## C $\epsilon$ <br> 

- Control circuit EEx ia IIC
- Lead breakage (LB) monitoring and short-circuit (SC) monitoring
- 1 signal output with 1 changeover contact
- 1 serially switched output
- 1 error message output
- LC display
- Start-up override
- Preferred direction of the output relay, switching delay, hysteresis and direction of action adjustable


## 24 V DC:

KFD2-DW-Ex1.D
Successor KFD2-DWB-Ex1.D

## Function

The rotation speed monitor compares an input frequency $\mathrm{f}_{\mathrm{E}}$ (max. 5 kHz ) with a predetermined reference frequency $f_{S}$ (switch point). The input frequency $f_{E}$ is adjustable within the range of 0.001 Hz ... 999 Hz (thumbwheel switch S1 ... S4). At higher frequencies, the input frequency $f_{E}$ must be downscaled by the pre-scaler so that a frequency of max. 1 kHz is available.

## LC-display

The LC-display shows the input frequency $f_{E}$ in respect to the adjusted switch point $f_{S}$ in \%; max. display faults $\pm 2$ digit; range: 0.00 \% ... 199.9 \%.

## Start bridge

The start-up override is initiated by assigning a "1-signal" to terminal 15 (on a KFD2-DW-Ex1.D) or by using a jumper on terminals 14 and 15 (on a KHA6-DW-Ex1.D).
This function causes the relay output to take up a specific switch status for an adjustable time period. The time period is determined with the S 4 thumbwheel switch position and the $t$ potentiometer's position on the front panel. The start bridge is only active as long as terminal 15 is linked. If terminal 15 is already linked before the switching of the supply voltage, then the function is activated by switching.

## Connection



## Composition



| Supply |  |
| :---: | :---: |
| Connection | Power Rail or terminals 17+, 18- |
| Rated voltage | $20 . .35 \mathrm{~V}$ DC |
| Ripple | $\leq 10$ \% |
| Rated current | $\leq 93 \mathrm{~mA}$ |
| Input |  |
| Connection | intrinsically safe: terminals $1+, 2+, 3-$ non-intrinsically safe: terminal 15 |
| Rated values | acc. to EN 60947-5-6 (NAMUR), see system description for electrical data |
| Open-circuit voltage/short-circuit current | approx. 8 V DC / approx. 8 mA |
| Switching point/Switching hysteresis | 1.2 ... $2.1 \mathrm{~mA} /$ approx. 0.2 mA |
| Pulse/Pause ratio | $\geq 0.1 \mathrm{~ms} / \geq 0.1 \mathrm{~ms}$ |
| Pulse delay | 2.5 ... 15 ms |
| Signal level | 1-signal: $15 \ldots 35 \mathrm{~V}$ DC ( 1 mA at 24 V DC) 0 -signal: 0 ... 5 V DC or open input |
| Function | start-up override |
| Lead monitoring | breakage I = $0.05 \ldots 0.15 \mathrm{~mA}$, short-circuit $6.2 \ldots 7.4 \mathrm{~mA}$ |
| Output |  |
| Connection | output I: terminals 7+, 8- ; output II: terminals 9+, 13- ; output III: terminals 10, 11, 12 |
| Output I | fault signal ; electronic output, passive |
| Output I and II |  |
| Signal level | 1-signal: (L+) -2.5 V (100 mA, short-circuit proof) 0 -signal: blocked output (off-state current $\leq 10 \mu \mathrm{~A}$ ) |
| Output II | serial switching ; electronic output, passive |
| Output III | signal ; relay |
| Contact loading | 250 V AC / $2 \mathrm{~A} / \cos \phi \geq 0.7$; 40 V DC / 2 A resistive load |
| Mechanical life | $5 \times 10^{7}$ switching cycles |
| Energized/de-energized delay | approx. 20 ms / approx. 20 ms |
| Transfer characteristics |  |
| Switching frequency |  |
| Signal | $\leq 10 \mathrm{~Hz}$ |
| Serial switching | $\leq 5 \mathrm{kHz}$ |
| Switching point error | 0.2 \% of nominal frequency |
| Electrical isolation |  |
| Input/output | safe electrical isolation acc. to EN 50020 |
| Input/power supply | safe electrical isolation acc. to EN 50020 |
| Output/power supply | according to DIN EN 50178, rated insulation voltage $253 \mathrm{~V}_{\text {eff }} \mathrm{AC}$ |
| Output/output | according to DIN EN 50178, rated insulation voltage $253 \mathrm{~V}_{\text {eff }} \mathrm{AC}$ |
| Directive conformity |  |
| Electromagnetic compatibility |  |
| Directive 89/336/EC | on request |
| Standard conformity |  |
| Insulation coordination | acc. to DIN EN 50178 |
| Electrical isolation | acc. to DIN EN 50178 |
| Climatic conditions | acc. to DIN IEC 721 |
| Input | acc. to EN 60947-5-6 (NAMUR), see system description for electrical data |
| Ambient conditions |  |
| Ambient temperature | $-25 \ldots 6{ }^{\circ} \mathrm{C}(248 \ldots 338 \mathrm{~K})$ |
| Mechanical specifications |  |
| Protection degree | IP20 |
| Mass | approx. 270 g |
| Data for application in conjunction with hazardous areas |  |
| EC-Type Examination Certificate | PTB No. Ex-89.C. 2145 ; for additional certificates refer to the approval list |
| Group, category, type of protection | [EEx ia] IIC resp. [EEx ia] IIB |
| Voltage $U_{0}$ | 12.7 V |
| Current $\mathrm{I}_{0}$ | 17.3 mA |
| Power $\mathrm{P}_{0}$ | 55 mW |
| Supply |  |
| Safety maximum voltage $U_{m}$ | 40 V DC |
| Type of protection [EEx ia] |  |
| Explosion group | IIB IIC |
| External capacitance | $1.1 \mu \mathrm{~F} \quad 0.45 \mu \mathrm{~F}$ |
| External inductance | $5 \mathrm{mH} \quad 2 \mathrm{mH}$ |
| Type of protection [EEx ib] |  |


| Explosion group | IIC |  |
| :---: | :---: | :---: |
| External capacitance | $5 \mu \mathrm{~F} \quad 1.2 \mu \mathrm{~F}$ | $1.2 \mu \mathrm{~F}$ |
| External inductance | 114 mH |  |
| Outputs |  |  |
| Safety maximum voltage $\mathrm{U}_{\mathrm{m}}$ | 40 V DC |  |
| Electrical isolation |  |  |
| Input/output | safe electrical isolation acc. to EN 50020 |  |
| Input/power supply | safe electrical isolation acc. to EN 50020 |  |
| Directive conformity |  |  |
| Directive 94/9 EC | on request |  |
| Safety parameter |  |  |
| CSA control drawing | LR 36087-19 |  |
| Connection | terminals 1, 3; 2, 3; 4, 6; 5, 6 |  |
| Input I |  |  |
| Safety parameter | $12.6 \mathrm{~V} / 650 \mathrm{Ohm}$ |  |
| Voltage $\quad \mathrm{V}_{\text {OC }}$ | 12.6 V |  |
| Current ${ }_{\text {IS }}$ | 19.8 mA |  |
| Explosion group | A\&B C\&E | D, F\&G |
| Max. external capacitance $C_{a}$ | $1.273 \mu \mathrm{~F} \quad 3.82 \mu \mathrm{~F}$ | $10.18 \mu \mathrm{~F}$ |
| Max. external inductance $\mathrm{L}_{\mathrm{a}}$ | $84.88 \mathrm{mH} \quad 298.7 \mathrm{mH}$ | 744.4 mH |
| General information |  |  |
| Supplementary information | EC-Type Examination Certificate, Statement of Conformity, Declaration of Conformity and instructions have to be observed. For information see www.pepperl-fuchs.com. |  |

## Notes

Adjustment instructions: Pre-scaler (S6)
The input frequency $f_{E}$ can be reduced by means of the pre-scaler S 6 , as the microprocessor of the rotational speed controller can process a frequency of max. 1 kHz .

| Switch S6 in pos. I: | $1: 1$ | $(1 \mathrm{kHz})$ | $?$ | Separator ratio TV $=1$ |
| :--- | :---: | :---: | :---: | :---: |
| Switch S6 in pos. II: | $2: 1$ | $(2 \mathrm{kHz})$ | $?$ | Separator ratio TV $=0,5$ |
| Switch S6 in pos. III: | $10: 1$ | $(5 \mathrm{kHz})$ | $?$ | Separator ratio TV $=0,1$ |
| Switch S6 in pos. IV: | $100: 1$ | $(5 \mathrm{kHz})$ | $?$ | Separator ratio TV $=0,01$ |

By means of the solder bridge 1 can be determined, if the serially switched output is operated dependent or independant of the adjustment of the pre-scaler.

Solder bridge 1 in pos. I:
Solder bridge 1 in pos. II:
Adjustment of the solder bridge 1:
Delivery:
serially switched output switches pre-scaler independent serially switched output switches pre-scaler dependent see drawing on next page)
solder bridge 1 in position I

Adjustment of the reference frequency $\mathrm{f}_{\mathrm{S}}$ (switch point)
$\mathrm{f}_{\mathrm{S}}=(\mathrm{S} 1 \times 100+\mathrm{S} 2 \times 10+\mathrm{S} 3 \times 1) \times \mathrm{S} 4 \times \mathrm{TV}$
By means of the thumbwheel switch S 1 up to S 4 the switch point $\mathrm{f}_{\mathrm{S}}$ is adjusted. However, the separator ratio TV should be considered.
Example:
Rotation speed data must be converted into the respective frequencies. The number of the pulses (z) per rotation must be known.
The result is:

```
            n X Z
f= ------- n= revolutions per minute in 1/min
```

A motor runs with 1065 turns/min. and delivers 2 pulses/rotation.
2 pulses/rotation
1065 x 2
$f_{s}=---------=35,5 \mathrm{~Hz}$

Adjustment: S1:3
S2: 5
S3: 5
S4: 1/5
S6:I

## Switch S4

| Switch S4 switch position | Reference frequency (S1 + S2 + S3) | Hysteresis |
| :---: | :---: | :---: |
| 0 | $\times 10^{-0} \mathrm{~Hz}$ | 1 |
| 1 | $\times 10^{-1} \mathrm{~Hz}$ | $1 \%$ |
| 2 | $\times 10^{-2} \mathrm{~Hz}$ | $1 \%$ |
| 3 | $\times 10^{-3} \mathrm{~Hz}$ | $1 \%$ |
| 4 | $\times 10^{-0} \mathrm{~Hz}$ | $5 \%$ |
| 5 | $\times 10^{-1} \mathrm{~Hz}$ | $5 \%$ |
| 6 | $\times 10^{-2} \mathrm{~Hz}$ | $5 \%$ |
| 7 | $\times 10^{-3} \mathrm{~Hz}$ | $5 \%$ |

## Adjustment of the time delay of the relay output

With the thumbwheel switch S 5 the circuit delay of the relay output can be adjusted. The value of the time constant $\tau$ is by approximation.

$$
\tau=\frac{2^{N+1}}{-----} \quad f_{s}=\text { reference frequency }
$$

The value N can be adjusted at the thumbwheel switch S 5 from 0 ... 9 .
Table: start-up override

| Switch S4 in Pos. | Time domain |  |  |
| :---: | :---: | :---: | :---: |
|  | Potentiometer $\tau$ | Output relay |  |
|  | $2 \mathrm{~s} \ldots 50 \mathrm{~s}$ | Solder bridge 2 open | Solder bridge 2 closed. |
| 0 or 4 | $20 \mathrm{~s} \ldots 500 \mathrm{~s}$ | energized | de-energized |
| 1 or 5 | $200 \mathrm{~s} \ldots 5000 \mathrm{~s}$ | energized | de-energized |
| 2 or 6 | $2000 \mathrm{~s} \ldots 50000 \mathrm{~s}$ | energized | de-energized |
| 3 or 7 | energized | de-energized |  |

## Mode of operation of the relay output

The mode of operation can be determined by means of the solder bridge LB2 (Adjustment of the solder bridge LB2: see drawing below).
Solder bridge LB2 open: $\quad f_{E} \geq f_{S}: \quad$ Relay energized
Solder bridge LB2 closed: $\quad f_{E} \geq f_{S}: \quad$ Relay de-energized
Delivery: solder bridge LB2 open

## Preferred direction of the relay output

When connecting the supply voltage a preferred direction of the relay output can be set, until the input frequency $f_{E}$ is measured for the first time.

## Adjustment of the solder bridge 1, the solder bridges LB1, LB2

By means of the solder bridge LB1 the following is set after the activation over a duration of approx. 380 ms .
LB1 open (Delivery)
$f_{E} \leq f_{S}$
LB1 closed
$f_{E} \geq f_{S}$

Depending on LB2 the output relay takes the corresponding state for these approx. 380 ms .
If the start-up override ("Logic-1" at terminal 15) is started with power-up, the LB 1 looses significance.
Delivery: solder bridge LB1 open
Solder bridge LB2 open
After removal of the cover and of the left-hand side part the jumpers are visible on the printed circuit board.


