

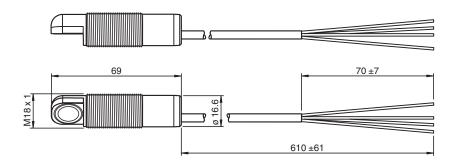
Ultrasonic sensor UB800-18GM40A-U-610MM-Y

- Analog output 0.5 ... 4.5 V
- Measuring window adjustable
- Program input
- Temperature compensation
- Customer-specific cable length
- Deutsch 4-pin, DT04 connector

Single head system



Dimensions



Technical Data

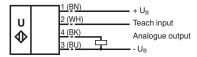
General specifications		
Sensing range		50 800 mm
Adjustment range		70 800 mm
Dead band		0 50 mm
Standard target plate		100 mm x 100 mm
Transducer frequency		approx. 255 kHz
Response delay		approx. 100 ms
Indicators/operating means		
LED green		Power on
LED yellow		solid yellow: object in the evaluation range yellow, flashing: program function, object detected
LED red		solid red: Error red, flashing: program function, object not detected
Electrical specifications		
Operating voltage	U _B	10 30 V DC
No-load supply current	I_0	≤ 20 mA
Input		

Input type		1 program input lower evaluation limit A1: -U _B +1 V, upper evaluation limit A2: +4 V +U _B input impedance: > 4.7 k Ω , pulse duration: \geq 1 s
Output		
Output type		1 analog output 0.5 4.5 V
Default setting		evaluation limit A1: 70 mm evaluation limit A2: 800 mm
Resolution		0.4 mm at max. sensing range
Deviation of the characteristic curve		± 1 % of full-scale value
Repeat accuracy		± 0.5 % of full-scale value
Load impedance		> 1 kOhm
Temperature influence		± 1.5 % of full-scale value
Compliance with standards and directives		
Standard conformity		
Standards		EN IEC 60947-5-2:2020 IEC 60947-5-2:2019 EN 60947-5-7:2003 IEC 60947-5-7:2003
Approvals and certificates		
UL approval		cULus Listed, Class 2 Power Source
CCC approval		CCC approval / marking not required for products rated ≤36 V
Ambient conditions		
Ambient temperature		-25 70 °C (-13 158 °F)
Storage temperature		-40 85 °C (-40 185 °F)
Mechanical specifications		
Connection type		cable
Housing length		69 mm
Housing diameter		18 mm
Degree of protection		IP67
Material		
Housing		brass, nickel-plated
Transducer		epoxy resin/hollow glass sphere mixture; foam polyurethane, cover PBT
Cable		
Sheath diameter		4.8 mm
Bending radius		> 38.4 mm , fixed > 72 mm , moving
Material		PVC
Number of cores		4
Core cross section		4 x 0.5 mm ²
Length	L	610 mm
Mass		65 g
General information		
Scope of delivery		Deutsch connector DT04-4P-CE01 Deutsch wedge W4P German contact 0460-202-1631

Connection

Standard symbol/Connections:

(version U)

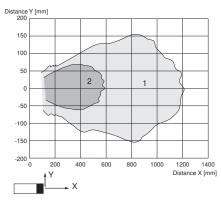


Core colours in accordance with EN 60947-5-2.



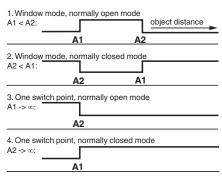
Characteristic Curve

Characteristic response curve



Curve 1: flat surface 100 mm x 100 mm Curve 2: round bar, Ø 25 mm

Programmable output modes



5. A1 -> ∞, A2 -> ∞: Object presence detection mode
Object detected: Switch output closed
No object detected: Switch output open

Programming

The sensor features a programmable analog output with two programmable evaluation boundaries. Programming the evaluation boundaries and the operating mode is done by applying the supply voltage $-U_B$ or $+U_B$ to the Teach-In input. The supply voltage must be applied to the Teach-In input for at least 1 s. LEDs indicate whether the sensor has recognized the target during the programming procedure.

Note:

Evaluation boundaries may only be specified directly after Power on. A time lock secures the adjusted switching points against unintended modification 5 minutes after Power on. To modify the evaluation boundaries later, the user may specify the desired values only after a new Power On.

Note

If a programming adapter UB-PROG2 is used for the programming procedure, button A1 is assigned to -UB and button A2 is assigned to +UB.

Programming the analog output Rising ramp

- 1. Place the target at the near end of the desired evaluation range
- 2. Program the evaluation boundary by applying -U_B to the Teach-In input (yellow LED flashes)
- 3. Disconnect the Teach-In input from $\mbox{-}\mbox{U}_{B}$ to save the evaluation boundary
- 4. Place the target at the far end of the desired evaluation range
- 5. Program the evaluation boundary by applying $+U_B$ to the Teach-In input (yellow LED flashes)
- 6. Disconnect the Teach-In input from $+U_B$ to save the evaluation boundary

Falling ramp

- 1. Place the target at the far end of the desired evaluation range
- 2. Program the evaluation boundary by applying -U_B to the Teach-In input (yellow LED flashes)
- 3. Disconnect the Teach-In input from -U_B to save the evaluation boundary
- 4. Place the target at the near end of the desired evaluation range
- 5. Program the evaluation boundary by applying +U_B to the Teach-In input (yellow LED flashes)
- 6. Disconnect the Teach-In input from +U_B to save the evaluation boundary

Additional Information

If the sensor is installed at places, where the environment temperature can fall below 0 °C, for the sensors fixation, one of the mounting flanges BF 12, BF 12-F or BF 5-30 must be used. In case of direct mounting of the sensor in a through hole, it has to be fixed at the middle of the housing thread.