Functional Safety
SMART Transmitter Power
Supply
HiD2030(SK)

**Manual** 







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# 1 Introduction

#### 1.1 Content of this Document

This document contains information for usage of the device in functional safety-related applications. You need this information to use your product throughout the applicable stages of the product life cycle. These can include the following:

- Product identification
- Delivery, transport, and storage
- Mounting and installation
- Commissioning and operation
- Maintenance and repair
- Troubleshooting
- Dismounting
- Disposal



#### Note

This document does not substitute the instruction manual.



#### Note

For full information on the product, refer to the instruction manual and further documentation on the Internet at www.pepperl-fuchs.com.

The documentation consists of the following parts:

- Present document
- Instruction manual
- Manual
- Datasheet

Additionally, the following parts may belong to the documentation, if applicable:

- EU-type examination certificate
- · EU declaration of conformity
- · Attestation of conformity
- Certificates
- Control drawings
- FMEDA report
- Assessment report
- Additional documents

For more information about Pepperl+Fuchs products with functional safety, see www.pepperl-fuchs.com/sil.

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# 1.2 Safety Information

# **Target Group, Personnel**

Responsibility for planning, assembly, commissioning, operation, maintenance, and dismounting lies with the plant operator.

Only appropriately trained and qualified personnel may carry out mounting, installation, commissioning, operation, maintenance, and dismounting of the product. The personnel must have read and understood the instruction manual and the further documentation.

#### **Intended Use**

The device is only approved for appropriate and intended use. Ignoring these instructions will void any warranty and absolve the manufacturer from any liability.

The device is developed, manufactured and tested according to the relevant safety standards.

Use the device only

- · for the application described
- with specified environmental conditions
- · with devices that are suitable for this safety application

## **Improper Use**

Protection of the personnel and the plant is not ensured if the device is not used according to its intended use.



# 1.3 Symbols Used

This document contains symbols for the identification of warning messages and of informative messages.

# **Warning Messages**

You will find warning messages, whenever dangers may arise from your actions. It is mandatory that you observe these warning messages for your personal safety and in order to avoid property damage.

Depending on the risk level, the warning messages are displayed in descending order as follows:



# Danger!

This symbol indicates an imminent danger.

Non-observance will result in personal injury or death.



#### Warning!

This symbol indicates a possible fault or danger.

Non-observance may cause personal injury or serious property damage.



#### Caution!

This symbol indicates a possible fault.

Non-observance could interrupt the device and any connected systems and plants, or result in their complete failure.

# **Informative Symbols**



#### Note

This symbol brings important information to your attention.



#### **Action**

This symbol indicates a paragraph with instructions. You are prompted to perform an action or a sequence of actions.

# 2 Product Description

# 2.1 Validity

This manual is only valid for devices with a part number greater than #70122700.

Contact your Pepperl+Fuchs representative for information about older devices.

#### 2.2 Function

#### **General**

This isolated barrier is used for intrinsic safety applications.

Digital signals may be superimposed on the analog values in the explosion hazardous or non-explosion hazardous area, which are transferred bidirectionally.

A separate fault bus is signaled if the input signal is outside the range from 0.2 mA to 24 mA. The fault conditions can be monitored via a Fault Indication Board.

This device mounts on a HiD Termination Board.

#### **HiD2030**

The device provides a fully floating supply to power 2-wire SMART transmitters in the explosion-hazardous area, and repeats the current to drive a non-explosion hazardous area load. It is also used with 2-wire current sources.

In the non-explosion hazardous area, the signal current is repeated to drive a load (source).

#### HiD2030SK

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In the non-explosion hazardous area, the signal current is repeated with a passive current output (sink).



#### Note

See corresponding datasheets for further information.

#### 2.3 Interfaces

The device has the following interfaces:

- · Safety relevant interfaces: input I, input II, output I, output II
- Non-safety relevant interfaces: separate fault bus



#### Note

For corresponding connections see datasheet.

# 2.4 Marking

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HiD2030, HiD2030SK	Up to SIL 2



#### Note

If you design the safety loops in homogeneous redundancy (HFT = 1), you can use the devices in applications up to SIL 3.

# 2.5 Standards and Directives for Functional Safety

# **Device specific standards and directives**

Functional safety	IEC/EN 61508, part 1 – 7, edition 2010: Functional safety of electrical/electronic/programmable electronic
	safety-related systems (manufacturer)

# System-specific standards and directives

Functional safety	IEC 61511-1:2016+COR1:2016+A1:2017 EN 61511-1:2017+A1:2017 Functional safety – Safety instrumented systems for the process
	industry sector (user)

# 3 Planning

# 3.1 System Structure

## 3.1.1 Low Demand Mode of Operation

If there are two control loops, one for the standard operation and another one for the functional safety, then usually the demand rate for the safety loop is assumed to be less than once per year.

The relevant safety parameters to be verified are:

- the PFD<sub>avg</sub> value (average Probability of dangerous Failure on Demand) and the T<sub>1</sub> value (proof test interval that has a direct impact on the PFD<sub>avg</sub> value)
- the SFF value (Safe Failure Fraction)
- the HFT architecture (Hardware Fault Tolerance)

## 3.1.2 High Demand or Continuous Mode of Operation

If there is only one safety loop, which combines the standard operation and safety-related operation, then usually the demand rate for this safety loop is assumed to be higher than once per year.

The relevant safety parameters to be verified are:

- the PFH value (Probability of dangerous Failure per Hour)
- Fault reaction time of the safety system
- the SFF value (Safe Failure Fraction)
- the HFT architecture (Hardware Fault Tolerance)

### 3.1.3 Safe Failure Fraction

The safe failure fraction describes the ratio of all safe failures and dangerous detected failures to the total failure rate.

$$SFF = (\lambda_s + \lambda_{dd}) / (\lambda_s + \lambda_{dd} + \lambda_{du})$$

A safe failure fraction as defined in IEC/EN 61508 is only relevant for elements or (sub)systems in a complete safety loop. The device under consideration is always part of a safety loop but is not regarded as a complete element or subsystem.

For calculating the SIL of a safety loop it is necessary to evaluate the safe failure fraction of the elements and subsystems, but not of a single device.

Nevertheless the SFF of the device is given in this document for reference.

# 3.2 Assumptions

The following assumptions have been made during the FMEDA:

- Only one input and one output are part of the safety function.
- Failure rate based on the Siemens standard SN 29500.
- Failure rates are constant, wear is not considered.
- External power supply failure rates are not included.
- The safety-related device is considered to be of type A device with a hardware fault tolerance of 0.
- The device will be used under average industrial ambient conditions comparable
  to the classification "stationary mounted" according to MIL-HDBK-217F.

Alternatively, operating stress conditions typical of an industrial field environment similar to IEC/EN 60654-1 Class C with an average temperature over a long period of time of 40 °C may be assumed. For a higher average temperature of 60 °C, the failure rates must be multiplied by a factor of 2.5 based on experience. A similar factor must be used if frequent temperature fluctuations are expected.

- If you are using the HART function, observe that the HART signal superimposes an analog signal on the signal line. This is negligible for slow acquisition system (typically < 25 acquisition/s). If in doubt, use HART filters at the analog input of the receiving device.
- The application program in the programmable logic controller (PLC) is configured to detect underrange and overrange failures.
- The fault bus is not considered in the FMEDA and in the calculations.

## SIL 2 Application

- To build a SIL safety loop for the defined SIL, it is assumed as an example that this device uses 10 % of the available budget for PFD<sub>ava</sub>/PFH.
- Since the safety loop has a hardware fault tolerance of 0 and it is a type A device, the SFF must be > 60 % according to table 2 of IEC/EN 61508-2 for a SIL 2 (sub) system.

# 3.3 Safety Function and Safe State

#### **Safe State**

The safe state depends on the limit value in the respective application.

# **Safety Function**

The device transfers analog signals from the input to the output with a deviation of less than 2%.

Values outside the range of the output signals indicate a fault in the periphery or within the device and a dangerous detected failure. The valid range is

- 3.6 mA to 21 mA for current outputs and
- 0.9 V to 5.25 V for voltage outputs.

Input signals	Output signals
0/4 mA to 20 mA	0/4 mA to 20 mA
0/4 mA to 20 mA	0/1 V to 5 V

Table 3.1

#### **DIP switch settings for HiD2030**

The outputs can be configured as:

- 4 mA to 20 mA current output
- 1 V to 5 V voltage output

Output	CH 2		CH 1	
	SW1	SW2	SW3	SW4
4 mA to 20 mA	OFF	OFF	OFF	OFF
1 V to 5 V	ON	ON	ON	ON

Table 3.2

## DIP switch settings for HiD2030SK

No user configuration available for this device.

#### **Line Fault Detection**

The line fault detection is always active. The line fault detection cannot be deactivated.



## Note

The separate fault bus is not safety relevant.

#### **Reaction Time**

The reaction time for all safety functions is < 10 ms.



#### Note

See corresponding datasheets for further information.



# 3.4 Characteristic Safety Values

Parameters	Characteristic values
Assessment type and documentation	Full assessment
Device type	Α
Mode of operation	Low demand mode or high demand mode
HFT	0
SIL	2
SC	3
Safety function	Transfer of the analog signals
$\lambda_s^1$	109 FIT
$\lambda_{dd}$	68 FIT
$\lambda_{du}$	51.9 FIT
λtotal (safety function) <sup>1</sup>	229 FIT
λ <sub>not part</sub>	182 FIT
SFF <sup>1</sup>	77.35 %
MTBF <sup>2</sup>	190 years
PFH	5.19 x 10 <sup>-8</sup> 1/h
PTC	100 %
PFD <sub>avg</sub> for T <sub>1</sub> = 1 year	2.27 x 10 <sup>-4</sup>
PFD <sub>avg</sub> for T <sub>1</sub> = 2 years	4.54 x 10 <sup>-4</sup>
PFD <sub>avg</sub> for T <sub>1</sub> = 5 years	1.14 x 10 <sup>-3</sup>
Fault reaction time <sup>3</sup>	< 10 ms

Table 3.3

The characteristic safety values like PFD, PFH, SFF, HFT and  $T_1$  are taken from the FMEDA report. Observe that PFD and  $T_1$  are related to each other.

The function of the devices has to be checked within the proof test interval  $(T_1)$ .

<sup>1 &</sup>quot;No effect failures" are not influencing the safety function and are therefore not included in the SFF and the safety values of the safety function.

 $<sup>^2</sup>$  acc. to SN29500. This value includes failures which are not part of the safety function/MTTR = 8 h. The value is calculated for one safety function of the device.

<sup>3</sup> Time between fault detection and fault reaction

# 3.5 Useful Lifetime

Although a constant failure rate is assumed by the probabilistic estimation this only applies provided that the useful lifetime of components is not exceeded. Beyond this useful lifetime, the result of the probabilistic estimation is meaningless as the probability of failure significantly increases with time. The useful lifetime is highly dependent on the component itself and its operating conditions – temperature in particular. For example, electrolytic capacitors can be very sensitive to the operating temperature.

This assumption of a constant failure rate is based on the bathtub curve, which shows the typical behavior for electronic components.

Therefore it is obvious that failure calculation is only valid for components that have this constant domain and that the validity of the calculation is limited to the useful lifetime of each component.

It is assumed that early failures are detected to a huge percentage during the installation and therefore the assumption of a constant failure rate during the useful lifetime is valid.

However, according to IEC/EN 61508-2, a useful lifetime, based on general experience, should be assumed. Experience has shown that the useful lifetime often lies within a range period of about 8 to 12 years.

As noted in DIN EN 61508-2:2011 note N3, appropriate measures taken by the manufacturer and plant operator can extend the useful lifetime.

Our experience has shown that the useful lifetime of a Pepperl+Fuchs product can be higher if the ambient conditions support a long life time, for example if the ambient temperature is significantly below 60 °C.

Please note that the useful lifetime refers to the (constant) failure rate of the device. The effective life time can be higher.

The estimated useful lifetime is greater than the warranty period prescribed by law or the manufacturer's guarantee period. However, this does not result in an extension of the warranty or guarantee services. Failure to reach the estimated useful lifetime is not a material defect.



# 4 Mounting and Installation



# Mounting and Installing the Device

- 1. Observe the safety instructions in the instruction manual.
- 2. Observe the information in the manual.
- 3. Observe the requirements for the safety loop.
- 4. Connect the device only to devices that are suitable for this safety application.
- 5. Check the safety function to ensure the expected output behavior.

# 4.1 Configuration



# **Configuring the Device**

The device is configured via DIP switches. The DIP switches for setting the safety functions are on the side of the device.

- 1. De-energize the device before configuring the device.
- 2. Remove the device.
- 3. Configure the device for the required safety function via the DIP switches, see chapter 3.3.
- 4. Secure the DIP switches to prevent unintentional adjustments.
- Mount the device.
- 6. Connect the device again.



#### Note

See corresponding datasheets for further information.

## 5

# **Operation**



#### Danger!

Danger to life from missing safety function

If the safety loop is put out of service, the safety function is no longer guaranteed.

- Do not deactivate the device.
- Do not bypass the safety function.
- Do not repair, modify, or manipulate the device.



#### Operating the device

- 1. Observe the safety instructions in the instruction manual.
- 2. Observe the information in the manual.
- 3. Use the device only with devices that are suitable for this safety application.
- **4.** Correct any occurring safe failures within 8 hours. Take measures to maintain the safety function while the device is being repaired.

#### 5.1 Proof Test

This section describes a possible proof test procedure. The user is not obliged to use this proposal. The user may consider different concepts with an individual determination of the respective effectiveness, e. g. concepts according to NA106:2018.

According to IEC/EN 61508-2 a recurring proof test shall be undertaken to reveal potential dangerous failures that are not detected otherwise.

Check the function of the subsystem at periodic intervals depending on the applied PFD<sub>avg</sub> in accordance with the characteristic safety values provided. See chapter 3.4.

It is under the responsibility of the plant operator to define the type of proof test and the interval time period.

With the following instructions a proof test can be performed which will reveal all of the possible dangerous faults (diagnostic coverage 100 %).

#### Equipment required:

Digital multimeter with an accuracy better than 0.1 %
 Use for the proof test of the intrinsic safety side of the device a special digital multimeter for intrinsically safe circuits.

Intrinsically safe circuits that were operated with non-intrinsically safe circuits may not be used as intrinsically safe circuits afterwards.

- Power supply set to nominal voltage of 24 V DC
- For HiD2030SK: Power supply 24 V DC and line resistor 250 Ω/1 W
- Process calibrator with current source and current sink function with an accuracy better than 20  $\mu\text{A}$





#### **Proof Test Procedure**

- 1. Put out of service the entire safety loop. Protect the application by means of other measures.
- 2. Prepare a test set-up, see figures below.
- 3. Test all channels of the device. Verify the current and voltage values as given in table below.
- 4. After the test, reset the device to the original settings.

Set input value (mA)	Mandatory measuring points		
	Output value (mA)	Output value (V)	
20.0	20.0 ± 0.4	5.0 ± 0.1	
12.0	12.0 ± 0.4	3.0 ± 0.1	
4.0	4.0 ± 0.4	1.0 ± 0.1	
23.0	23.0 ± 0.4	5.75 ± 0.1	
0	< 0,2	< 0.05	

Table 5.1 Steps to be performed for the proof test

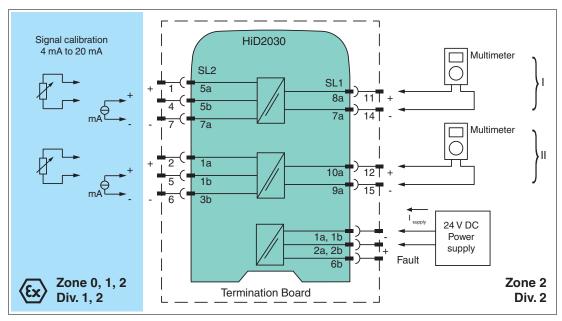


Figure 5.1 Proof test set-up for HiD2030

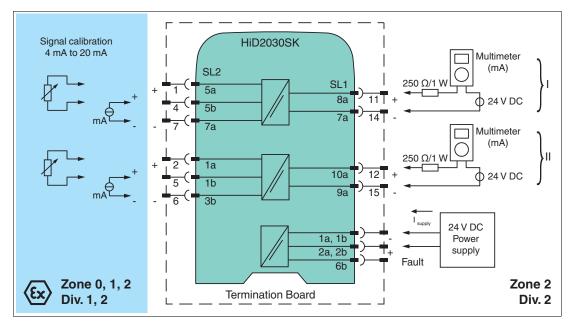


Figure 5.2 Proof test set-up for HiD2030SK

#### 6

# **Maintenance and Repair**



#### Danger!

Danger to life from missing safety function

Changes to the device or a defect of the device can lead to device malfunction. The function of the device and the safety function is no longer guaranteed.

Do not repair, modify, or manipulate the device.



## Maintaining, Repairing or Replacing the Device

In case of maintenance, repair or replacement of the device, proceed as follows:

- 1. Implement appropriate maintenance procedures for regular maintenance of the safety loop.
- 2. While the device is maintained, repaired or replaced, the safety function does not work. Take appropriate measures to protect personnel and equipment while the safety function is not available.
- Secure the application against accidental restart.
- 3. Do not repair a defective device. A defective device must only be repaired by the manufacturer.
- 4. If there is a defect, always replace the device with an original device.



## **Reporting Device Failure**

If you use the device in a safety loop according to IEC/EN 61508, it is required to inform the device manufacturer about possible systematic failures.

Report all failures in the safety function that are due to functional limitations or a loss of device function – especially in the case of possible dangerous failures.

In these cases, contact your local sales partner or the Pepperl+Fuchs technical sales support (service line).

It is not necessary to report failures in the safety function that are due to external influences or damage.

# 7 List of Abbreviations

ESD Emergency Shutdown

FIT Failure In Time in 10<sup>-9</sup> 1/h

FMEDA Failure Mode, Effects, and Diagnostics Analysis

 $\lambda_s$  Probability of safe failure

 $\lambda_{dd}$  Probability of dangerous detected failure  $\lambda_{du}$  Probability of dangerous undetected failure

 $\lambda_{\text{no effect}}$  Probability of failures of components in the safety loop that have

no effect on the safety function.

 $\lambda_{\text{not part}}$  Probability of failure of components that are not in the safety loop  $\lambda_{\text{total (safety function)}}$  Probability of failure of components that are in the safety loop

HFT Hardware Fault Tolerance

MTBF Mean Time Between Failures

MTTR Mean Time To Restoration

PCS Process Control System

PFD<sub>avg</sub> Average Probability of dangerous Failure on Demand
PFH Average frequency of dangerous failure per hour

PLC Programmable Logic Controller

PTC Proof Test Coverage
SC Systematic Capability
SFF Safe Failure Fraction

SIF Safety Instrumented Function

SIL Safety Integrity Level

SIS Safety Instrumented System

T<sub>1</sub> Proof Test Interval



# Your automation, our passion.

# **Explosion Protection**

- Intrinsic Safety Barriers
- Signal Conditioners
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- Electrical Ex Equipment
- Purge and Pressurization
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- HART Interface Solutions
- Surge Protection
- Wireless Solutions
- Level Measurement

# **Industrial Sensors**

- Proximity Sensors
- Photoelectric Sensors
- Industrial Vision
- Ultrasonic Sensors
- Rotary Encoders
- Positioning Systems
- Inclination and Acceleration Sensors
- Fieldbus Modules
- AS-Interface
- Identification Systems
- Displays and Signal Processing
- Connectivity

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Download our latest policy here:

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