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Model Number

PCV80G-F200-R4-V19

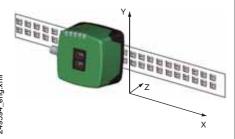
Read head for incident light positioning system

Features

- RS 485 interface
- Non-contact positioning on Data Matrix code tape
- Travel ranges up to 10 km, in X and Y direction
- Mechanically rugged: no wearing parts, long operating life, maintenance-free
- High resolution and precise positioning, especially for facilities with curves and switch points as well as inclines and declines.
- · Green light

Diagrams

Coordinates



Technical data

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Passage speed v	≤ 12.5 m/s
Measuring range	max. 10000 m
Light type	Integrated LED lightning (green)

 Read distance
 80 mm

 Depth of focus
 ± 15 mm

 Reading field
 40 mm x 25 mm

 Ambient light limit
 100000 Lux

 Resolution
 ± 0.1 mm

Nominal ratings

Camera
Type CMOS , Global shutter
Processor

Clock pulse frequency 600 MHz

Speed of computation 4800 MIPS Functional safety related parameters

MTTF_d 91 a
Mission Time (T_M) 45 a
Diagnostic Coverage (DC) 0 %
Indicators/operating means

LED indicator 7 LEDs (communication, alignment aid, status information)

 $\begin{tabular}{ll} \textbf{Electrical specifications} \\ \textbf{Operating voltage U_B} & 15 \dots 30 \ V \ DC \ , \ PELV \\ \textbf{No-load supply current I_0} & \text{max. 200 mA} \\ \end{tabular}$

Power consumption P₀ 3 W
Interface
Interface type RS 485 interface

Data output code binary code
Transfer rate 38400 ... 230400 Bit/s
Termination Switchable terminal resistor

Query cycle time ≥ 10 ms

Înput type 1 to 3 functional inputs , programmable Output

Output type 1 to 3 switch outputs , PNP , programmable , short-circuit protected

Switching voltage Operating voltage
Switching current 150 mA each output

Standard conformity
Emitted interference EN 61000-6-4:2007+A1:2011
Noise immunity EN 61000-6-2:2005

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Shock resistance EN 60068-2-27:2009
Vibration resistance EN 60068-2-6:2008
Ambient conditions

Operating temperature $0 \dots 60 \,^{\circ}\text{C} (32 \dots 140 \,^{\circ}\text{F}), -20 \dots 60 \,^{\circ}\text{C} (-4 \dots 140 \,^{\circ}\text{F})$ (noncondensing; prevent icing on the lens!)

 $\begin{array}{lll} \mbox{Storage temperature} & -20 \dots 85 \ ^{\circ}\mbox{C (-4} \dots 185 \ ^{\circ}\mbox{F)} \\ \mbox{Relative humidity} & 90 \ ^{\circ}\mbox{, noncondensing} \\ \end{array}$

Mechanical specifications

Connection type 8-pin, M12 x 1 connector
Housing width 70 mm
Housing height 70 mm
Degree of protection IP67
Material

Housing PC/ABS
Mass approx. 160 g

Approvals and certificates

UL approval cULus Listed, General Purpose, Class 2 Power Source,

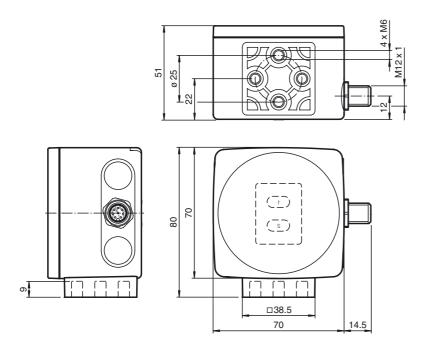
Type 1 enclosure

CCC approval CCC approval / marking not required for products rated ≤36

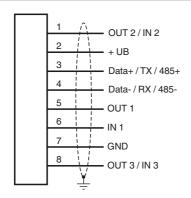
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Dimensions



Electrical Connection



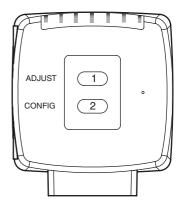
Pinout

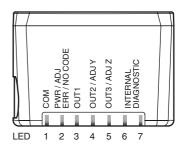


General

The reading head is part of the positioning system in the method for measurement by Pepperl+Fuchs. It consists of a camera module and an integrated illumination unit among other things. The reading head detects position marks, which are put on an adhesive code band in the form of Data Matrix code. The mounting of the code band is as a rule stationary on a firm part of the plant (elevator shaft, overhead conveyor mounting rails...); that of the reading head is parallel on the moving "vehicle" (elevator car, overhead conveyor chassis...).

Additional Information





Accessories

PCV-USB-RS485-Converter Set

USB to RS 485 interface converter

PCV-KBL-V19-STR-RS485

Cable unit with power supply for USB/RS-485 interface converter

V19-G-ABG-PG9

Female connector, M12, 8-pin, shielded, field attachable

V19-G-ABG-PG9-FE

Female connector, M12, 8-pin, shielded, field attachable

PCV-SC12

Grounding clip for PCV system

PCV-LM25

Marker head for 25 mm code tape

Mounting bracket for PCV* read head

PCV-AG80

Alignment guide for PCV80-* read head

Vision Configurator

Operating software for camera-based sensors

Mounting and commissioning

Mount the reading head such that its optical surface captures the optimal read distance to the code band (see Technical Data). The stability of the mounting and the guidance of the vehicle must be provided such that the depth of field of the reading head is not closed during operation. All reading heads can be optimally customized by parameterization for specific requirements. The parameterization of reading heads with a bidirectional interface (all except SSI-interface) can take place via the interface itself (internal parameterization) or via an optical parameterization code (external parameterization). The reading heads with SSI interface only have the possibility of external parameterization via optical parameterization codes.

Displays and Controls

The reading head allows visual function check and fast diagnosis with 7 indicator LEDs. The reading head has 2 buttons on the reverse of the device to activate the alignment aid and parameterization mode.

LEDs

LED	Color	Label	Meaning
1	Yellow	COM	Communication active
2	Green/red	PWR/ADJ	Code recognized/not recognized, Error
		ERR/NO CODE	
3	Yellow	OUT1	Output 1
4	Yellow	OUT2/ADJ Y	Output 2, Alignment aid Y
5	Yellow	OUT3/ADJ Z	Output 3, Alignment aid Z
6,7	red/green/yellow	INTERNAL	Internal diagnostics
		DIAGNOSTICS	

External parameterization

For external parameterization you require the parameterization code as Data Matrix with the desired reading head parameters. Data Matrix code cards for step-by-step external parameterization are printed in the reading heads operating instructions.

Parameterization is only possible within 10 minutes of switching on the reading head. If a button is pressed after 10 minutes subsequent to switching on, there is visual signaling via the LEDs (LED1, yellow/LED2, red/LED3, yellow/LED4, yellow/LED5, yellow flash for 2 seconds)

- The switchover from normal operation to parameterization mode is via button 2 on the reverse of the reading head. Button 2 must be pressed for more than 2 seconds. LED3 now flashes.
 - **Note:** Parameterization mode automatically ends after 1 minute of inactivity. The reading head returns to normal operation and works with unchanged settings.
- Place the parameterization code in the view of the camera module. After recognition of the parameterization code, the green LED2 lights up
 for 1s. In the event of an invalid parameterization code, the red LED2 lights up for 2 s.
- A short press on button 2 ends the parameterization mode and the changed parameters are not stored volatile in the reading head.

Alignment aid for the Y and Z coordinates

The activation of the alignment aid is only possible within 10 minutes of switching on the reading head. The switchover from normal operation to "alignment aid operating mode is via button 1 on the reverse of the reading head.

- Press the button 1 for longer than 2 s. LED2 flashes green for a recognized code band. LED2 flashes red for an unrecognized code band.
- Z coordinate: If the distance of the camera to the code band too small, the yellow LED5 lights up. If the distance of the camera to the code band too large, the yellow LED5 lights up. Within the target range, the yellow LED5 flashes at the same time as the green LED2.
- Y coordinate: If the optical axis of the camera is too deep in relation to the middle of the code band, the yellow LED4 lights up. If the optical axis is too high, the yellow LED4 extinguishes. Within the target range, the yellow LED4 flashes at the same time as the green LED2.
- A short press on button 1 ends the alignment aid and the reading head changes to normal operation.

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