if necessary.
Device measures incorrectly.	Parametrization error	Check parameterization and adjust it if necessary (see next chapter).

Table 11.1

### 11.1.2 Parametrization errors

Error	Possible cause	Remedial action
Measured value wrong	If measured distance (Setup menu → Distance) matches the real distance: Calibration error	<ul style="list-style-type: none"> <li>Check and adjust the <b>Empty calibration</b> parameter if necessary, see page 113.</li> <li>Check and adjust the <b>Full calibration</b> parameter if necessary, see page 113.</li> <li>Check and adjust <b>Linearization</b> submenu if necessary, see page 125.</li> </ul>
	If measured distance (Setup menu → Distance) does not match the real distance: An interference echo affects the measurement.	Perform mapping ( <b>Confirm distance</b> parameter), see page 116.
No change of the measured value when emptying/filling the tank	An interference echo affects the measurement.	Perform mapping ( <b>Confirm distance</b> parameter), see page 116.
	Build-up at the probe.	Clean the probe.
	Error in the echo tracking	Deactivate echo tracking: Expert → Sensor → Echo tracking → Evaluation mode = <b>History off</b> .
The <b>Echo lost</b> appears after switching on the supply voltage.	Noise level too high during initialization phase.	Enter <b>Empty calibration</b> parameter again, see page 113.
Device displays a level when the tank is empty.	Incorrect probe length	<ul style="list-style-type: none"> <li>Carry out probe length correction (<b>Confirm probe length</b> parameter), see page 139.</li> <li>Carry out mapping over entire probe while the tank is empty (<b>Confirm distance</b> parameter), see page 116.</li> </ul>
Wrong slope of the level in the entire measuring range	Wrong bin type selected.	Set <b>Bin type</b> parameter correctly, see page 112.

Table 11.2 Parametrization errors for level measurements



## 11.2 Diagnostic information on local display

### 11.2.1 Diagnostic message

Faults detected by the self-monitoring system of the measuring device are displayed as a diagnostic message in alternation with the measured value display.

Measured value display in alarm condition	Diagnostic message
1 Status signal 2 Status symbol (symbol for event level) 3 Status symbol with diagnostics event 4 Event text 5 Operating elements	

Table 11.3

### Status signals

<b>F</b>	<b>Failure (F)</b> A device error is present. The measured value is no longer valid.
<b>C</b>	<b>Function check (C)</b> The device is in service mode (e. g. during a simulation).
<b>S</b>	<b>Out of specification (S)</b> The device is operated: <ul style="list-style-type: none"><li>• outside of its technical specifications (e. g. during startup or a cleaning)</li><li>• outside of the configuration carried out by the user (e. g. level outside configured span)</li></ul>
<b>M</b>	<b>Maintenance required (M)</b> Maintenance is required. The measured value is still valid.

Table 11.4

### Status symbol (symbol for event level)

	<b>"Alarm" status</b> The measurement is interrupted. The signal outputs take on the defined alarm condition. A diagnostic message is generated.
	<b>"Warning" status</b> The device continues to measure. A diagnostic message is generated.

Table 11.5



## Diagnostics event and event text

The fault can be identified using the diagnostics event. The event text helps you by providing information about the fault. In addition, the corresponding symbol is displayed before the diagnostics event.

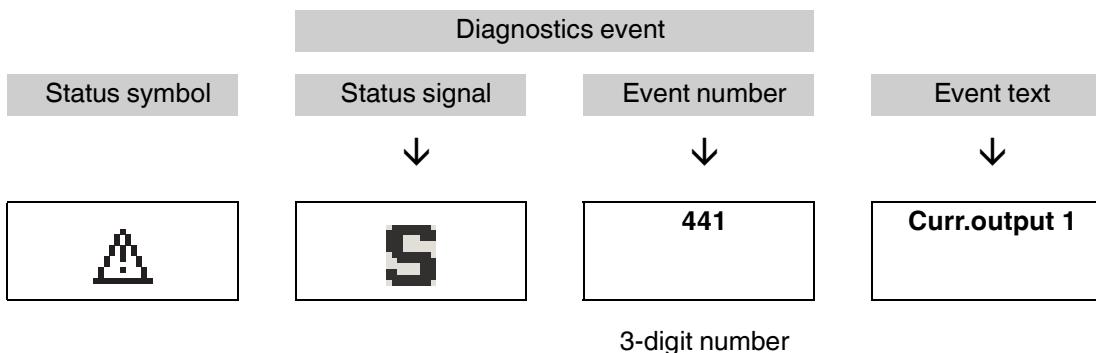


Table 11.6 Example

If two or more diagnostic messages are pending simultaneously, only the message with the highest priority is shown. Additional pending diagnostic messages can be shown in **Diagnostic list** submenu.



### Note!

Past diagnostic messages that are no longer pending are shown as follows:

- On the local display: in **Event logbook** submenu
- In PACTware: via the "Event List /HistoROM" function.

## Operating elements

Operating functions in menu, submenu	
	<b>Plus key</b> Opens the message about the remedial measures.
	<b>Enter key</b> Opens the operating menu.

Table 11.7



### 11.2.2 Remedial measures

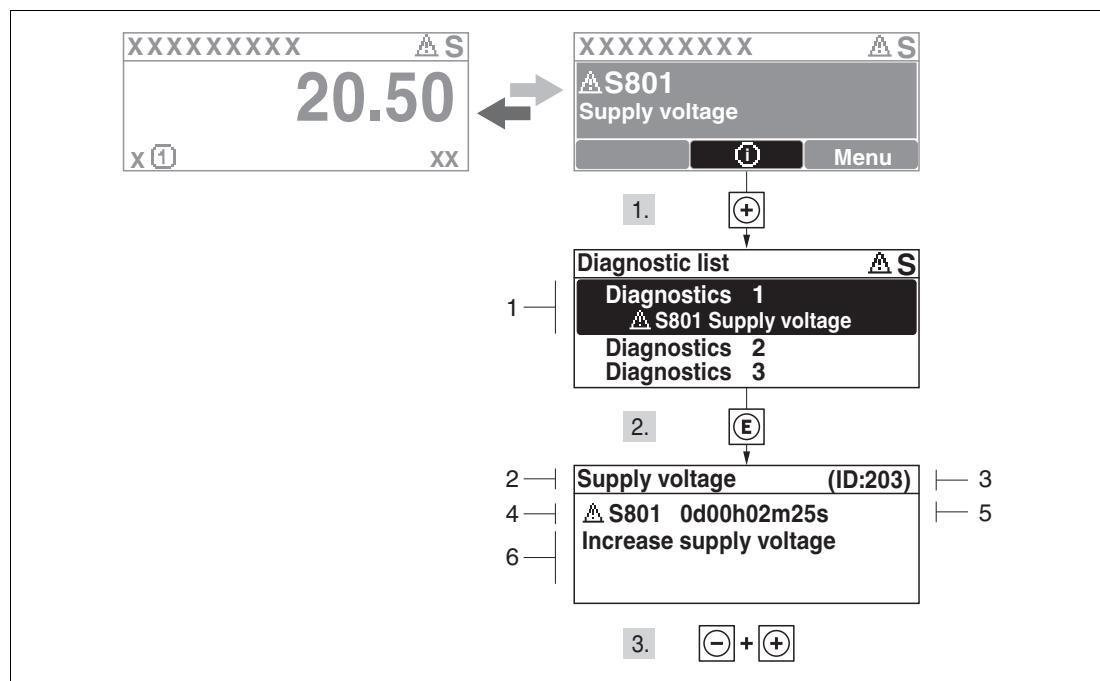


Figure 11.1 Message for remedial measures

- 1 Diagnostic information
- 2 Short text
- 3 Service ID
- 4 Diagnostic behavior with diagnostic code
- 5 Operation time of occurrence
- 6 Remedial measures



#### Calling up remedial measures during a diagnostic message

The user is in the diagnostic message.

1. Press  $\oplus$  ( $\textcircled{i}$  symbol).  
↳ **Diagnostic list** submenu opens.
2. Select the desired diagnostic event with  $\oplus$  or  $\ominus$  and press  $\textcircled{E}$ .  
↳ The message for the remedial measures for the selected diagnostic event opens.
3. Press  $\oplus$  and  $\ominus$  simultaneously.  
↳ The message for the remedial measures closes.



### Calling up remedial measures in diagnostics menu

The user is in the **Diagnostics** menu at an entry for a diagnostics event, e. g. in **Diagnostic list** submenu or in **Previous diagnostics**.

1. Press **E**.  
↳ The message for the remedial measures for the selected diagnostic event opens.
2. Press **⊕** and **⊖** simultaneously.  
↳ The message for the remedial measures closes.

## 11.3 Diagnostic event in the operating tool

If a diagnostic event is present in the device, the status signal appears in the top left status in the operating tool along with the corresponding symbol for event level in accordance with NAMUR NE 107:

- Failure (F)
- Function check (C)
- Out of specification (S)
- Maintenance required (M)



### Calling up remedial measures

1. Navigate to the **Diagnostics** menu.  
↳ In the **Actual diagnostics** parameter, the diagnostic event is shown with event text.
2. On the right in the display range, hover the cursor over the **Actual diagnostics** parameter.  
↳ A tool tip with remedial measures for the diagnostic event appears.



## 11.4

### Diagnostic list

In the **Diagnostic list** submenu, up to 5 currently pending diagnostic messages can be displayed. If more than 5 messages are pending, the messages with the highest priority are shown on the display.

**Navigation:** Diagnostics → Diagnostic list



Calling up and closing the remedial measures

1. Press

↳ The message for the remedial measures for the selected diagnostic event opens.

2. Press and simultaneously.

↳ The message about the remedial measures closes.

## 11.5

### List of diagnostic events

Diagnostic number	Short text	Repairing action	Status signal (from the factory)	Diagnostic behavior (from the factory)
Diagnostic of sensor				
003	Broken probe detected	1. Check map 2. Check sensor	F	Alarm
046	Build-up detected	Clean sensor	F	Alarm
104	HF cable	1. Dry HF cable connection and check sealing 2. Change HF cable	F	Alarm
105	HF cable	1. Tighten HF cable connection 2. Check sensor 3. Change HF cable	F	Alarm
106	Sensor	1. Check sensor 2. Check HF cable 3. Contact service	F	Alarm
Diagnostic of electronic				
242	Software incompatible	1. Check software 2. Flash or change main electronics module	F	Alarm
252	Modules incompatible	1. Check electronic modules 2. Change I/O or main electronic module	F	Alarm
261	Electronic modules	1. Restart device 2. Check electronic modules 3. Change I/O module or main electronics	F	Alarm
262	Module connection	1. Check module connection 2. Change electronic modules	F	Alarm



Diagnostic number	Short text	Repairing action	Status signal (from the factory)	Diagnostic behavior (from the factory)
270	Main electronic failure	Change main electronic module	F	Alarm
271	Main electronic failure	1. Restart device 2. Change main electronic module	F	Alarm
272	Main electronic failure	1. Restart device 2. Contact service	F	Alarm
272	Main electronic failure	1. Restart device 2. Contact service	M	Alarm
273	Main electronic failure	1. Emergency operation via display 2. Change main electronics	F	Alarm
275	I/O module failure	Change I/O module	F	Alarm
276	I/O module failure	1. Restart device 2. Change I/O module	F	Alarm
282	Data storage	1. Restart device 2. Contact service	F	Alarm
283	Memory content	1. Transfer data or reset device 2. Contact service	F	Alarm
311	Electronic failure	1. Transfer data or reset device 2. Contact service	F	Alarm
311	Electronic failure	Maintenance required! 1. Do not perform reset 2. Contact service	M	Warning
Diagnostic of configuration				
410	Data transfer	1. Check connection 2. Retry data transfer	F	Alarm
411	Up-/Download active	Up-/Download active, please wait	C	Warning
431	Trim 1 to 2	Carry out trim	C	Warning
435	Linearization	Check linearization table	F	Alarm
437	Configuration incompatible	1. Restart device 2. Contact service	F	Alarm
438	Dataset	1. Check data set file 2. Check device configuration 3. Up- and download new configuration	M	Warning
441	Current output 1 to 2	1. Check process 2. Check current output settings	S	Warning

Diagnostic number	Short text	Repairing action	Status signal (from the factory)	Diagnostic behavior (from the factory)
484	Simulation failure mode	Deactivate simulation	C	Alarm
485	Simulation measured value	Deactivate simulation	C	Warning
491	Simulation current output 1 to 2	Deactivate simulation	C	Warning
494	Switch output simulation	Deactivate simulation current output	C	Warning
585	Simulation distance	Deactivate simulation	C	Warning
Diagnostic of process				
801	Energy too low	Increase supply voltage	S	Warning
803	Current loop	1. Check wiring 2. Change I/O module	F	Alarm
825	Operating temperature	1. Check ambient temperature 2. Check process temperature	S	Warning
825	Operating temperature	1. Check ambient temperature 2. Check process temperature	F	Alarm
921	Change of reference	1. Check reference configuration 2. Check pressure 3. Check sensor	S	Warning
936	EMC interference	Check installation on EMC	F	Alarm
941	Echo lost	Check DC value	S	Warning
941	Echo lost	Check DC value	F	Alarm
942	In safety distance	1. Check level 2. Check safety distance 3. Reset self holding	S	Warning
942	In safety distance	1. Check level 2. Check safety distance 3. Reset self holding	S	Alarm
943	In blocking distance	Reduced accuracy Check level	S	Warning
944	Level range	Reduced accuracy Level at process connection	S	Warning
950	Advanced diagnostic 1 to 2 occurred	Maintain your diagnostic event	M	Warning <sup>a</sup>

Table 11.8

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<sup>a</sup> Diagnostic status is changeable.

## 11.6 Event logbook

### 11.6.1 Event history

A chronological overview of the event messages that have occurred is provided in the **Event list** submenu<sup>1</sup>.

**Navigation:** Diagnostics → Event logbook → Event list

A maximum of 20 event messages can be displayed in chronological order. If the advanced HistoROM function is enabled in the device (order option), up to 100 entries can be displayed.

The event history includes entries for:

- Diagnostic events
- Information events

In addition to the operation time of its occurrence, each event is also assigned a symbol that indicates whether the event has occurred or is ended:

- Diagnostic event
  - : Event has occurred
  - : Event has ended
- Information event
  - : Event has occurred

#### Calling up and closing the remedial measures

- 
1. Press .  
↳ The message for the remedial measures for the selected diagnostic event opens.
  2. Press and simultaneously.  
↳ The message about the remedial measures closes.

### 11.6.2 Filtering the event logbook

Using the **Filter options** parameter, you can define which category of event messages is displayed in the **Event list** submenu.

**Navigation:** Diagnostics → Event logbook → Filter options

#### Filter categories

- All
- Failure (F)
- Function check (C)
- Out of specification (S)
- Maintenance required (M)
- Information

<sup>1</sup> This submenu can only be accessed via the local display. When operating the device via Software, the event history can be displayed using **Event List /HistoROM** function.



### 11.6.3 List of information events

Info number	Info name
I1000	----- Device OK
I1089	Power on
I1090	Configuration reset
I1091	Configuration changed
I1092	Trend data deleted
I1110	Write protection switch changed
I1137	Electronic changed
I1151	History reset
I1154	Reset terminal voltage min/max
I1155	Reset electronic temperature
I1156	Memory error trend
I1157	Memory error event list
I1184	Display connected
I1185	Display backup done
I1186	Restore via display done
I1187	Settings downloaded with display
I1188	Display data cleared
I1189	Backup compared
I1256	Display: access status changed
I1264	Safety sequence aborted
I1335	Firmware changed
I1398	CDI: access status changed

Table 11.9

## 11.7 Firmware history

Date	Software version	Modifications	Operating Instructions	Description of Parameters	Technical Information
07.2010	01.00.zz	Original software	BA01004O/98/EN/ 05.10	GP01000O/98/EN/ 05.10	TI01004O/98/EN/ 05.10
01.2011	01.01.zz	<ul style="list-style-type: none"> <li>• SIL integrated</li> <li>• Improvements and bugfixes</li> <li>• additional languages</li> </ul>	<ul style="list-style-type: none"> <li>• BA01004O/98/EN /10.10</li> <li>• BA01004O/98/EN /13.11</li> <li>• BA01004O/98/EN /14.12</li> </ul>	<ul style="list-style-type: none"> <li>• GP01000O/98/E N/10.10</li> <li>• GP01000O/98/E N/13.11</li> </ul>	<ul style="list-style-type: none"> <li>• TI01004O/98/EN/ 10.10</li> <li>• TI01004O/98/EN/ 13.11</li> <li>• TI01004O/98/EN/ 14.12</li> <li>• TI01004O/98/EN/ 15.12</li> </ul>
02.2014	01.02.zz	<ul style="list-style-type: none"> <li>• Support of SD03</li> <li>• additional languages</li> <li>• HistoROM functionality enhanced</li> <li>• <b>Advanced Diagnostic</b> function block integrated</li> <li>• Improvements and bugfixes</li> </ul>	BA01004O/98/EN/ 15.13	GP01000O/98/EN/ 14.13	TI01004O/98/EN/ 16.13

Table 11.10



## 12 Maintenance

The measuring device requires no special maintenance.

### 12.1 Exterior cleaning

When exterior-cleaning the device, always use cleaning agents that do not attack the surface of the housing and the seals.



## 13 Repairs

### 13.1 General information on repairs

#### 13.1.1 Repair concept

The Pepperl+Fuchs repair concept assumes that the devices have a modular design and that repairs can be done by the Pepperl+Fuchs service or specially trained customers.

Spare parts are contained in suitable kits. They contain the related replacement instructions.

For more information on service and spare parts, contact the Service Department at Pepperl+Fuchs.

#### 13.1.2 Repairs to Ex-approved devices

When carrying out repairs to Ex-approved devices, please note the following:

- Repairs to Ex-approved devices may only be carried out by trained personnel or by the Pepperl+Fuchs Service.
- Comply with the prevailing standards, national Ex-area regulations, safety instructions (SI) and certificates.
- Only use original spare parts from Pepperl+Fuchs.
- When ordering a spare part, please note the device designation on the nameplate. Only replace parts with identical parts.
- Carry out repairs according to the instructions. On completion of repairs, carry out the specified routine test on the device.
- Only Pepperl+Fuchs Service may convert a certified device into a different certified variant.
- Document all repair work and conversions.

#### 13.1.3 Replacement of an electronics module

If an electronics module has been replaced, it is not necessary to perform a new basic setup as the calibration parameters are stored in the HistoROM which is located in the housing.

However, after exchanging the main electronics module it may be necessary to record a new mapping (interference echo suppression).

#### 13.1.4 Replacement of a device

After a complete device or electronic module has been replaced, the parameters can be downloaded into the instrument again in one of the following ways:

- Via the display module  
Condition: The configuration of the old device has been saved in the display module.
- Via PACTware  
Condition: The configuration of the old device has been saved to the computer via PACTware.

You can continue to measure without carrying out a new setup. Only a linearization and a tank map (interference echo suppression) have to be recorded again.



## 13.2

### Spare parts

- A few interchangeable measuring device components are identified by a spare part nameplate. This contains information about the spare part.
- The connection compartment cover of the device contains a spare part nameplate that includes the following information:
  - A list of the most important spare parts for the measuring device, including their ordering information.
  - For additional information of spare parts, refer to [www.pepperl-fuchs.com](http://www.pepperl-fuchs.com). There, all spare parts for the measuring device are listed, including the order code, and can be ordered. If available, the corresponding Installation Instructions can also be downloaded there.

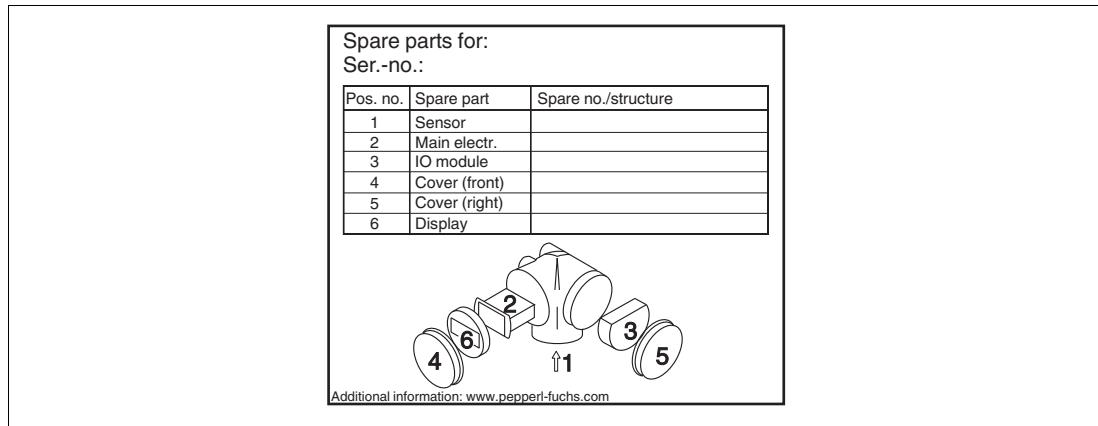


Figure 13.1 Example for spare part nameplate in connection compartment cover



#### Note!

Measuring device serial number:

- Is located on the device and spare part nameplate.
- Can be read out via the "Serial number" parameter in the "Device information" submenu.

## 13.3

### Return

The measuring device must be returned if repairs or a factory calibration are required, or if the wrong measuring device has been ordered or delivered. According to legal regulations, Pepperl+Fuchs, as an ISO-certified company, is required to follow certain procedures when handling returned products that are in contact with medium.

To ensure swift, safe and professional device returns, please read the return procedures and conditions on the Pepperl+Fuchs website at ([www.pepperl-fuchs.com](http://www.pepperl-fuchs.com)).

## 13.4

### Disposal

Observe the following notes during disposal:

- Observe valid federal/national regulations.
- Ensure proper separation and reuse of the device components.



## 14 Accessories

### 14.1 Device-specific accessories

#### 14.1.1 Weather protection cover

Accessory	Description
Weather protection cover	<p>The diagram illustrates the weather protection cover for the LTC57 HART device. It shows a top-down view of the cover with dimensions: total width 298.5 (11.8) mm, inner width 255.1 (10) mm, and side height 55 mm. Below this, a front view shows the cover's profile with a height of 222 (8.74) mm. A cloud icon with rain drops is positioned above the cover. The bottom part of the diagram shows a cross-section of the cover's base, indicating a height of 155 (6.1) mm and a side angle of 65°. The cover is shown mounted on a device with a circular opening.</p> <p><b>a</b> 37.8 mm (1.49 in) <b>b</b> 54 mm (2.13 in)</p> <p>The weather protection cover can be ordered together with the device (product structure, feature "Accessory enclosed", option B "Weather protection cover"). Alternatively, it can be separately ordered as an accessory.</p>

Table 14.1



#### 14.1.2 Mounting bracket for the electronics housing

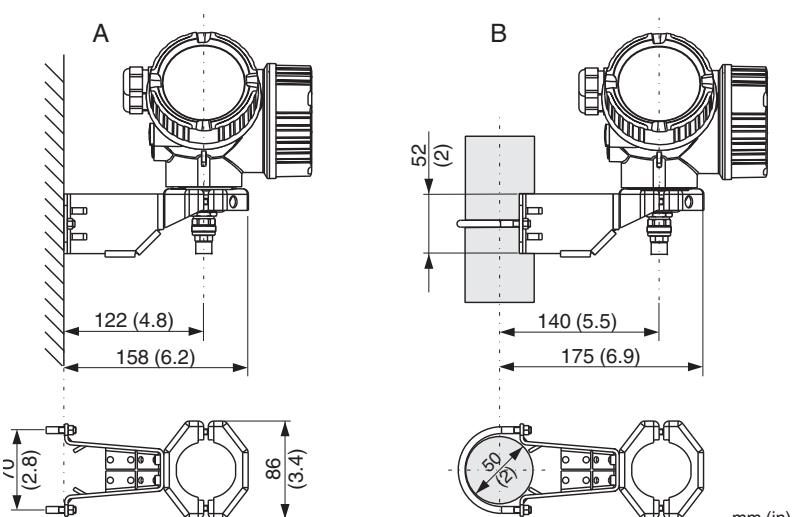
Accessory	Description
Mounting bracket for the electronics housing	 <p><b>A</b> Wall mounting <b>B</b> Pipe mounting</p> <p>For the "Sensor remote" device version, the mounting bracket is part of the delivery. If required, it can also be ordered as an accessory.</p>

Table 14.2



#### 14.1.3 Mounting kit, isolated

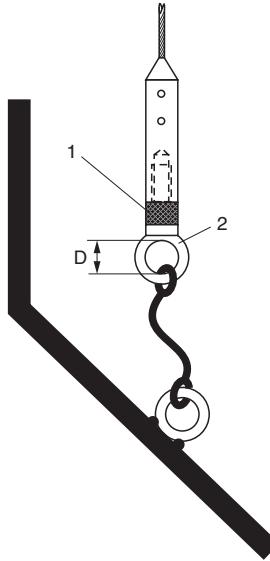
Accessory	Description
Mounting kit, isolated	 <p><b>1</b> Insulating sleeve <b>2</b> Eye-bolt</p> <p>For reliably insulated fixing of the probe.</p> <p>Maximum process temperature: 150 °C (300 °F)</p> <p>For rope probes 4 mm (1/6 in) or 6 mm (1/4 in) with PA &gt; steel:</p> <ul style="list-style-type: none"><li>• Eye-bolt M8 DIN 580</li><li>• Diameter D = 20 mm (0.8 in)</li></ul> <p>For rope probes 6 mm (1/4 in) or 8 mm (1/3 in) with PA &gt; steel:</p> <ul style="list-style-type: none"><li>• Eye-bolt M10 DIN 580</li><li>• Diameter D = 25 mm (1 in)</li></ul> <p>Due to the risk of electrostatic charge, the insulating sleeve is not suitable for use in hazardous areas. In these cases the fixing must be reliably grounded.</p> <p>The mounting kit can also be ordered directly with the device (see product structure, feature "Accessory enclosed", option G "Mounting kit, isolated, rope").</p>

Table 14.3



## 14.2

### Communication-specific accessories

Accessory	Description
HART Loop Converter KFD2-HLC-Ex1.D.**	Evaluates the dynamic HART variables and converts them to analog current signals or limit values.

Table 14.4

Accessory	Description
WirelessHART-Adapter WHA-ADP-F8B2-*P*-*	Connects field devices to a WirelessHART network. The WirelessHART adapter can be mounted directly at a HART device and is easily integrated into an existing HART network. It ensures safe data transmission and can be operated in parallel with other wireless networks.

Table 14.5



**Note!**

For details refer to data sheet on [www.pepperl-fuchs.com](http://www.pepperl-fuchs.com).

## 14.3

### Service-specific accessories

Accessory	Description
PACTware	PACTware is an operating software with graphical support (MS Windows) for intelligent transmitters with the communication protocols HART and PROFIBUS PA.

Table 14.6



**Note!**

For details refer to data sheet on [www.pepperl-fuchs.com](http://www.pepperl-fuchs.com).

## 14.4

### System components

Accessory	Description
KFD2-STC-Ex1	Transmitter power supply with power supply for safe isolation of 4 ... 20 mA current circuits. Provides bi-directional HART communication.

Table 14.7

Accessory	Description
KFD2-STC-1	Transmitter power supply for 2-wire sensors or transmitters exclusively for non-Ex areas. Provides bi-directional HART communication.

Table 14.8



**Note!**

For details refer to data sheet on [www.pepperl-fuchs.com](http://www.pepperl-fuchs.com).



## 15

# Operating menu

### 15.1

## Overview of the operating menu (for local display)

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Setup	
Device tag	page 112
Distance unit	page 112
Bin type	page 112
Empty calibration	
Full calibration	page 113
Level	page 114
Distance	page 114
Signal quality	page 115
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Confirm distance	page 118
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Record Map	page 118
Distance	page 118
Setup → Advanced setup	
Locking status	page 119
Access status display	page 120
Enter access code	page 120
Setup → Advanced setup → Level	
Medium type	page 121
Medium property	page 121
Process property	page 122
Advanced process conditions	page 123
Level unit	page 123
Blocking distance	page 124
Level correction	page 124

Setup → Advanced setup → Linearization	page 125
Linearization type	page 125
Unit after linearization	page 127
Free text	page 127
Maximum value	page 128
Diameter	page 128
Intermediate height	page 129
Table mode	page 130
Activate table	page 132
Setup → Advanced setup → Linearization → Edit table	page 133
Level (Manual)	page 133
Customer value	page 133
Setup → Advanced setup → Safety settings	page 134
Output echo lost	page 134
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Ramp at echo lost	page 135
Blocking distance	page 136
Setup → Advanced setup → SIL/WHG confirmation	page 137
Setup → Advanced setup → Deactivate SIL/WHG	page 137
Reset write protection	page 137
Code incorrect	page 137
Setup → Advanced setup → Probe settings	page 138
Probe grounded	page 138
Setup → Advanced setup → Probe settings → Probe length correction	page 140
Confirm probe length	page 140
Present probe length	page 140
Setup → Advanced setup → Current output 1 to 2	page 141
Assign current output	page 141
Current span	page 142
Fixed current	page 142
Damping	page 142
Failure mode	page 143
Failure current	page 143
Output current 1 to 2	page 143



Setup → Advanced setup → Switch output		page 144
	Switch output function	page 144
	Assign status	page 145
	Assign limit	page 145
	Assign diagnostic behavior	page 145
	Switch-on value	page 146
	Switch-on delay	page 147
	Switch-off value	page 147
	Switch-off delay	page 148
	Failure mode	page 148
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Setup → Advanced setup → Display		page 149
	Language	page 149
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	Decimal places 1 to 4	page 151
	Display interval	page 152
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	Header text	page 153
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	Backlight	page 154
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Setup → Advanced setup → Configuration backup display		page 155
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	Configuration management	page 156
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Setup → Advanced setup → Administration		page 158
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Setup → Advanced setup → Administration → Define access code		page 158
	Define access code	page 160
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Diagnostics	page 161
Actual diagnostics	page 161
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Diagnostics → Device information	page 165
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Diagnostics → Measured values	page 167
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Level linearized	page 167
Output current 1 to 2	page 167
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Diagnostics → Data logging	page 168
Assign channel 1 to 4	page 168
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Diagnostics → Simulation		page 171
	Assign measurement variable	page 171
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	Simulation current output	page 171
	Value current output	page 172
	Switch output simulation	page 172
	Switch status	page 172
	Simulation device alarm	page 172

Diagnostics → Device check		page 173
	Start device check	page 173
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	Level signal	page 173
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Expert		
See GP01000O (HART)		

## 15.2

## Overview of the operating menu (for operating tool)

Setup	page 112
Device tag	page 112
Distance unit	page 112
Bin type	page 112
Empty calibration	page 113
Full calibration	page 113
Level	page 114
Distance	page 114
Signal quality	page 115
Confirm distance	page 116
Present mapping	page 117
Mapping end point	page 117
Record map	page 117
Setup → Advanced setup	page 119
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Enter access code	page 120
Setup → Advanced setup → Level	page 121
Medium type	page 121
Medium property	page 121
Process property	page 122
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Level unit	page 123
Blocking distance	page 124
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Setup → Advanced setup → Linearization	page 125
Linearization type	page 125
Unit after linearization	page 127
Free text	page 127
Level linearized	page 127
Maximum value	page 128
Diameter	page 128
Intermediate height	page 129
Table mode	page 130
Table number	page 131
Level (Manual)	page 131
Level (Semi-automatic)	page 131
Customer value	page 131
Activate table	page 132
Setup → Advanced setup → Safety settings	page 134
Output echo lost	page 134
Value echo lost	page 134
Ramp at echo lost	page 135
Blocking distance	page 136
Setup → Advanced setup → SIL/WHG confirmation	page 137
Setup → Advanced setup → Deactivate SIL/WHG	page 137
Reset write protection	page 137
Code incorrect	page 137
Setup → Advanced setup → Probe settings	page 138
Probe grounded	page 138
Present probe length	page 138
Confirm probe length	page 139
Setup → Advanced setup → Current output 1 to 2	page 141
Assign current output	page 141
Current span	page 142
Fixed current	page 142
Damping	page 142
Failure mode	page 143
Failure current	page 143
Output current 1 to 2	page 143



Setup → Advanced setup → Switch output	page 144
Switch output function	page 144
Assign status	page 145
Assign limit	page 145
Assign diagnostic behavior	page 145
Switch-on value	page 146
Switch-on delay	page 147
Switch-off value	page 147
Switch-off delay	page 148
Failure mode	page 148
Switch status	page 148
Invert output signal	page 148
Setup → Advanced setup → Display	page 149
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Format display	page 150
Value 1 to 4 display	page 151
Decimal places 1 to 4	page 151
Display interval	page 152
Display damping	page 152
Header	page 152
Header text	page 153
Separator	page 153
Number format	page 153
Decimal places menu	page 153
Backlight	page 154
Contrast display	page 154
Setup → Advanced setup → Configuration backup display	page 155
Operating time	page 155
Last backup	page 155
Configuration management	page 156
Backup state	page 157
Comparison result	page 157
Setup → Advanced setup → Administration	page 158
Define access code	page 158
Device reset	page 159



Diagnostics		page 161
	Actual diagnostics	page 161
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	Timestamp	page 161
	Operating time from restart	page 162
	Operating time	page 162

Diagnostics → Diagnostic list		page 163
	Diagnostics 1 to 5	page 163
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Diagnostics → Device information		page 165
	Device tag	page 165
	Serial number	page 165
	Firmware version	page 165
	Device name	page 165
	Order code	page 165
	Extended order code 1 to 3	page 165
	Device revision	page 166
	Device ID	page 166
	Device type	page 166
	Manufacturer ID	page 166

Diagnostics → Measured values		page 167
	Distance	page 167
	Level linearized	page 167
	Output current 1 to 2	page 167
	Measured current 1	page 167
	Terminal voltage 1	page 167

Diagnostics → Data logging		page 168
	Assign channel 1 to 4	page 168
	Logging interval	page 169
	Clear logging data	page 169



Diagnostics → Simulation		page 171
	Assign measurement variable	page 171
	Value process variable	page 171
	Simulation current output	page 171
	Value current output	page 172
	Switch output simulation	page 172
	Switch status	page 172
	Simulation device alarm	page 172
Diagnostics → Device check		page 173
	Start device check	page 173
	Result device check	page 173
	Last check time	page 173
	Level signal	page 173
	Launch signal	page 174
Expert		
	See GP01000O (HART)	



## 15.3 Setup menu



### Note!

#### Symbols

- : Indicates the navigation path to the parameter via display and operating module.
- : Indicates the navigation to the parameter via operating tools (e. g. PACTware).
- : Marks parameters which can be locked by an access code. See page 59.

### Setup

#### Navigation

■ □ Setup

### Device tag

#### Blocking



#### Navigation

■ □ Setup → Device tag

#### Description

Enter tag for measuring point.

#### Factory settings

LTC5X

### Distance unit

#### Blocking



#### Navigation

■ □ Setup → Distance unit

#### Description

Select distance unit.

#### Selection

##### SI units

- m
- mm

##### US units

- ft
- in

#### Factory setting

m

### Bin type

#### Blocking



#### Navigation

■ □ Setup → Bin type

#### Prerequisite

**Medium type** (page 121) = **Solid**

#### Description

Specify bin type.

#### Selection

- Concrete
- Plastic/wood
- Metallic
- Aluminium

#### Factory setting

Metallic



## Empty calibration

<b>Blocking</b>	
<b>Navigation</b>	Setup → Empty calibr.
<b>Description</b>	Specify the distance E between the process connection and the minimum level (0 %).
<b>User entry</b>	Depending on the probe
<b>Factory setting</b>	Depending on the probe
<b>Additional information</b>	

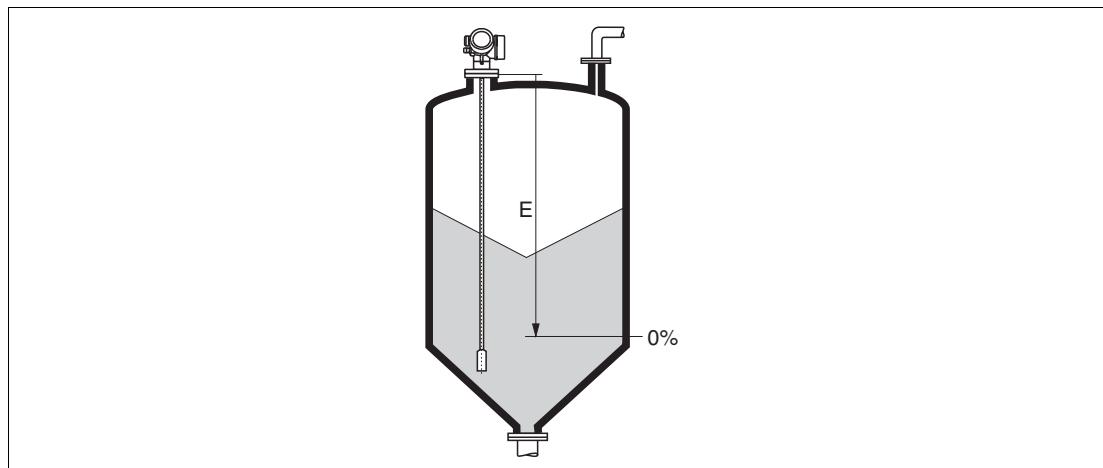


Figure 15.1     Empty calibration (E) for level measurements in bulk solids.

## Full calibration

<b>Blocking</b>	
<b>Navigation</b>	Setup → Full calibr.
<b>Description</b>	Specify the distance F between the minimum level (0 %) and the maximum level (100 %).
<b>User entry</b>	Depending on the probe
<b>Factory setting</b>	Depending on the probe
<b>Additional information</b>	

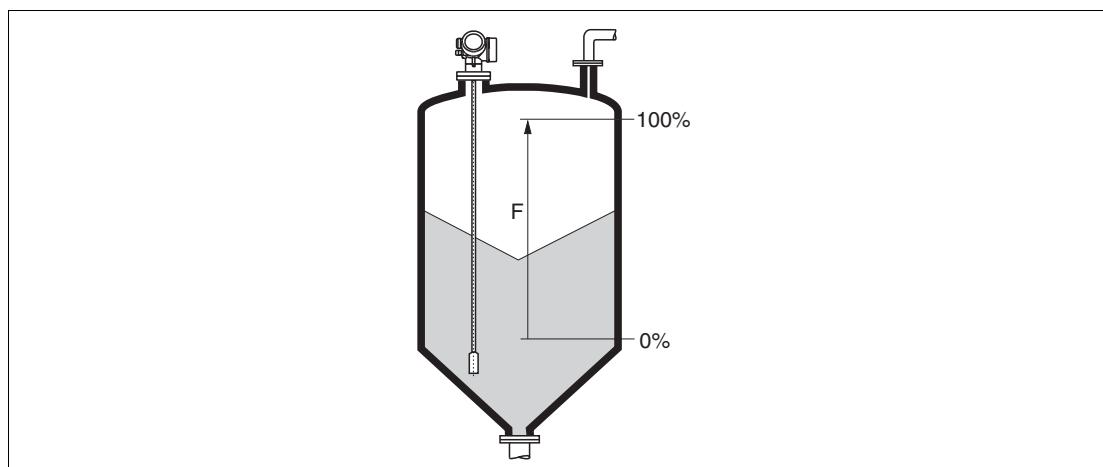


Figure 15.2     Full calibration (F) for level measurements in bulk solids



## Level

### Navigation

Setup → Level

### Description

Displays the measured level  $L_L$  (before linearization).

**Additional information** **Note:** The unit is defined in the **Level unit** parameter (page 123).

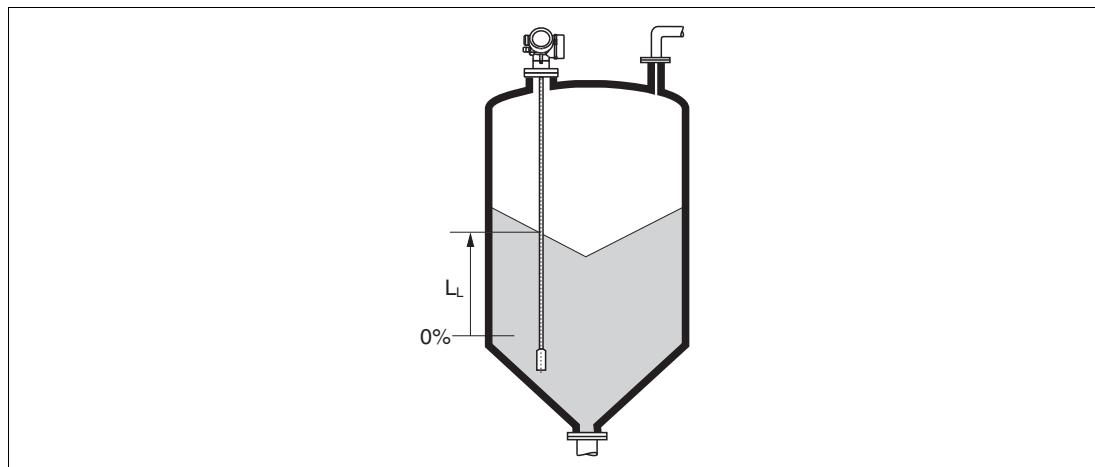


Figure 15.3 Level in case of bulk solid measurements

## Distance

### Navigation

Setup → Distance

### Description

Displays the measured distance  $D_L$  between the reference point (lower edge of the flange or threaded connection) and the level.

**Additional information** **Note:** The unit is defined in the **Level unit** parameter (page 112).

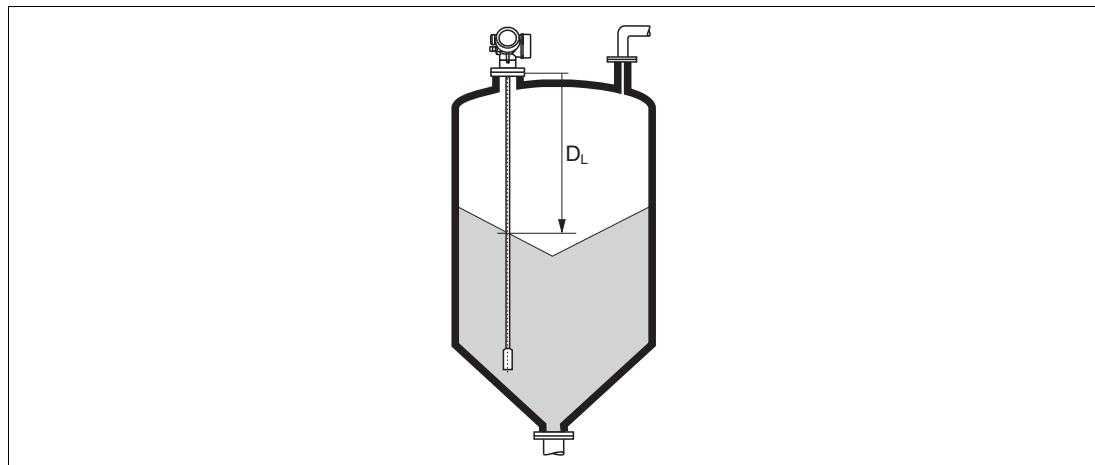


Figure 15.4 Distance for bulk solid measurements



## Signal quality

### Navigation

Setup → Signal quality

### Description

Displays the signal quality of the evaluated echo.

### Display

- **Strong**

The evaluated echo exceeds the threshold by at least 10 mV.

- **Medium**

The evaluated echo exceeds the threshold by at least 5 mV.

- **Weak**

The evaluated echo exceeds the threshold by less than 5 mV.

- **No signal**

The device does not find a usable echo.

### Additional information

The signal quality indicated in this parameter always refers to the currently evaluated echo: Either the level echo or the end-of-probe echo. To differentiate between these two, the quality of the end-of-probe echo is always displayed in brackets.

**Note:** In case of a lost echo (**Signal quality = No signal**) the device generates the following error message:

- F941, for **Output echo lost** (page 134) = **Alarm**.

- S941, if another option has been selected in **Output echo lost** (page 134).



## Confirm distance

<b>Blocking</b>	
<b>Navigation</b>	Setup → Confirm distance
<b>Description</b>	Specify, whether the measured distance matches the real distance. Depending on the selection the device automatically sets the range of mapping.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Manual map</li><li>• Distance OK</li><li>• Distance unknown</li><li>• Distance too small <sup>a</sup></li><li>• Distance too big <sup>b</sup></li><li>• Tank empty</li><li>• Delete map</li><li>•</li></ul>
<b>Factory setting</b>	Distance unknown
<b>Additional information</b>	Meaning of the options <ul style="list-style-type: none"><li>• <b>Manual map</b> To be selected if the range of mapping is to be defined manually in the <b>Mapping end point</b> parameter (page 117). In this case it is not necessary to confirm the distance.</li><li>• <b>Distance OK</b> To be selected if the measured distance matches the actual distance. The device performs a mapping.</li><li>• <b>Distance unknown</b> To be selected if the actual distance is unknown. A mapping can not be performed in this case.</li><li>• <b>Distance too small</b> To be selected if the measured distance is smaller than the actual distance. The device searches for the next echo and returns to the <b>Confirm distance</b> parameter. The distance is recalculated and displayed. The comparison must be repeated until the displayed distance matches the actual distance. After this, the recording of the map can be started by selecting <b>Distance OK</b>.</li><li>• <b>Distance too big</b> To be selected if the measured distance exceeds the actual distance. The device adjusts the signal evaluation and returns to the <b>Confirm distance</b> parameter. The distance is recalculated and displayed. The comparison must be repeated until the displayed distance matches the actual distance. After this, the recording of the map can be started by selecting <b>Distance OK</b>.</li><li>• <b>Tank empty</b> To be selected if the tank is completely empty. The device records a mapping covering the complete length of the probe.</li><li>• <b>Delete map</b> To be selected if the present mapping curve (if one exists) is to be deleted. The device returns to the <b>Confirm distance</b> parameter and a new mapping can be recorded.</li></ul>
<p><b>Note:</b> When operating via the display module, the measured distance is displayed together with this parameter for reference purposes. If the teaching procedure with the <b>Distance too small</b> option or the <b>Distance too big</b> option is quit before the distance has been confirmed, a map is <b>not</b> recorded and the teaching procedure is reset after 60 s.</p>	

<sup>a</sup> Visibility depends on order options or device settings  
<sup>b</sup> Visibility depends on order options or device settings



## Present mapping

<b>Navigation</b>	Setup → Present mapping
<b>Description</b>	Indicates up to which distance a mapping has already been recorded.
<b>Mapping end point</b>	
<b>Blocking</b>	
<b>Navigation</b>	Setup → Map. end point
<b>Prerequisite</b>	<b>Confirm distance</b> (page 116) = <b>Manual map</b> or <b>Distance too small</b>
<b>Description</b>	Specify new end of the mapping.
<b>User entry</b>	0 to 200000.0 m
<b>Factory setting</b>	0.1 m
<b>Additional information</b>	This parameter defines up to which distance the new mapping is to be recorded. The distance is measured from the reference point, i. e. from the lower edge of the mounting flange or the threaded connection. <b>Note:</b> For reference purposes the <b>Present mapping</b> parameter (page 117) is displayed together with this parameter. It states up to which distance a mapping has already been recorded.

## Record map

<b>Blocking</b>	
<b>Navigation</b>	Setup → Record map
<b>Prerequisite</b>	<b>Confirm distance</b> (page 116) = <b>Manual map</b> or <b>Distance too small</b>
<b>Description</b>	Start recording of the map.
<b>Selection</b>	<ul style="list-style-type: none"><li>• No</li><li>• Record map</li><li>• Delete map</li></ul>
<b>Factory setting</b>	No
<b>Additional information</b>	Meaning of the options <ul style="list-style-type: none"><li>• <b>No</b> The map is not recorded.</li><li>• <b>Record map</b> The map is recorded. After the recording is completed, the new measured distance and the new mapping range appear on the display. When operating via the local display, these values must be confirmed by pressing <input checked="" type="checkbox"/>.</li><li>• <b>Delete map</b> The mapping (if one exists) is deleted and the device displays the recalculated measured distance and the mapping range. When operating via the local display, these values must be confirmed by pressing <input checked="" type="checkbox"/>.</li></ul>



### 15.3.1 Mapping wizard



#### Note!

The **Mapping** wizard is only available when operating via the local display. When operating via an operating tool, all parameters concerning the mapping are located directly in the **Setup** menu (page 112).



#### Note!

In the **Mapping** wizard two parameters are displayed simultaneously on the display module at any one time. The upper parameter can be edited, whereas the lower parameter is displayed for reference purposes only.

### Mapping wizard

#### Navigation

Setup → Mapping

### Confirm distance

#### Blocking



#### Navigation

Setup → Mapping → Confirm distance

#### Description

**Confirm distance** (page 116)

### Mapping end point

#### Blocking



#### Navigation

Setup → Mapping → Map. end point

#### Description

**Mapping end point** (page 117)

### Record map

#### Blocking



#### Navigation

Setup → Mapping → Record map

#### Description

**Record map** (page 117)

### Distance

#### Navigation

Setup → Mapping → Distance

#### Description

**Distance** (page 114)



## 15.3.2 Advanced setup submenu

### Advanced setup

#### Navigation

Setup → Advanced setup

### Locking status

#### Navigation

Setup → Advanced setup → Locking status

#### Description

Indicates the write protection with the highest priority that is currently active.

#### User interface

- Hardware locked
- SIL locked
- WHG locked
- Temporarily locked

#### Additional information

Meaning and priorities of the types of write protection

- **Hardware locked (priority 1)**

The DIP switch for hardware locking is activated on the main electronics module. This locks write access to the parameters.

- **SIL locked (priority 2)**

The SIL mode is activated. Writing access to the relevant parameters is denied.

- **WHG locked (priority 3)**

The WHG mode is activated. Writing access to the relevant parameters is denied.

- **Temporarily locked (priority 4)**

Write access to the parameters is temporarily locked on account of internal processes in progress in the device (e. g. data upload/download, reset etc.).

The parameters can be modified as soon as the processes are complete.

**Note:** On the display module, the symbol appears in front of parameters that cannot be modified since they are write-protected.

### Access status tooling

#### Navigation

Setup → Advanced setup → Access stat.tool

#### Description

Indicates access authorization to parameters via operating tool.

#### User interface

- Operator
- Maintenance
- Service

#### Additional information

**Note:** The access authorization can be changed via the **Enter access code** parameter (page 120).

**Note:** If additional write protection is active, this restricts the current access authorization even further. The write protection status can be viewed via the **Locking status** parameter (page 119).



## Access status display

<b>Navigation</b>	Setup → Advanced setup → Access stat.disp
<b>Prerequisite</b>	The device has a local display.
<b>Description</b>	Indicates access authorization to parameters via local display.
<b>User interface</b>	<ul style="list-style-type: none"><li>• Operator</li><li>• Maintenance</li><li>• Service</li></ul>
<b>Additional information</b>	<p><b>Note:</b> If a  symbol appears in front of a parameter, the parameter cannot be changed via the local display with the current access authorization.</p> <p><b>Note:</b> The access authorization can be changed via the <b>Enter access code</b> parameter (page 120).</p> <p><b>Note:</b> If additional write protection is active, this restricts the current access authorization even further. The write protection status can be viewed via the <b>Locking status</b> parameter (page 119).</p>

## Enter access code

<b>Navigation</b>	Setup → Advanced setup → Ent. access code
<b>Description</b>	Enter access code to disable write protection of parameters.
<b>User entry</b>	0 to 9999
<b>Additional information</b>	<ul style="list-style-type: none"><li>• For local operation, the customer-specific access code, which has been defined in the <b>Define access code</b> parameter (page 158), has to be entered.</li><li>• If an incorrect access code is entered, the user retains his current access authorization.</li><li>• The write protection affects all parameters marked with the  symbol in this document. On the local display, the  symbol in front of a parameter indicates that the parameter is write-protected.</li><li>• If no key is pressed for 10 min, or the user switches from the navigation and editing mode back to the measured value display mode, the device automatically locks the write protected parameters after another 60 s.</li></ul>
	<p><b>Note:</b> Please contact your Pepperl+Fuchs Sales Center if you lose your access code.</p>



### 15.3.3 Level submenu

#### Level

##### Navigation

Setup → Advanced setup → Level

#### Medium type

##### Navigation

Setup → Advanced setup → Level → Medium type

##### Description

Specify type of medium.

##### User interface

- Liquid
- Solid

##### Factory setting

- LTC50, LTC51: **Liquid**
- LTC57: **Solid**

##### Additional information

The **Solid** option is only available for **Operating mode = Level**

**Note:** This parameter determines the value of several other parameters and strongly influences the complete signal evaluation. Therefore, it is strongly recommended **not to change** the factory setting.

#### Medium property

##### Blocking



##### Navigation

Setup → Advanced setup → Level → Medium property

##### Prerequisite

- **Operating mode = Level**
- **EOP level evaluation ≠ Fix DC**

##### Description

Specify relative dielectric constant  $\epsilon_r$  of the medium.

##### Selection

- Unknown
- DC 1.4 ... 1.6
- DC 1.6 ... 1.9
- DC 1.9 ... 2.5
- DC 2.5 ... 4
- DC 4 ... 7
- DC 7 ... 15
- DC > 15

##### Factory setting

Dependent on **Medium type** (page 121) and **Medium group**.

##### Additional information

Dependency on **Medium type** and **Medium group**

Medium type	Medium group	Medium property
Liquid	Water based (DC $\geq 4$ )	DC 4 ... 7
	Others	Unknown
Solid	–	Unknown

**Note:** Dielectric constants of important media commonly used in the industry are summarized in the technical information (TI).

**Note:** For **EOP level evaluation = Fix DC**, the exact dielectric constant has to be entered into the **DC value** parameter. Therefore, the **Medium property** parameter is not available in this case.



## Process property

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Level → Process property
<b>Description</b>	Specify typical rate of level change.
<b>Selection</b>	<b>For Medium type = Liquid</b> <ul style="list-style-type: none"><li>• Very fast &gt; 10 m (400 in)/min</li><li>• Fast &gt; 1 m (40 in)/min</li><li>• Standard &lt; 1 m (40 in)/min</li><li>• Medium &lt; 10 cm (4 in)/min</li><li>• Slow &lt; 1 cm (0.4 in)/min</li><li>• No filter/test</li></ul> <b>For Medium type = Solid</b> <ul style="list-style-type: none"><li>• Very fast &gt; 100 m (333 ft)/h</li><li>• Fast &gt; 10 m (33 ft)/h</li><li>• Standard &lt; 10 m (33 ft)/h</li><li>• Medium &lt; 1 m (3 ft)/h</li><li>• Slow &lt; 0.1 m (0.3 ft)/h</li><li>• No filter/test</li></ul>
<b>Factory setting</b>	Standard < 1 m (40 in)/min
<b>Additional information</b>	The device adjusts the signal evaluation filters and the damping of the output signal to the typical rate of level change defined in this parameter:

### For Medium type = Liquid

Process property	Step response time/s
Very fast > 10 m (400 in)/min	5
Fast > 1 m (40 in)/min	5
Standard < 1 m (40 in)/min	14
Medium < 10 cm (4 in)/min	39
Slow < 1 cm (0.4 in)/min	76
No filter/test	< 1

### For Medium type = Solid

Process property	Step response time/s
Very fast > 100 m (333 ft)/h	37
Fast > 10 m (33 ft)/h	37
Standard < 10 m (33 ft)/h	74
Medium < 1 m (3ft)/h	146
Slow < 0.1 m (0.3ft)/h	290
No filter/test	< 1



## Advanced process conditions

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Level → Adv. conditions
<b>Description</b>	Specify additional process conditions (if required).
<b>Selection</b>	<ul style="list-style-type: none"><li>• None</li><li>• Oil/water condensate <sup>a</sup></li><li>• Probe near tank bottom <sup>b</sup></li><li>• Build up</li><li>• Foam (&gt; 5 cm/0.16 ft) <sup>c</sup></li></ul>
<b>Factory setting</b>	None
<b>Additional information</b>	<p>Meaning of the options</p> <ul style="list-style-type: none"><li>• <b>Oil/water condensate</b> Makes sure that in the case of two-phase media always the total level is detected (example: oil/condensate application).</li><li>• <b>Probe near tank bottom</b> Improves the empty detection, especially if the probe is mounted close to the tank bottom.</li><li>• <b>Build up</b> Increases <b>EOP range upper area</b> in order to ensure a safe empty-detection even if the end-of-probe signal has shifted due to build-up. Enables a safe empty-detection even if the end-of-probe signal has shifted due to build-up.</li><li>• <b>Foam (&gt; 5cm/0.16 ft)</b> Optimizes the signal evaluation in applications with foam formation.</li></ul>

<sup>a</sup> only for **Medium type = Liquid**

<sup>b</sup> only for **Medium type = Liquid**

<sup>c</sup> only for **Medium type = Liquid**

## Level unit

<b>Blocking</b>					
<b>Navigation</b>	Setup → Advanced setup → Level → Level unit				
<b>Description</b>	Select level unit.				
<b>Selection</b>	<table><tr><td><b>SI units</b></td><td><b>US units</b></td></tr><tr><td><ul style="list-style-type: none"><li>• %</li><li>• m</li><li>• mm</li></ul></td><td><ul style="list-style-type: none"><li>• ft</li><li>• in</li></ul></td></tr></table>	<b>SI units</b>	<b>US units</b>	<ul style="list-style-type: none"><li>• %</li><li>• m</li><li>• mm</li></ul>	<ul style="list-style-type: none"><li>• ft</li><li>• in</li></ul>
<b>SI units</b>	<b>US units</b>				
<ul style="list-style-type: none"><li>• %</li><li>• m</li><li>• mm</li></ul>	<ul style="list-style-type: none"><li>• ft</li><li>• in</li></ul>				
<b>Factory setting</b>	%				
<b>Additional information</b>	<p>The level unit may differ from the distance unit defined in the <b>Distance unit</b> parameter (page 112):</p> <ul style="list-style-type: none"><li>• The unit defined in the <b>Distance unit</b> parameter is used for the basic calibration (<b>Empty calibration</b> (page 113) and <b>Full calibration</b> (page 113)).</li><li>• The unit defined in the <b>Level unit</b> parameter is used to display the (unlinearized) level.</li></ul>				



## Blocking distance

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Level → Blocking dist.
<b>Description</b>	Specify upper blocking distance UB.
<b>User entry</b>	0 to 200 m
<b>Factory setting</b>	<ul style="list-style-type: none"><li>For coax probes: 0 mm (0 in)</li><li>For rod and rope probes up to 8 m (26 ft): 200 mm (8 in)</li><li>For rod and rope probes above 8 m (26 ft): 0.025 x length of probe</li></ul>
<b>Additional information</b>	No echoes are evaluated within the blocking distance UB. Therefore, UB can be used to suppress interference echos within the upper end of the probe.

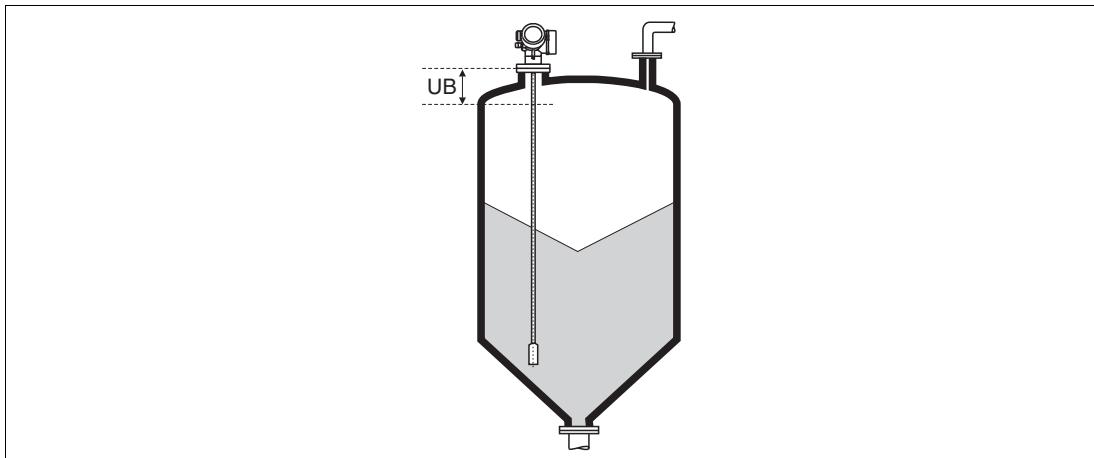


Figure 15.5 Blocking distance (UB) for bulk solid measurements

## Level correction

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Level → Level correction
<b>Description</b>	Specify level correction (if required).
<b>User entry</b>	-200000.0 to 200000.0 %
<b>Factory setting</b>	0.0 %
<b>Additional information</b>	The value specified in this parameter is added to the measured level (before linearization).



## 15.3.4 Linearization submenu

### Linearization

#### Navigation

Setup → Advanced setup → Linearization

### Linearization type

#### Blocking



#### Navigation

Setup → Advanced setup → Linearization → Lineariz. type

#### Description

Select linearization type.

#### Selection

- None
- Linear
- Table
- Pyramid bottom
- Conical bottom
- Angled bottom
- Horizontal cylinder
- Sphere

#### Factory setting

None

#### Additional information

Meaning of the options

- **None**

The level is transmitted in the level unit without linearization.

- **Linear**

The output value (volume/weight) is directly proportional to the level L. This is valid, for example, for vertical cylinders. The following additional parameters have to be specified:

– **Unit after linearization** (page 127)

– **Maximum value** (page 128): Maximum volume or weight

- **Table**

The relationship between the measured level L and the output value (volume/weight) is given by a linearization table consisting of up to 32 pairs of values "level - volume" or "level - weight", respectively. The following additional parameters have to be specified:

– **Unit after linearization** (page 127)

– **Table mode** (page 130)

– For each table point: **Level** (page 131)

– For each table point: **Customer value** (page 131)

– **Activate table** (page 132)

- **Pyramid bottom**

The output value corresponds to the volume or weight in a silo with pyramid bottom. The following additional parameters have to be specified:

– **Unit after linearization** (page 127)

– **Maximum value** (page 128): Maximum volume or weight

– **Intermediate height** (page 129): The height of the pyramid

- **Conical bottom**

The output value corresponds to the volume or weight in a tank with conical bottom. The following additional parameters have to be specified:

– **Unit after linearization** (page 127)

– **Maximum value** (page 128): Maximum volume or weight

– **Intermediate height** (page 129): The height of the conical part of the tank



- **Angled bottom**

The output value corresponds to the volume or weight in a silo with an angled bottom. The following additional parameters have to be specified:

- **Unit after linearization** (page 127)
- **Maximum value** (page 128): Maximum volume or weight
- **Intermediate height** (page 129): Height of the angled bottom

- **Horizontal cylinder**

The output value corresponds to the volume or weight in a horizontal cylinder.

The following additional parameters have to be specified:

- **Unit after linearization** (page 127)
- **Maximum value** (page 128): Maximum volume or weight
- **Diameter** (page 128)

- **Sphere**

The output value corresponds to the volume or weight in a spherical tank. The following additional parameters have to be specified:

- **Unit after linearization** (page 127)
- **Maximum value** (page 128): Maximum volume or weight
- **Diameter** (page 128)

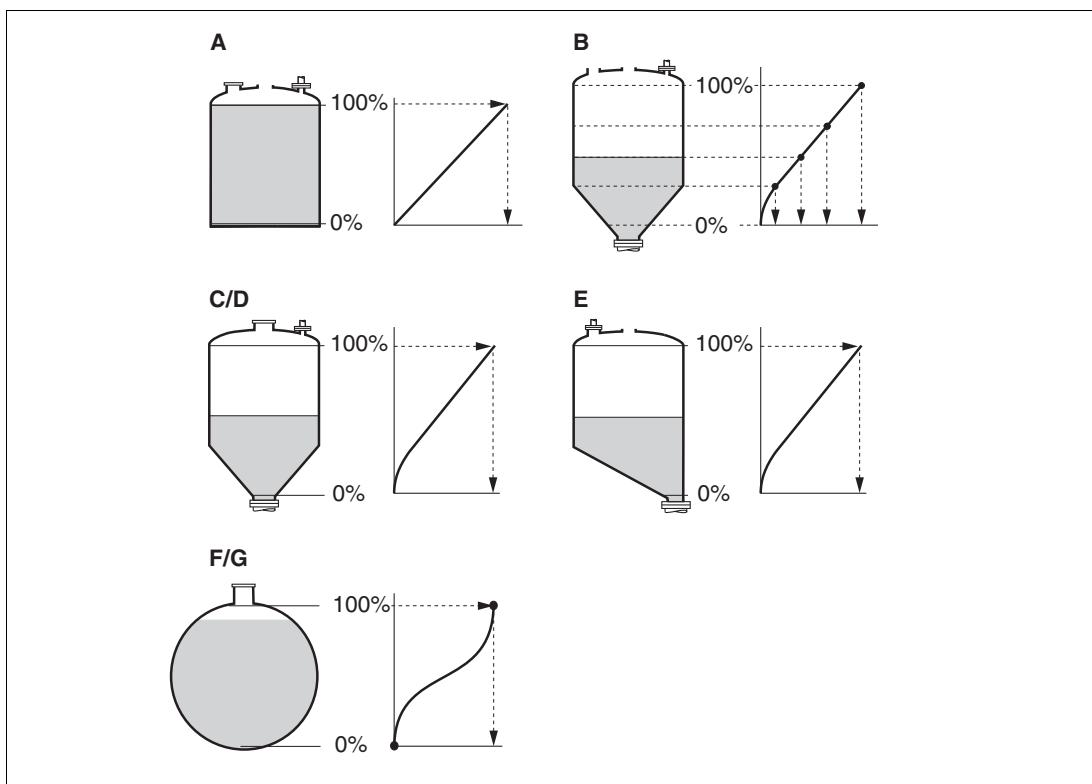


Figure 15.6 Linearization types

- A** None
- B** Table
- C** Pyramid bottom
- D** Conical bottom
- E** Angled bottom
- F** Sphere
- G** Horizontal cylinder

## Unit after linearization

<b>Blocking</b>			
<b>Navigation</b>		Setup → Advanced setup → Linearization → Unit lineariz.	
<b>Prerequisite</b>		<b>Linearization type</b> (page 125) ≠ <b>None</b>	
<b>Description</b>		Select unit of the linearized value.	
<b>Selection</b>	<b>SI units</b> <ul style="list-style-type: none"> <li>• STon</li> <li>• t</li> <li>• kg</li> <li>• cm<sup>3</sup></li> <li>• dm<sup>3</sup></li> <li>• m<sup>3</sup></li> <li>• hl</li> <li>• l</li> <li>• %</li> </ul> <b>Custom-specific units</b> Free text	<b>US units</b> <ul style="list-style-type: none"> <li>• lb</li> <li>• UsGal</li> <li>• ft<sup>3</sup></li> </ul>	<b>Imperial units</b> impGal
<b>Factory setting</b>	%		
<b>Additional information</b>	The selected unit is only used to be indicated on the display. The measured value is <b>not</b> transformed according to the selected unit. <b>Note:</b> It is also possible to configure a distance-to-distance linearization, i. e. a transformation from the level unit to a different distance unit. To do so, select the <b>Linear</b> linearization mode. In order to define the new level unit, select the <b>Free text</b> option in the <b>Unit after linearization</b> parameter and enter the required unit into the <b>Free text</b> parameter (page 127).		

## Free text

<b>Blocking</b>			
<b>Navigation</b>		Setup → Advanced setup → Linearization → Free text	
<b>Prerequisite</b>		<b>Unit after linearization</b> (page 127) = <b>Free text</b>	
<b>Description</b>		Enter unit symbol.	
<b>User entry</b>		Up to 32 alphanumerical characters (letters, numbers, special characters)	
<b>Factory setting</b>	Free text		

## Level linearized

<b>Navigation</b>		Setup → Advanced setup → Linearization → Level linearized
<b>Description</b>		Displays linearized level.
<b>Additional information</b>	<b>Note:</b> The unit is defined by the <b>Unit after linearization</b> parameter (page 127).	

## Maximum value

<b>Blocking</b>	
<b>Navigation</b>	  Setup → Advanced setup → Linearization → Maximum value
<b>Prerequisite</b>	<b>Linearization type</b> (page 125) has one of the following values: <ul style="list-style-type: none"><li>• Linear</li><li>• Pyramid bottom</li><li>• Conical bottom</li><li>• Angled bottom</li><li>• Horizontal cylinder</li><li>• Sphere</li></ul>
<b>Description</b>	Specify the maximum content of the vessel (100 %) measured in the units after linearization.
<b>User entry</b>	-50000.0 to 50000.0 %
<b>Factory setting</b>	100.0 %

## Diameter

<b>Blocking</b>	
<b>Navigation</b>	  Setup → Advanced setup → Linearization → Diameter
<b>Prerequisite</b>	<b>Linearization type</b> (page 125) has one of the following values: <ul style="list-style-type: none"><li>• Horizontal cylinder</li><li>• Sphere</li></ul>
<b>Description</b>	Specify tank diameter.
<b>User entry</b>	0 to 9999.999 m
<b>Factory setting</b>	2 m

**Additional information** The unit is defined in the **Distance unit** parameter (page 112).



## Intermediate height

**Blocking****Navigation**

Setup → Advanced setup → Linearization → Intermed. height

**Prerequisite**

**Linearization type** (page 125) has one of the following values:

- Pyramid bottom
- Conical bottom
- Angled bottom

**Description**

Specify intermediate height H.

**User entry**

0 to 200 m

**Factory setting**

0 m

**Additional information** The unit is defined in the **Distance unit** parameter (page 112).

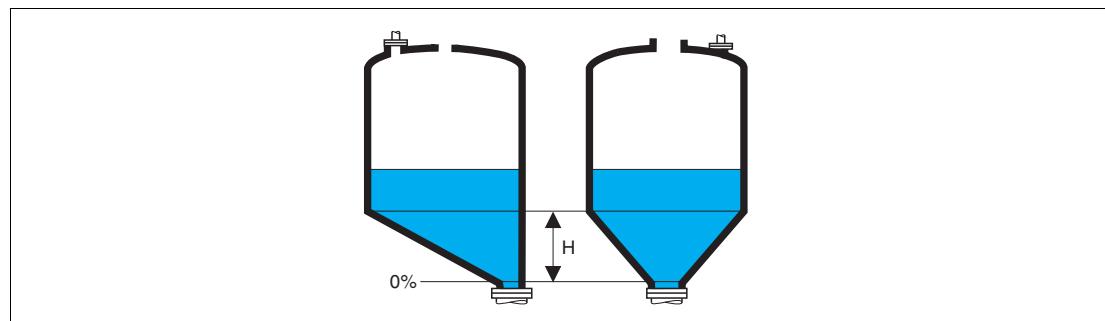


Figure 15.7

**H**      Intermediate height



## Table mode

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Linearization → Table mode
<b>Prerequisite</b>	<b>Linearization type</b> (page 125) = <b>Table</b>
<b>Description</b>	Select editing mode of the linearization table.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Manual</li><li>• Semi-automatic <sup>a</sup></li><li>• Clear table</li><li>• Sort table</li></ul>
<b>Factory setting</b>	Manual
<b>Additional information</b>	<p>Meaning of the options</p> <ul style="list-style-type: none"><li>• <b>Manual</b> The level and the associated linearized value are entered manually for each linearization point.</li><li>• <b>Semi-automatic</b> The level is measured by the device for each linearization point. The associated linearized value is entered manually.</li><li>• <b>Clear table</b> Deletes the existing linearization table.</li><li>• <b>Sort table</b> Rearranges the linearization points into an ascending order.</li></ul> <p>Conditions the linearization table must meet:</p> <ul style="list-style-type: none"><li>• The table may consist of up to 32 pairs of values "Level - Linearized Value".</li><li>• The table must be monotonic (monotonically increasing or decreasing).</li><li>• The first linearization point must refer to the minimum level.</li><li>• The last linearization point must refer to the maximum level.</li></ul> <p>How to enter the table</p> <ul style="list-style-type: none"><li>• Via PACTware The table points can be entered via the <b>Table number</b> (page 131), <b>Level</b> (page 131) and <b>Customer value</b> (page 131) parameters. As an alternative, the graphic table editor may be used: Device Operation → Device Functions → Additional Functions → Linearization (Online/Offline)</li><li>• Via local display Select the <b>Edit table</b> (page 133) submenu to call up the graphic table editor. The table is displayed and can be edited line by line.</li></ul> <p><b>Note:</b> The factory setting for the level unit is "%". If you want to enter the linearization table in physical units, you must select the appropriate unit in the <b>Level unit</b> parameter (page 123) beforehand.</p> <p><b>Note:</b> If a decreasing table is entered, the values for 20 mA and 4 mA of the current output are interchanged. That means: 20 mA refers to the lowest level, whereas 4 mA refers to the highest level. If required, the current output can be inverted in the <b>Measuring mode</b> parameter.</p>

<sup>a</sup> Visibility depends on order options or device settings



## Table number

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Linearization → Table number
<b>Prerequisite</b>	<b>Linearization type</b> (page 125) = <b>Table</b>
<b>Description</b>	Select table point you are going to enter or change.
<b>User entry</b>	1 to 32
<b>Factory setting</b>	1

## Level (Manual)

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Linearization → Level
<b>Prerequisite</b>	<ul style="list-style-type: none"><li><b>Linearization type</b> (page 125) = <b>Table</b></li><li><b>Table mode</b> (page 130) = <b>Manual</b></li></ul>
<b>Description</b>	Enter level value of the table point (value before linearization).
<b>User entry</b>	Signed floating-point number
<b>Factory setting</b>	0 %

## Level (Semi-automatic)

<b>Navigation</b>	Setup → Advanced setup → Linearization → Level
<b>Prerequisite</b>	<ul style="list-style-type: none"><li><b>Linearization type</b> (page 125) = <b>Table</b></li><li><b>Table mode</b> (page 130) = <b>Semi-automatic</b></li></ul>
<b>Description</b>	Displays measured level (value before linearization). This value is transmitted to the table.

## Customer value

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Linearization → Customer value
<b>Prerequisite</b>	<b>Linearization type</b> (page 125) = <b>Table</b>
<b>Description</b>	Enter linearized value for the table point.
<b>User entry</b>	Signed floating-point number
<b>Factory setting</b>	0 %



## Activate table

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Linearization → Activate table
<b>Prerequisite</b>	<b>Linearization type</b> (page 125) = <b>Table</b>
<b>Description</b>	Activate (enable) or deactivate (disable) the linearization table.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Disable</li><li>• Enable</li></ul>
<b>Factory setting</b>	Disable
<b>Additional information</b>	<p>Meaning of the options</p> <ul style="list-style-type: none"><li>• <b>Disable</b> The measured level is not linearized. If <b>Linearization type</b> (page 125) = <b>Table</b> at the same time, the device issues error message F435.</li><li>• <b>Enable</b> The measured level is linearized according to the table.</li></ul> <p><b>Note:</b> When editing the table, the <b>Activate table</b> parameter is automatically reset to <b>Disable</b> and must be reset to <b>Enable</b> after the table has been entered.</p>



### 15.3.5 Edit table submenu

#### Edit table

**Note:** The **Edit table** submenu is only available when operating via the local display. When operating via an operating tool, all parameters concerning the table editor are located directly in the **Linearization** submenu (page 125).

##### Navigation

Setup → Advanced setup → Linearization → Edit table

#### Level

##### Blocking



##### Navigation

Setup → Advanced setup → Linearization → Edit table → Level

##### Description

**Level** (page 131)

#### Customer value

##### Blocking



##### Navigation

Setup → Advanced setup → Linearization → Edit table → Customer value

##### Description

**Customer value** (page 131)



## 15.3.6 Safety settings submenu

### Safety settings

#### Navigation

Setup → Advanced setup → Safety sett.

### Output echo lost

#### Blocking



#### Navigation

Setup → Advanced setup → Safety sett. → Output echo lost

#### Description

Define the behavior of the output signal in case of a lost echo.

#### Selection

- Last valid value
- Ramp at echo lost
- Value echo lost
- Alarm

#### Factory setting

Last valid value

#### Additional information

Meaning of the options

- **Last valid value**  
The last valid value is kept in the case of a lost echo.
- **Ramp at echo lost**  
In the case of a lost echo the output value is continuously shifted towards 0 % or 100 %. The slope of the ramp is defined in the **Ramp at echo lost** parameter (page 135).
- **Value echo lost**  
In the case of a lost echo the output assumes the value defined in the **Value echo lost** parameter (page 134).
- **Alarm**  
In the case of a lost echo the device generates an alarm; see the **Failure mode** parameter (page 148).

### Value echo lost

#### Blocking



#### Navigation

Setup → Advanced setup → Safety sett. → Value echo lost

#### Prerequisite

**Output echo lost** (page 134) = **Value echo lost**

#### Description

Define output value in case of a lost echo.

#### User entry

0 to 200000.0 %

#### Factory setting

0.0 %

#### Additional information

Use the unit which has been defined for the measured value output:

- without linearization: **Level unit** (page 123)
- with linearization: **Unit after linearization** (page 127)



## Ramp at echo lost

**Blocking****Navigation**

Setup → Advanced setup → Safety sett. → Ramp echo lost

**Prerequisite**

**Output echo lost** (page 134) = **Ramp at echo lost**

**Description**

Define the slope of the ramp in the case of a lost echo.

**User entry**

Signed floating-point number

**Factory setting**

0.0 %/min

**Additional information**

- The unit for the slope of the ramp is "percentage of the measuring range per minute" (%/min).
- For a negative slope of the ramp: The measured value is continuously decreased until it reaches 0 %.
- For a positive slope of ramp: The measured value is continuously increased until it reaches 100 %.

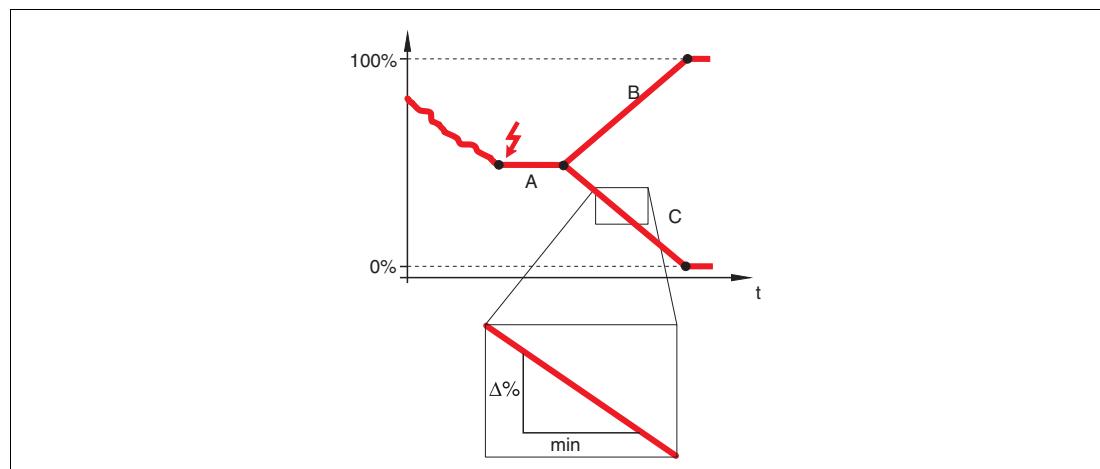


Figure 15.8

- A** Delay time echo lost  
**B** Ramp at echo lost (positive value)  
**C** Ramp at echo lost (negative value)



## Blocking distance

**Blocking****Navigation**

Setup → Advanced setup → Safety sett. → Blocking dist.

**Description**

Specify upper blocking distance UB.

**User entry**

0 to 200 m

**Factory setting**

- For coax probes: 0 mm (0 in)
- For rod and rope probes up to 8 m (26 ft): 200 mm (8 in)
- For rod and rope probes above 8 m (26 ft): 0.025 x length of probe

**Additional information** No echoes are evaluated within the blocking distance UB. Therefore, UB can be used to: Suppress interference echoes within the upper end of the probe.

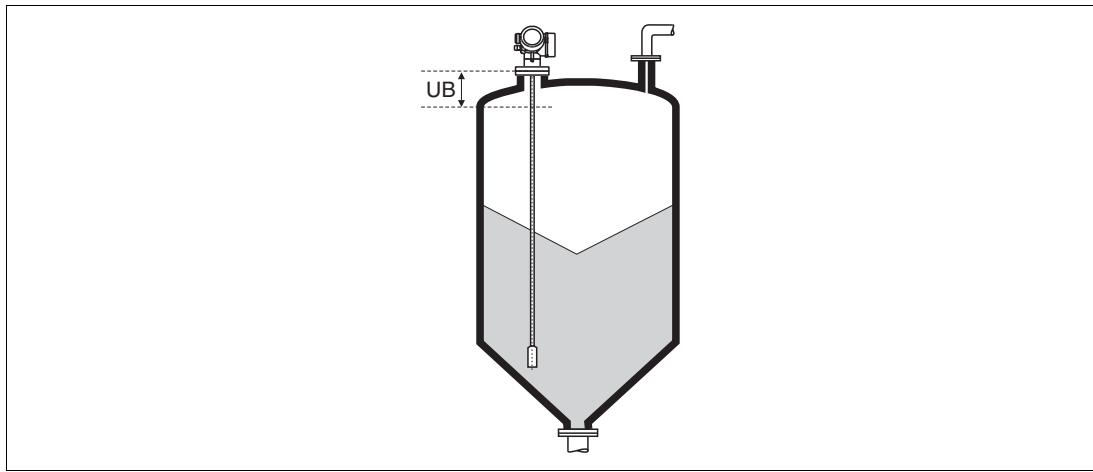


Figure 15.9 Blocking distance (UB) for bulk solid measurements



### 15.3.7 SIL/WHG confirmation wizard

#### SIL/WHG confirmation

**Note:** Wizard **SIL/WHG confirmation** wizard is only available for devices with SIL or WHG approval (Feature: "Additional approval", option A: "SIL" or C: "WHG overfill prevention") which are currently **not** in the SIL- or WHG-locked state. The **SIL/WHG confirmation** wizard is required to lock the device according to SIL or WHG. For details refer to the "Functional Safety Manual" of the respective device, which describes the locking procedure and the parameters of the sequence.

##### Navigation

Setup → Advanced setup → SIL/WHG confirm.

### 15.3.8 Deactivate SIL/WHG wizard

#### Deactivate SIL/WHG

##### Navigation

Setup → Advanced setup → Deactiv. SIL/WHG

#### Reset write protection

##### Blocking



##### Navigation

Setup → Advanced setup → Deactiv. SIL/WHG → Res. write prot.

##### Description

Enter unlocking code.

##### User entry

0 to 65535

##### Factory setting

0

#### Code incorrect

##### Blocking



##### Navigation

Setup → Advanced setup → Deactiv. SIL/WHG → Code incorrect

##### Description

Indicates that a wrong unlocking code has been entered. Select procedure.

##### Selection

- Reenter code
- Abort sequence

##### Factory setting

Reenter code



## 15.3.9 Probe settings submenu

### Probe settings

The **Probe settings** submenu helps to ensure that the end of probe signal within the envelope curve is correctly assigned by the evaluation algorithm. The assignment is correct if the length of probe indicated by the device matches the actual length of the probe. The automatic probe length correction can only be performed if the probe is installed in the vessel and is completely uncovered (no medium). For partially filled vessels and if the probe length is known, select **Confirm probe length** (page 139) = **Manual input** in order to enter the value manually.

**Note:** If a mapping (interference echo suppression) has been recorded after shortening the probe, it is no longer possible to perform an automatic probe length correction. In this case there are two options:

- Delete the map using the **Record map** parameter (page 117) before performing the automatic probe length correction. After the probe length correction, a new map can be recorded using the **Record map** parameter (page 117).
- Alternative: Select **Confirm probe length** (page 139) = **Manual input** and enter the probe length manually into the **Present probe length** parameter (page 138).

**Note:** An automatic probe length correction is only possible after the correct option has been selected in the **Probe grounded** parameter (page 138).

#### Navigation

Setup → Advanced setup → Probe settings

### Probe grounded

#### Blocking



#### Navigation

Setup → Advanced setup → Probe settings → Probe grounded

#### Prerequisite

#### Operating mode = Level

#### Description

Specify whether the probe is grounded.

#### Selection

- No
- Yes

#### Factory setting

No

### Present probe length

#### Blocking



#### Navigation

Setup → Advanced setup → Probe settings → Pres. length

#### Description

- In most cases:  
Displays the length of the probe according to the currently measured end-of-probe signal.
- For **Confirm probe length** (page 139) = **Manual input**:  
Enter actual length of probe.

#### User entry

0 to 200 m

#### Factory setting

4 m

## Confirm probe length

<b>Blocking</b>	
<b>Navigation</b>	 Setup → Advanced setup → Probe settings → Confirm length
<b>Description</b>	Select, whether the value displayed in the <b>Present probe length</b> parameter (page 138) matches the actual length of the probe. Based on this input, the device performs a probe length correction.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Probe length OK</li><li>• Probe length too small</li><li>• Probe length too big</li><li>• Probe covered</li><li>• Manual input</li><li>• Probe length unknown</li></ul>
<b>Factory setting</b>	Probe length OK
<b>Additional information</b>	<p>Meaning of the options</p> <ul style="list-style-type: none"><li>• <b>Probe length OK</b> To be selected if the indicated length is correct. An adjustment is not required. The device quits the sequence.</li><li>• <b>Probe length too small</b> To be selected if the displayed length is smaller than the actual length of the probe. A different end of probe signal is allocated and the newly calculated length is displayed in the <b>Present probe length</b> parameter (page 138). This procedure has to be repeated until the displayed value matches the actual length of the probe.</li><li>• <b>Probe length too big</b> To be selected if the displayed length is bigger than the actual length of the probe. A different end of probe signal is allocated and the newly calculated length is indicated in the <b>Present probe length</b> parameter (page 138). This procedure has to be repeated until the displayed value matches the actual length of the probe.</li><li>• <b>Probe covered</b> To be selected if the probe is (partially or completely) covered. A probe length correction is impossible in this case. The device quits the sequence.</li><li>• <b>Manual input</b> To be selected if no automatic probe length correction is to be performed. Instead, the actual length of the probe must be entered manually into the <b>Present probe length</b> parameter (page 138)<sup>a</sup>.</li><li>• <b>Probe length unknown</b> To be selected if the actual length of the probe is unknown. A probe length correction is impossible in this case. The device quits the sequence.</li></ul>

<sup>a</sup> When operated via PACTware, the **Manual input** option needs not to be selected explicitly. In PACTware the length of the probe can always be edited.



## 15.3.10 Probe length correction wizard

### Probe length correction

**Note:** The **Probe length correction** wizard is only available when operating via the local display. When operating via an operating tool, all parameters concerning the probe length correction are located directly in the **Probe settings** submenu (page 138).

#### Navigation

Setup → Advanced setup → Probe settings → Prob.length corr

### Confirm probe length

#### Blocking



#### Navigation

Setup → Advanced setup → Probe settings → Prob.length corr → Confirm length

#### Description

**Confirm probe length** (page 139)

### Present probe length

#### Blocking



#### Navigation

Setup → Advanced setup → Probe settings → Prob.length corr → Pres. length

#### Description

**Present probe length** (page 138)



### 15.3.11 Current output 1 to 2 submenu

#### Current output 1 to 2

**Note:** The **Current output 2** submenu (page 141) is only available for devices with two current outputs.

##### Navigation

Setup → Advanced setup → Curr.output 1 to 2

#### Assign current output 1 to 2

##### Blocking



##### Navigation

Setup → Advanced setup → Curr.output 1 to 2 → Assign curr.

##### Description

Select process variable for current output.

##### Selection

- Level linearized
- Distance
- Electronic temp.
- Relat.echo ampl.
- Analog out. AD 1
- Analog out. AD 2

##### Factory setting

For level measurements

- Current output 1: Level linearized
- Current output 2<sup>a</sup>: Relat.echo ampl.

##### Additional information

Definition of the current range for the process variables

Process variable	4 mA value	20 mA value
Level linearized	0 % <sup>b</sup> or the associated linearized value	100 % <sup>c</sup> or the associated linearized value
Distance	0 (i. e. level is at the reference point)	<b>Empty calibration</b> (page 113) (i. e. level is at 0 %)
Electronic temperature	-50 °C (-58 °F)	100 °C (212 °F)
Relative echo amplitude	0 mV	2000 mV
Analog output adv. diagnostics 1/2	depending on the parametrization of the advanced diagnostics	

<sup>a</sup> only for devices with two current outputs

<sup>b</sup> The 0 % level is defined by **Empty calibration** parameter (page 113).

<sup>c</sup> The 100 % level is defined by **Full calibration** parameter (page 113).



## Current span

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Curr.output 1 to 2 → Current span
<b>Description</b>	Select current range for process variable and alarm signal.
<b>Selection</b>	<ul style="list-style-type: none"><li>• 4...20 mA</li><li>• 4...20 mA NAMUR</li><li>• 4...20 mA US</li><li>• Fixed current</li></ul>
<b>Factory setting</b>	4...20 mA NAMUR
<b>Additional information</b>	Meaning of the options

Option	Current range for process variable	Lower alarm signal level	Upper alarm signal level
4...20 mA	4 to 20.5 mA	< 3.6 mA	> 21.95 mA
4...20 mA NAMUR	3.8 to 20.5 mA	< 3.6 mA	> 21.95 mA
4...20 mA US	3.9 to 20.8 mA	< 3.6 mA	> 21.95 mA
Fixed current	Constant current, defined in the <b>Fixed current</b> parameter (page 142).		

**Note:**

- In the case of an error, the output current assumes the value defined in the **Failure mode** parameter (page 143).
- If the measured value is out of the measuring range, diagnostic message **Current output** is issued.

## Fixed current

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Curr.output 1 to 2 → Fixed current
<b>Prerequisite</b>	<b>Current span</b> (page 142) = <b>Fixed current</b>
<b>Description</b>	Define constant value of the current.
<b>User entry</b>	4 to 22.5 mA
<b>Factory setting</b>	4 mA

## Damping

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Curr.output 1 to 2 → Damping
<b>Description</b>	Define time constant $\tau$ for the damping of the output current.
<b>User entry</b>	0.0 to 999.9 s
<b>Factory setting</b>	0.0 s
<b>Additional information</b>	Fluctuations of the measured value affect the output current with an exponential delay, the time constant $\tau$ of which is defined in this parameter. With a small time constant the output reacts immediately to changes of the measured value. With a big time constant the reaction of the output is more delayed. For $\tau = 0$ (factory setting) there is no damping.

## Failure mode

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Curr.output 1 to 2 → Failure mode
<b>Prerequisite</b>	<b>Current span</b> (page 142) ≠ <b>Fixed current</b>
<b>Description</b>	Select behavior of the output current in case of an error.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Min.</li><li>• Max.</li><li>• Last valid value</li><li>• Actual value</li><li>• Defined value</li></ul>
<b>Factory setting</b>	Max.
<b>Additional information</b>	<p>Meaning of the options</p> <ul style="list-style-type: none"><li>• <b>Min.</b> The current output adopts the value of the lower alarm level according to the <b>Current span</b> parameter (page 142).</li><li>• <b>Max.</b> The current output adopts the value of the upper alarm level according to the <b>Current span</b> parameter (page 142).</li><li>• <b>Last valid value</b> The current remains constant at the last value it had before the error occurred.</li><li>• <b>Actual value</b> The output current follows the actual measured value; the error is ignored.</li><li>• <b>Defined value</b> The output current assumes the value defined in the <b>Failure current</b> parameter (page 143).</li></ul> <p><b>Note:</b> The error behavior of other output channels is not influenced by these settings but is defined in separate parameters.</p>

## Failure current

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Curr.output 1 to 2 → Failure current
<b>Prerequisite</b>	<b>Failure mode</b> (page 143) = <b>Defined value</b>
<b>Description</b>	Enter current output value in alarm condition.
<b>User entry</b>	3.59 to 22.5 mA
<b>Factory setting</b>	22.5 mA

## Output current 1 to 2

<b>Navigation</b>	Setup → Advanced setup → Curr.output 1 to 2 → Output curr. 1 to 2
<b>Description</b>	Displays calculated output current.



### 15.3.12 Switch output submenu

#### Switch output

##### Navigation

Setup → Advanced setup → Switch output

#### Switch output function

##### Blocking



##### Navigation

Setup → Advanced setup → Switch output → Switch out funct

##### Description

Select function for switch output.

##### Selection

- Off
- On
- Diagnostic behavior
- Limit
- Digital output

##### Factory setting

Off

##### Additional information

Meaning of the options

- **Off**

The output is always open (non-conductive).

- **On**

The output is always closed (conductive).

- **Diagnostic behavior**

The output is normally closed and is only opened if a diagnostic event is present. The **Assign diagnostic behavior** parameter (page 145) determines for which type of event the output is opened.

- **Limit**

The output is normally closed and is only opened if a measured variable exceeds or falls below a defined limit. The limit values are defined by the following parameters:

- **Assign limit** (page 145)
- **Switch-on value** (page 146)
- **Switch-off value** (page 147)

- **Digital output**

The switching state of the output tracks the output value of a DI function block. The function block is selected in the **Assign status** parameter (page 145).

**Note:** The **Off** and **On** options can be used to simulate the switch output.



## Assign status

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Switch output → Assign status
<b>Prerequisite</b>	<b>Switch output function (page 144) = Digital Output</b>
<b>Description</b>	Select device status for switch output.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Off</li><li>• Digital output AD 1</li><li>• Digital output AD 2</li></ul>
<b>Factory setting</b>	Off
<b>Additional information</b>	The <b>Digital output AD 1</b> and <b>Digital output AD 2</b> options refer to the Advanced Diagnostic Blocks.

## Assign limit

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Switch output → Assign limit
<b>Prerequisite</b>	<b>Switch output function (page 144) = Limit</b>
<b>Description</b>	Select process variable for limit monitoring.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Off</li><li>• Level linearized</li><li>• Distance</li><li>• Thickness upper layer</li><li>• Terminal voltage</li><li>• Electronic temperature</li><li>• Measured capacitance</li><li>• Relative echo amplitude</li><li>• Absolute echo amplitude</li></ul>
<b>Factory setting</b>	Off

## Assign diagnostic behavior

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Switch output → Assign diag. beh
<b>Prerequisite</b>	<b>Switch output function (page 144) = Diagnostic behavior</b>
<b>Description</b>	Select diagnostic behavior for switch output.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Alarm</li><li>• Alarm or warning</li><li>• Warning</li></ul>
<b>Factory setting</b>	Alarm



## Switch-on value

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Switch output → Switch-on value
<b>Prerequisite</b>	<b>Switch output function</b> (page 144) = <b>Limit</b>
<b>Description</b>	Enter measured value for the switch-on point.
<b>User entry</b>	Signed floating-point number
<b>Factory setting</b>	0
<b>Additional information</b>	The switching behavior depends on the relative position of the <b>Switch-on value</b> and <b>Switch-off value</b> parameters:

### Switch-on value > Switch-off value

- The output is closed if the measured value is larger than **Switch-on value**.
- The output is opened if the measured value is smaller than **Switch-off value**.

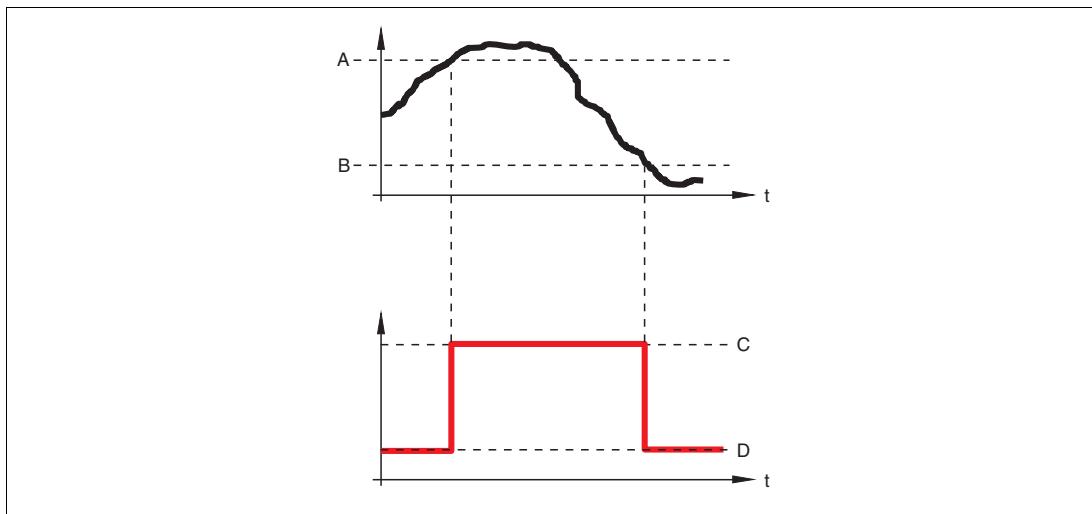


Figure 15.10

- A** Switch-on value
- B** Switch-off value
- C** Output closed (conductive)
- D** Output opened (non-conductive)



### Switch-on value < Switch-off value

- The output is closed if the measured value is smaller than **Switch-on value**.
- The output is opened if the measured value is larger than **Switch-off value**.

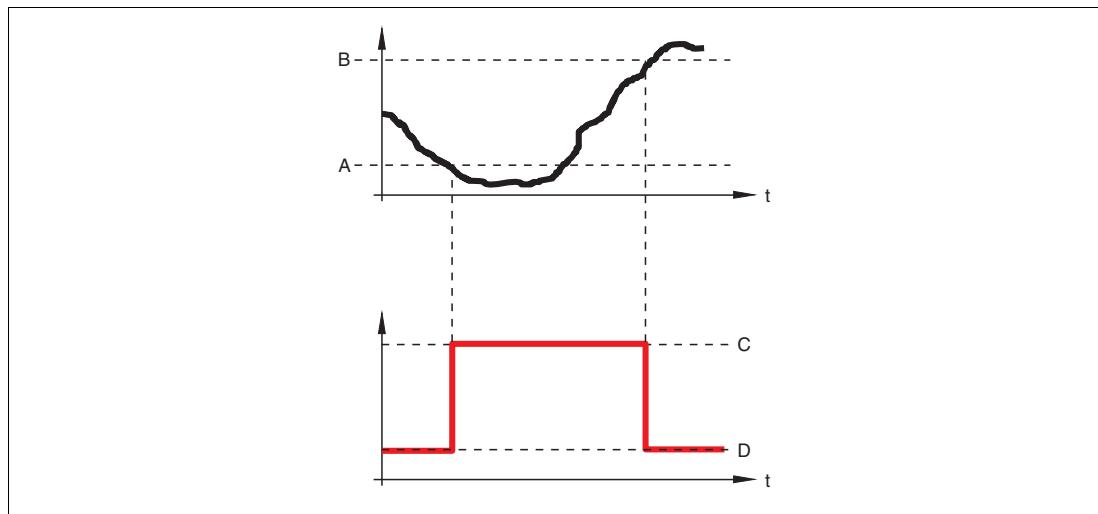


Figure 15.11

- A     Switch-on value
- B     Switch-off value
- C     Output closed (conductive)
- D     Output opened (non-conductive)

### Switch-on delay

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Switch output → Switch-on delay
<b>Prerequisite</b>	<ul style="list-style-type: none"><li>• <b>Switch output function</b> (page 144) = <b>Limit</b></li><li>• <b>Assign limit</b> (page 145) ≠ <b>Off</b></li></ul>
<b>Description</b>	Define switch-on delay.
<b>User entry</b>	0.0 to 100.0 s
<b>Factory setting</b>	0.0 s

### Switch-off value

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Switch output → Switch-off value
<b>Prerequisite</b>	<b>Switch output function</b> (page 144) = <b>Limit</b>
<b>Description</b>	Enter measured value for the switch-off point.
<b>User entry</b>	Signed floating-point number
<b>Factory setting</b>	0
<b>Additional information</b>	The switching behavior depends on the relative position of the <b>Switch-on value</b> and <b>Switch-off value</b> parameters (description: see the <b>Switch-on value</b> parameter (page 146)).



## Switch-off delay

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Switch output → Switch-off delay
<b>Prerequisite</b>	<ul style="list-style-type: none"><li>• <b>Switch output function</b> (page 144) = <b>Limit</b></li><li>• <b>Assign limit</b> (page 145) ≠ <b>Off</b></li></ul>
<b>Description</b>	Define switch-off delay.
<b>User entry</b>	0.0 to 100.0 s
<b>Factory setting</b>	0.0 s

## Failure mode

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Switch output → Failure mode
<b>Description</b>	Define output behavior in alarm condition.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Actual status</li><li>• Open</li><li>• Closed</li></ul>
<b>Factory setting</b>	Open

## Switch status

<b>Navigation</b>	Setup → Advanced setup → Switch output → Switch status
<b>Description</b>	Displays the current state of the switch output.

## Invert output signal

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Switch output → Invert outp.sig.
<b>Description</b>	Specify whether the output signal is to be inverted.
<b>Selection</b>	<ul style="list-style-type: none"><li>• No</li><li>• Yes</li></ul>
<b>Factory setting</b>	No
<b>Additional information</b>	Meaning of the options <ul style="list-style-type: none"><li>• <b>No</b> The behavior of the switch output is as described above.</li><li>• <b>Yes</b> The states <b>Open</b> and <b>Closed</b> are inverted as compared to the description above.</li></ul>



### 15.3.13 Display submenu

#### Display

**Note:** The **Display** submenu is only visible if a display module is connected to the device.

##### Navigation

Setup → Advanced setup → Display

#### Language

##### Navigation

Setup → Advanced setup → Display → Language

##### Description

Set display language.

##### Selection <sup>a</sup>

- English
- Deutsch
- Français
- Español
- Italiano
- Nederlands
- Portuguesa
- Polski
- Russian
- Svenska
- Türkçe
- Chinese
- Japanese
- Korean
- Arabic
- Bahasa Indonesia
- Thai
- Vietnamese
- Czech

##### Factory setting

English

##### Additional information

The **English** option can be selected in every device. One additional operating language can be selected in the product structure when ordering a device (feature "Additional Operation Language") and will be selectable in the **Language** parameter.

<sup>a</sup> Visibility depends on order options or device settings



## Format display

### Navigation

Setup → Advanced setup → Display → Format display

### Description

Select how measured values are shown on the display.

### Selection

- 1 value, max. size
- 1 bargraph + 1 value
- 2 values
- 1 value large + 2 values
- 4 values

### Factory setting

1 value, max. size

### Additional information

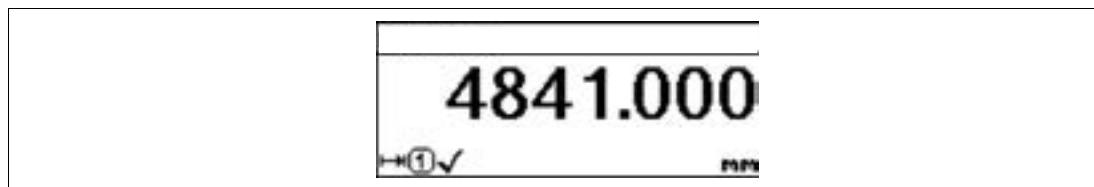


Figure 15.12 1 value, max. size

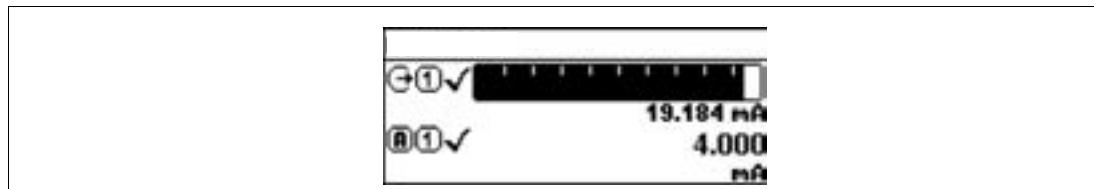


Figure 15.13 1 bargraph + 1 value

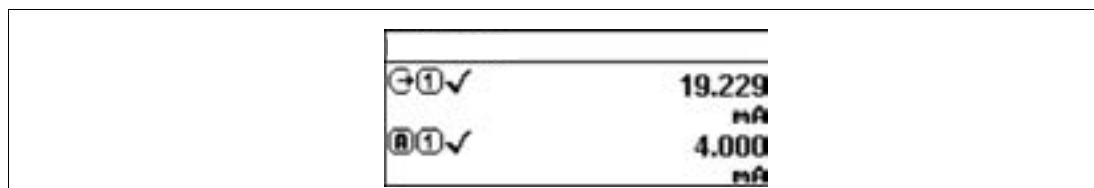


Figure 15.14 2 values

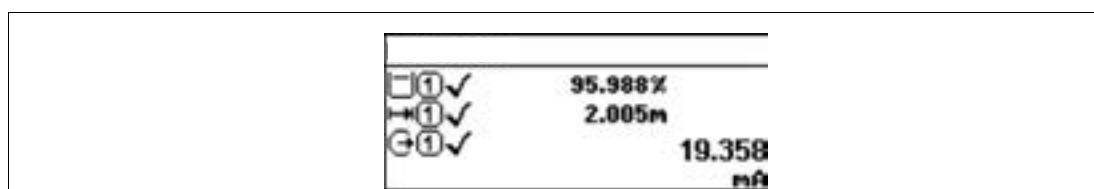


Figure 15.15 1 value large + 2 values

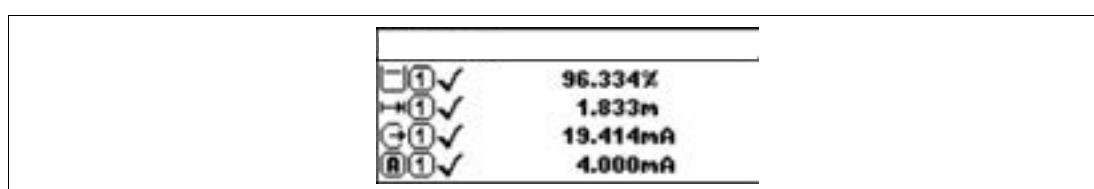


Figure 15.16 4 values



**Note:**

- The **Value 1 to 4 display** parameters (page 151) specify which measured values are shown on the display and in which order.
- If more measured values are specified than the current display mode permits, the values alternate on the device display. The display time until the next change is configured in the **Display interval** parameter (page 152).

### Value 1 to 4 display

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Display → Value 1 display
<b>Description</b>	Select the measured value that is shown on the local display.
<b>Selection</b>	<ul style="list-style-type: none"><li>• None <sup>a</sup></li><li>• Level linearized</li><li>• Distance</li><li>• Current output 1 <sup>b</sup></li><li>• Measured current</li><li>• Current output 2</li><li>• Terminal voltage</li><li>• Electronic temperature</li><li>• Analog output adv diagnostics 1</li><li>• Analog output adv diagnostics 2</li></ul>
<b>Factory setting</b>	For level measurements <ul style="list-style-type: none"><li>• Value 1 display: Level linearized</li><li>• Value 2 display: Distance</li><li>• Value 3 display: Current output 1</li><li>• Value 4 display: None</li></ul>

<sup>a</sup> can not be selected for the **Value 1 display** parameter

<sup>b</sup> Visibility depends on order options or device settings

### Decimal places 1 to 4

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Display → Decimal places 1
<b>Description</b>	Select the number of decimal places for the display value.
<b>Selection</b>	<ul style="list-style-type: none"><li>• x</li><li>• x.x</li><li>• x.xx</li><li>• x.xxx</li><li>• xxxxx</li></ul>
<b>Factory setting</b>	x.xx
<b>Additional information</b>	The <b>Decimal places 1 to 4</b> parameters do not affect the measuring or computational accuracy of the device. An error symbol between the measured value and the unit indicates that the device calculates with more digits than those indicated on the local display.



## Display interval

<b>Navigation</b>	Setup → Advanced setup → Display → Display interval
<b>Description</b>	Set time measured values are shown on display if display alternates between values.
<b>User entry</b>	1 to 10 s
<b>Factory setting</b>	5 s
<b>Additional information</b>	The <b>Display interval</b> parameter is only relevant if the number of measured values defined exceeds the number of values the selected display format can display simultaneously.

## Display damping

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Display → Display damping
<b>Description</b>	Define display reaction time to fluctuations in the measured value.
<b>User entry</b>	0.0 to 999.9 s
<b>Factory setting</b>	0.0 s

## Header

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Display → Header
<b>Description</b>	Select header contents on local display.
<b>Selection</b>	<ul style="list-style-type: none"><li>Device tag</li><li>Free text</li></ul>
<b>Factory setting</b>	Device tag
<b>Additional information</b>	Meaning of the options <ul style="list-style-type: none"><li><b>Device tag</b> Is defined in the <b>Device tag</b> parameter (page 112).</li><li><b>Free text</b> Is defined in the <b>Header text</b> parameter (page 153).</li></ul>

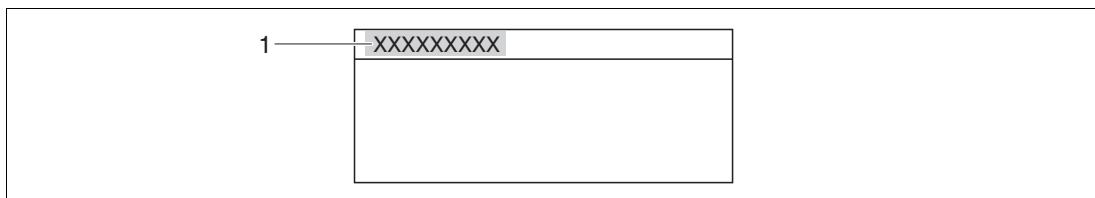


Figure 15.17

1 Position of the header text on the display



## Header text

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Display → Header text
<b>Prerequisite</b>	<b>Header</b> (page 152) = <b>Free text</b>
<b>Description</b>	Enter display header text.
<b>Factory setting</b>	_____
<b>Additional information</b>	The number of characters displayed depends on the characters used.

## Separator

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Display → Separator
<b>Description</b>	Select decimal separator for displaying numerical values.
<b>Selection</b>	<ul style="list-style-type: none"><li>• .</li><li>• ,</li></ul>
<b>Factory setting</b>	.

## Number format

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Display → Number format
<b>Description</b>	Choose number format for the display.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Decimal</li><li>• ft-in-1/16"</li></ul>
<b>Factory setting</b>	Decimal

**Additional information** The **ft-in-1/16"** option is only valid for distance units.

## Decimal places menu

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Display → Dec. places menu
<b>Description</b>	Select number of decimal places for the representation of numbers within the operating menu.
<b>Selection</b>	<ul style="list-style-type: none"><li>• x</li><li>• x.x</li><li>• x.xx</li><li>• x.xxx</li><li>• xxxxx</li></ul>
<b>Factory setting</b>	x.xxxx
<b>Additional information</b>	<ul style="list-style-type: none"><li>• Is only valid for numbers in the operating menu (e. g. <b>Empty calibration</b>, <b>Full calibration</b>), but not for the measured value display. The number of decimal places for the measured value display is defined in the <b>Decimal places 1 to 4</b> parameters (page 151).</li><li>• The <b>Decimal places menu</b> parameter does not affect the accuracy of the measurement or the calculations.</li></ul>



## Backlight

<b>Navigation</b>	Setup → Advanced setup → Display → Backlight
<b>Prerequisite</b>	The device has the SD03 local display (with optical keys).
<b>Description</b>	Switch the local display backlight on and off.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Disable</li><li>• Enable</li></ul>
<b>Factory setting</b>	Disable
<b>Additional information</b>	Meaning of the options <ul style="list-style-type: none"><li>• <b>Disable</b> Switches the backlight off.</li><li>• <b>Enable</b> Switches the backlight on.</li></ul>
	<b>Note:</b> Regardless of the setting in this parameter the backlight may be automatically switched off by the device if the supply voltage is too low.

## Contrast display

<b>Navigation</b>	Setup → Advanced setup → Display → Contrast display
<b>Description</b>	Adjust local display contrast setting to ambient conditions (e. g. lighting or reading angle).
<b>User entry</b>	20 to 80 %
<b>Factory setting</b>	Dependent on the display.
<b>Additional information</b>	<b>Note:</b> Setting the contrast via push-buttons: <ul style="list-style-type: none"><li>• Darker: Press the  and  buttons simultaneously.</li><li>• Brighter: Press the  and  buttons simultaneously.</li></ul>



### 15.3.14 Configuration backup display submenu

#### Configuration backup display

**Note:** This submenu is only visible if a display module is connected to the device. The configuration of the device can be saved to the display module at a certain point of time (backup). The saved configuration can be restored to the device if required, e. g. in order to bring the device back into a defined state. The configuration can also be transferred to a different device of the same type using the display module.

##### Navigation

Setup → Advanced setup → Conf.backup disp

#### Operating time

##### Navigation

Setup → Advanced setup → Conf.backup disp → Operating time

##### Description

Indicates how long the device has been in operation.

##### User interface

Days (d), hours (h), minutes (m), seconds (s)

##### Additional information

Maximum time: 9999 d (≈ 27 years)

#### Last backup

##### Navigation

Setup → Advanced setup → Conf.backup disp → Last backup

##### Description

Indicates when the last data backup was saved to the display module.

##### User interface

Days (d), hours (h), minutes (m), seconds (s)



## Configuration management

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Conf.backup disp → Config. managem.
<b>Description</b>	Select action for managing the device data in the display module.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Cancel</li><li>• Execute backup</li><li>• Restore</li><li>• Duplicate</li><li>• Compare</li><li>• Clear backup data</li></ul>
<b>Factory setting</b>	Cancel
<b>Additional information</b>	<p>Meaning of the options</p> <ul style="list-style-type: none"><li>• <b>Cancel</b> No action is executed and the user exits the parameter.</li><li>• <b>Execute backup</b> A backup copy of the current device configuration in the HistoROM (built-in in the device) is saved to the display module of the device.</li><li>• <b>Restore</b> The last backup copy of the device configuration is copied from the display module to the HistoROM of the device.</li><li>• <b>Duplicate</b> The transmitter configuration is duplicated to another device using the transmitter display module. The following parameters, which characterize the individual measuring point are <b>not</b> included in the transmitted configuration:<ul style="list-style-type: none"><li>– HART date code</li><li>– HART short tag</li><li>– HART message</li><li>– HART descriptor</li><li>– HART address</li><li>– Device tag</li><li>– Medium type</li></ul></li><li>• <b>Compare</b> The device configuration saved in the display module is compared to the current device configuration of the HistoROM. The result of this comparison is displayed in the <b>Comparison result</b> parameter (page 157).</li><li>• <b>Clear backup data</b> The backup copy of the device configuration is deleted from the display module of the device.</li></ul>

**Note:** While this action is in progress, the configuration cannot be edited via the local display and a message on the processing status appears on the display.

**Note:** If an existing backup is restored to a different device using the **Restore** option, it may occur that some device functionalities are no longer available. In some cases even a device reset will not restore the original status (page 159).

In order to transmit a configuration to a different device, the **Duplicate** option should always be used.



## Backup state

<b>Navigation</b>	Setup → Advanced setup → Conf.backup disp → Backup state
<b>Description</b>	Displays which backup action is currently in progress.

## Comparison result

<b>Navigation</b>	Setup → Advanced setup → Conf.backup disp → Compar. result
<b>Description</b>	Displays the comparison result between the device and the display.
<b>Additional information</b>	Meaning of the display options <ul style="list-style-type: none"><li>• <b>Settings identical</b> The current device configuration of the HistoROM is identical to the backup copy in the display module.</li><li>• <b>Settings not identical</b> The current device configuration of the HistoROM is not identical to the backup copy in the display module.</li><li>• <b>No backup available</b> There is no backup copy of the device configuration of the HistoROM in the display module.</li><li>• <b>Backup settings corrupt</b> The current device configuration of the HistoROM is corrupt or not compatible with the backup copy in the display module.</li><li>• <b>Check not done</b> The device configuration of the HistoROM has not yet been compared to the backup copy in the display module.</li><li>• <b>Dataset incompatible</b> The data sets are incompatible and can not be compared.</li></ul>
	<b>Note:</b> To start the comparison, set <b>Configuration management</b> (page 156) = <b>Compare</b> .
	<b>Note:</b> If the transmitter configuration has been duplicated from a different device by <b>Configuration management</b> (page 156) = <b>Duplicate</b> , the new device configuration in the HistoROM is only partially identical to the configuration stored in the display module: Sensor specific properties (e. g. the mapping curve) are not duplicated. Thus, the result of the comparison will be <b>Settings not identical</b> .



### 15.3.15 Administration submenu

#### Administration

##### Navigation

Setup → Advanced setup → Administration

#### Define access code

##### Blocking



##### Navigation

Setup → Advanced setup → Administration → Def. access code

##### Description

Define release code for write access to parameters.

##### User entry

0 to 9999

##### Factory setting

0

##### Additional information

**Note:** If the factory setting is not changed or 0 is defined as the access code, the parameters are not write-protected and the configuration data of the device can then always be modified. The user is logged on in the Maintenance role.

**Note:** The write protection affects all parameters marked with the symbol in this document. On the local display, the symbol in front of a parameter indicates that the parameter is write-protected.

**Note:** Once the access code has been defined, write-protected parameters can only be modified if the access code is entered in the **Enter access code** parameter (page 120).

**Note:** Please contact your Pepperl+Fuchs Sales Center if you lose your access code.

**Note:** For display operation: The new access code is only valid after it has been confirmed in the **Confirm access code** parameter (page 160).



## Device reset

<b>Blocking</b>	
<b>Navigation</b>	Setup → Advanced setup → Administration → Device reset
<b>Description</b>	Select to which state the device is to be reset.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Cancel</li><li>• To factory defaults</li><li>• To delivery settings</li><li>• Of customer settings</li><li>• Restart device</li></ul>
<b>Factory setting</b>	Cancel
<b>Additional information</b>	Meaning of the options <ul style="list-style-type: none"><li>• <b>Cancel</b> No action.</li><li>• <b>To factory defaults</b> All parameters are reset to the order-code specific factory setting.</li><li>• <b>To delivery settings</b> All parameters are reset to the delivery setting. The delivery setting may differ from the factory default if customer specific settings have been ordered. This option is only visible if customer specific settings have been ordered.</li><li>• <b>Of customer settings</b> All customer parameters are reset to their factory setting. Service parameters, however, remain unchanged.</li><li>• <b>Restart device</b> The restart resets every parameter which is stored in the volatile memory (RAM) to the factory setting (e. g. measured value data). The device configuration remains unchanged.</li></ul>



### 15.3.16 Define access code wizard

#### Define access code

**Note:** The **Define access code** wizard is only available when operating via the local display. When operating via an operating tool, the **Define access code** parameter is located directly in the **Administration** submenu. The **Confirm access code** parameter is not available for operation via operating tool.

**Navigation**

Setup → Advanced setup → Administration → Def. access code

#### Define access code

**Blocking****Navigation**

Setup → Advanced setup → Administration → Def. access code  
→ Def. access code

**Description**

Define access code (page 158)

#### Confirm access code

**Blocking****Navigation**

Setup → Advanced setup → Administration → Def. access code  
→ Confirm code

**Description**

Confirm the entered access code.

**User entry**

0 to 9999

**Factory setting**

0



## 15.4 Diagnostics menu

### Diagnostics

**Navigation** Diagnostics

#### Actual diagnostics

**Navigation** Diagnostics → Actual diagnos.

**Description** Displays current diagnostic message.

**Additional information** The display consists of:

- Symbol for event behavior
- Code for diagnostic behavior
- Operating time of occurrence
- Event text

**Note:** If several messages are active at the same time, the messages with the highest priority is displayed.

**Note:** Information on what is causing the message, and remedy measures, can be viewed via the symbol on the display.

#### Timestamp

**Navigation** Diagnostics → Timestamp

**Description** Displays timestamp for the **Actual diagnostics** parameter (page 161).

**User interface** Days (d), hours (h), minutes (m), seconds (s)

#### Previous diagnostics

**Navigation** Diagnostics → Prev.diagnostics

**Description** Displays the last diagnostic message which has been active before the current message.

**Additional information** The display consists of:

- Symbol for event behavior
- Code for diagnostics behavior
- Operating time of occurrence
- Event text

**Note:** The condition displayed may still apply. Information on what is causing the message, and remedy measures, can be viewed via the symbol on the display.

#### Timestamp

**Navigation** Diagnostics → Timestamp

**Description** Displays timestamp for the **Previous diagnostics** parameter (page 161).

**User interface** Days (d), hours (h), minutes (m), seconds (s)



## Operating time from restart

<b>Navigation</b>	 Diagnostics → Time fr. restart
<b>Description</b>	Displays the time the device has been in operation since the last device restart.
<b>User interface</b>	Days (d), hours (h), minutes (m), seconds (s)

## Operating time

<b>Navigation</b>	 Diagnostics → Operating time
<b>Description</b>	Indicates how long the device has been in operation.
<b>User interface</b>	Days (d), hours (h), minutes (m), seconds (s)
<b>Additional information</b>	Maximum time: 9999 d (≈ 27 years)



## 15.4.1 Diagnostic list submenu

### Diagnostic list

**Navigation**

Diagnostics → Diagnostic list

### Diagnostics 1 to 5

**Navigation**

Diagnostics → Diagnostic list → Diagnostics 1

**Description**

Display the current diagnostics messages with the highest to fifth-highest priority.

**Additional information**

The display consists of:

- Symbol for event behavior
- Code for diagnostic behavior
- Operating time of occurrence
- Event text

### Timestamp 1 to 5

**Navigation**

Diagnostics → Diagnostic list → Timestamp

**Description**

Displays timestamp for the **Diagnostics 1 to 5** parameter (page 163).

**User interface**

Days (d), hours (h), minutes (m), seconds (s)



## 15.4.2 Event logbook submenu

### Event logbook

**Note:** The **Event logbook** submenu is only available when operating via the local display. When operating via PACTware, the event list can be displayed in the PACTware function **Event List/HistoROM**.

**Navigation** Diagnostics → Event logbook

### Filter options

**Blocking**

**Navigation** Diagnostics → Event logbook → Filter options

**Description** Select event category.

- Selection**
- All
  - Failure (F)
  - Function check (C)
  - Out of specification (S)
  - Maintenance required (M)
  - Information (I)

**Factory setting** All

## 15.4.3 Event list submenu

The **Event list** submenu displays the history of past events of the category selected in the **Filter options** parameter (page 164). A maximum of 20 events are displayed in chronological order. If the advanced HistoROM functionality has been activated in the device, the event list may comprise up to 100 entries.

The following symbols indicate whether an event has occurred or has ended:

- Event has occurred
- Event has ended

**Note:** Information on what is causing the message, and remedy measures, can be viewed via the button.

### Display format

- For event messages in category I: information event, event text, "recording event" symbol and time the event occurred
- For event messages in category F, M, C, S (status signal): diagnostics event, event text, "recording event" symbol and time the event occurred



## 15.4.4 Device information submenu

### Device information

**Navigation** Diagnostics → Device info

#### Device tag

**Navigation** Diagnostics → Device info → Device tag

**Description** Enter tag for measuring point.

**Factory setting** LTC5X

#### Serial number

**Navigation** Diagnostics → Device info → Serial number

**Description** Displays serial number of the device.

**Additional information** **Note:** Uses of the serial number

- To identify the device quickly, e. g. when contacting Pepperl+Fuchs.
- To obtain specific information on the device: See [www.pepperl-fuchs.com](http://www.pepperl-fuchs.com).

**Note:** The serial number is also indicated on the nameplate.

#### Firmware version

**Navigation** Diagnostics → Device info → Firmware version

**Description** Displays Firmware version of the device.

**User interface** xx.yy.zz

**Additional information** **Note:** For firmware versions differing only in the last two digits ("zz") there is no difference concerning functionality or operation.

#### Device name

**Navigation** Diagnostics → Device info → Device name

**Description** Displays device name.

#### Order code

**Navigation** Diagnostics → Device info → Order code

**Description** Displays order code of the device.

**Additional information** The order code is generated from the extended order code, which defines all device features of the product structure. In contrast, the device features can not be read directly from the order code.

#### Extended order code 1 to 3

**Navigation** Diagnostics → Device info → Ext. order cd. 1

**Description** Display the three parts of the extended order code.

**Additional information** The extended order code indicates the version of all the features of the product structure and thus uniquely identifies the device.



## Device revision

<b>Navigation</b>	Diagnostics → Device info → Device revision
<b>Description</b>	Displays the device revision with which the device is registered with the HART Communication Foundation.
<b>Additional information</b>	The device revision is needed to allocate the correct Device Description file (DD) to the device.

## Device ID

<b>Navigation</b>	Diagnostics → Device info → Device ID
<b>Description</b>	Displays Device ID.
<b>Additional information</b>	In addition to the Device type and Manufacturer ID, the Device ID is part of the unique device identification (Unique ID) which characterizes each HART device unambiguously.

## Device type

<b>Navigation</b>	Diagnostics → Device info → Device type
<b>Description</b>	Displays the device type with which the device is registered with the HART Communication Foundation.
<b>Additional information</b>	The device type is needed to allocate the correct Device Description file (DD) to the device.

## Manufacturer ID

<b>Navigation</b>	Diagnostics → Device info → Manufacturer ID
<b>Description</b>	Displays the manufactured ID with which the device is registered with the HART Communication Foundation.



## 15.4.5 Measured values submenu

### Measured values

#### Navigation

■■■ Diagnostics → Measured val.

### Distance

#### Navigation

■■■ Diagnostics → Measured val. → Distance

#### Description

Displays the measured distance  $D_L$  between the reference point (lower edge of the flange or threaded connection) and the level.

**Additional information** Note: The unit is defined in the **Level unit** parameter (page 112).

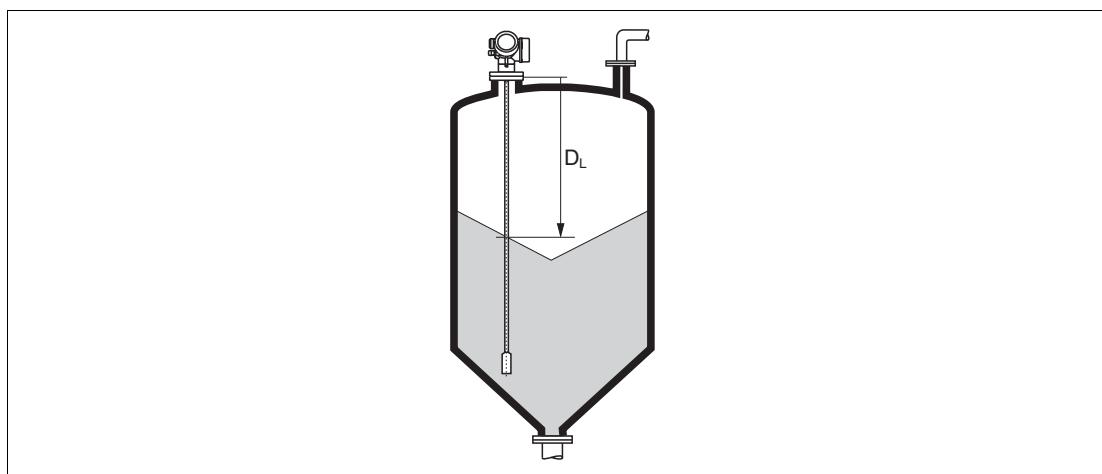


Figure 15.18 Distance for bulk solid measurements

### Level linearized

#### Navigation

■■■ Diagnostics → Measured val. → Level linearized

#### Description

Displays linearized level.

**Additional information** Note: The unit is defined by the **Unit after linearization** parameter (page 127).

### Output current 1 to 2

#### Navigation

■■■ Diagnostics → Measured val. → Output curr. 1 to 2

#### Description

Displays calculated output current.

### Measured current 1

#### Navigation

■■■ Diagnostics → Measured val. → Measur. curr. 1

#### Prerequisite

Only available for current output 1

#### Description

Displays the measured value of the output current.

### Terminal voltage 1

#### Navigation

■■■ Diagnostics → Measured val. → Terminal volt. 1

#### Prerequisite

Only available for current output 1

#### Description

Displays terminal voltage at the current output.



## 15.4.6 Data logging submenu

### Data logging

**Note:** The **Data logging** submenu is only available if the advanced functionality of the HistoROM has been activated in the device.

#### Navigation

Diagnostics → Data logging

### Assign channel 1 to 4

#### Blocking



#### Navigation

Diagnostics → Data logging → Assign chan. 1 to 4

#### Description

Allocate a process variable to the respective data logging channel.

#### Selection

- Off
- Level linearized
- Distance
- Unfiltered distance
- Current output 1
- Measured current
- Current output 2
- Terminal voltage
- Electronic temperature
- Measured capacitance <sup>a</sup>
- Absolute echo amplitude
- Relative echo amplitude
- Absolute EOP amplitude
- EOP shift
- Noise of signal
- Sensor debug
- Calculated DC value <sup>b</sup>
- Analog output adv. diagnostics 1
- Analog output adv. diagnostics 2

#### Factory setting

Off

#### Additional information

A total of 500 measured values can be logged. This means:

- 500 data points if 1 logging channel is used
- 250 data points if 2 logging channels are used
- 166 data points if 3 logging channels are used
- 125 data points if 4 logging channels are used

If the maximum number of data points is reached, the oldest data points in the data log are cyclically overwritten in such a way that the last 500, 250, 166 or 125 measured values are always in the log (ring memory principle).

**Note:** The logged data are deleted if a new option is selected in this parameter.

<sup>a</sup> Visibility depends on order options or device settings

<sup>b</sup> Visibility depends on order options or device settings

## Logging interval

<b>Blocking</b>	
<b>Navigation</b>	Diagnostics → Data logging → Logging interval
<b>Description</b>	Define logging interval $t_{\log}$ .
<b>User entry</b>	1.0 to 3600.0 s
<b>Factory setting</b>	30.0 s
<b>Additional information</b>	<p>This parameter defines the interval between the individual data points in the data log, and thus the maximum loggable process time <math>T_{\log}</math>:</p> <ul style="list-style-type: none"> <li>• If 1 logging channel is used: <math>T_{\log} = 500 \times t_{\log}</math></li> <li>• If 2 logging channels are used: <math>T_{\log} = 250 \times t_{\log}</math></li> <li>• If 3 logging channels are used: <math>T_{\log} = 166 \times t_{\log}</math></li> <li>• If 4 logging channels are used: <math>T_{\log} = 125 \times t_{\log}</math></li> </ul> <p>Once this time elapses, the oldest data points in the data log are cyclically overwritten such that a time of <math>T_{\log}</math> always remains in the memory (ring memory principle).</p> <p><b>Note:</b> The logged data are deleted if this parameter is changed.</p>

### Example

When using 1 logging channel

- $T_{\log} = 500 \times 1 \text{ s} = 500 \text{ s} \approx 8.5 \text{ min}$
- $T_{\log} = 500 \times 10 \text{ s} = 5000 \text{ s} \approx 1.5 \text{ h}$
- $T_{\log} = 500 \times 80 \text{ s} = 40000 \text{ s} \approx 11 \text{ h}$
- $T_{\log} = 500 \times 3600 \text{ s} = 1800000 \text{ s} \approx 20 \text{ d}$

## Clear logging data

<b>Blocking</b>	
<b>Navigation</b>	Diagnostics → Data logging → Clear logging
<b>Description</b>	Initiate a deletion of the complete logging memory.
<b>Selection</b>	<ul style="list-style-type: none"> <li>• Cancel</li> <li>• Clear data</li> </ul>
<b>Factory setting</b>	Cancel



## 15.4.7 Display channel 1 to 4 submenu

### Display channel 1 to 4

**Note:** The **Display channel 1 to 4** submenu is only available for operation via the local display. When operating via PACTware, the logging diagram can be displayed in the PACTware function **Event List/HistoROM**.

The **Display channel 1 to 4** submenu invokes a diagram of the logging history of the respective channel.

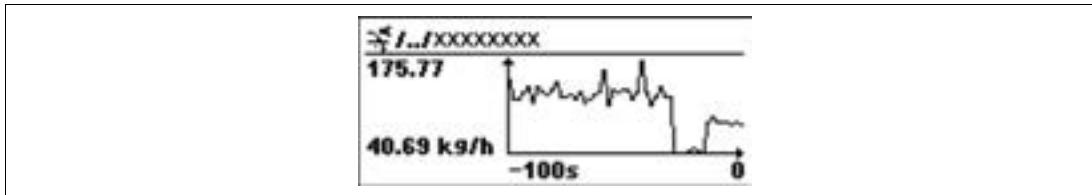


Figure 15.19

- X-axis: Depending on the number of selected channels, 250 to 1000 measured values of a process variable are displayed.
- Y-axis: Covers the approximate measured value span and constantly adapts this to the measurement.

**Note:** To return to the operating menu, press and simultaneously.

#### Navigation

Diagnostics → Data logging → Display chan. 1 to 4



## 15.4.8 Simulation submenu

### Simulation

**Navigation**

Diagnostics → Simulation

#### Assign measurement variable

**Blocking****Navigation**

Diagnostics → Simulation → Assign meas.var.

**Description**

Select process variable to be simulated.

**Selection**

- Off
- Level
- Level linearized
- Thickness linearized

**Factory setting**

Off

**Additional information**

- The value of the variable to be simulated is defined in the **Value process variable** parameter (page 171).
- If **Assign measurement variable** ≠ Off, a simulation is active. This is indicated by a diagnostic message of the **Function check (C)** category.

#### Value process variable

**Blocking****Navigation**

Diagnostics → Simulation → Value proc. var.

**Prerequisite**

**Assign measurement variable** (page 171) ≠ Off

**Description**

Specify value of the process value being simulated.

**User entry**

Signed floating-point number

**Factory setting**

0

**Additional information**

Downstream measured value processing and the signal output use this simulation value. In this way, users can verify whether the measuring device has been configured correctly.

#### Simulation current output 1 to 2

**Blocking****Navigation**

Diagnostics → Simulation → Sim.curr.out. 1 to 2

**Description**

Switch the simulation of the current output on or off.

**Selection**

- Off
- On

**Factory setting**

Off

**Additional information**

An active simulation is indicated by a diagnostic message of the **Function check (C)** category.



## Value current output 1 to 2

<b>Blocking</b>	
<b>Navigation</b>	Diagnostics → Simulation → Value curr.out 1 to 2
<b>Prerequisite</b>	<b>Simulation current output</b> (page 171) = <b>On</b>
<b>Description</b>	Enter current value for the simulation.
<b>User entry</b>	3.59 to 22.5 mA
<b>Factory setting</b>	3.59 mA
<b>Additional information</b>	The current output assumes the value specified in this parameter. In this way, users can verify the correct adjustment of the current output and the correct function of connected control units.

## Switch output simulation

<b>Blocking</b>	
<b>Navigation</b>	Diagnostics → Simulation → Switch sim.
<b>Description</b>	Switch the simulation of the switch output on or off.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Off</li><li>• On</li></ul>
<b>Factory setting</b>	Off

## Switch status

<b>Blocking</b>	
<b>Navigation</b>	Diagnostics → Simulation → Switch status
<b>Prerequisite</b>	<b>Switch output simulation</b> (page 172) = <b>On</b>
<b>Description</b>	Define the switch state to be simulated.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Open</li><li>• Closed</li></ul>
<b>Factory setting</b>	Open

**Additional information** The switch status assumes the value defined in this parameter. This helps to check correct operation of connected control units.

## Simulation device alarm

<b>Blocking</b>	
<b>Navigation</b>	Diagnostics → Simulation → Sim. alarm
<b>Description</b>	Switch alarm simulation on or off.
<b>Selection</b>	<ul style="list-style-type: none"><li>• Off</li><li>• On</li></ul>
<b>Factory setting</b>	Off
<b>Additional information</b>	When selecting the <b>On</b> option, the device generates an alarm. This helps to check the correct output behavior of the device in the case of an alarm. An active simulation is indicated by a diagnostic message of the <b>Function check (C)</b> category.



## 15.4.9 Device check submenu

### Device check

**Navigation** Diagnostics → Device check

#### Start device check

**Blocking**

**Navigation** Diagnostics → Device check → Start dev. check

**Description** Start a device check.

- Selection**
- No
  - Yes

**Factory setting** No

**Additional information** In the case of a lost echo a device check can not be performed.

#### Result device check

**Navigation** Diagnostics → Device check → Result dev.check

**Description** Displays the result of the device check.

**Additional information** Meaning of the display options

- **Installation OK**  
Measurement possible without restrictions.
- **Accuracy reduced**  
A measurement is possible. However, the measuring accuracy may be reduced due to the signal amplitudes.
- **Measurement capability reduced**  
A measurement is currently possible. However, there is the risk of an echo loss.  
Check the mounting position of the device and the dielectric constant of the medium.
- **Check not done**  
No device check has been performed.

#### Last check time

**Navigation** Diagnostics → Device check → Last check time

**Description** Displays the operating time at which the last device check has been performed.

#### Level signal

**Navigation** Diagnostics → Device check → Level signal

**Prerequisite** Device check has been performed.

**Description** Displays result of the device check for the level signal.

- User interface**
- Check not done
  - Check not OK
  - Check OK

**Additional information** For **Level signal = Check not OK**: Check the mounting position of the device and the dielectric constant of the medium.



## Launch signal

<b>Navigation</b>	Diagnostics → Device check → Launch signal
<b>Prerequisite</b>	Device check has been performed.
<b>Description</b>	Displays result of the display check for the launch signal.
<b>User interface</b>	<ul style="list-style-type: none"><li>• Check not done</li><li>• Check not OK</li><li>• Check OK</li></ul>
<b>Additional information</b>	For <b>Launch signal = Check not OK</b> : Check the mounting position of the device. In non-metallic vessels use a metal plate or a metal flange.



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