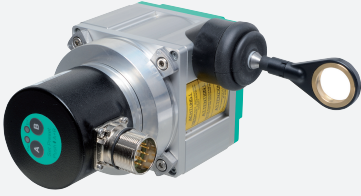


# Cable pull rotary encoder

## ECA30PL - SSI



- Robust aluminum drum housing
- Drum travel when cable retracted using threaded spindle
- Bellows with steel tip
- Comprehensive accessories
- Housing can be coated as an option (Hart Coat)
- Rust and acid-resistant measuring cable
- SSI interface
- Free of wear magnetic sampling
- Additionally push buttons for preset function (only model characteristic SB2, SG2)

Cable pull rotary encoder with SSI interface

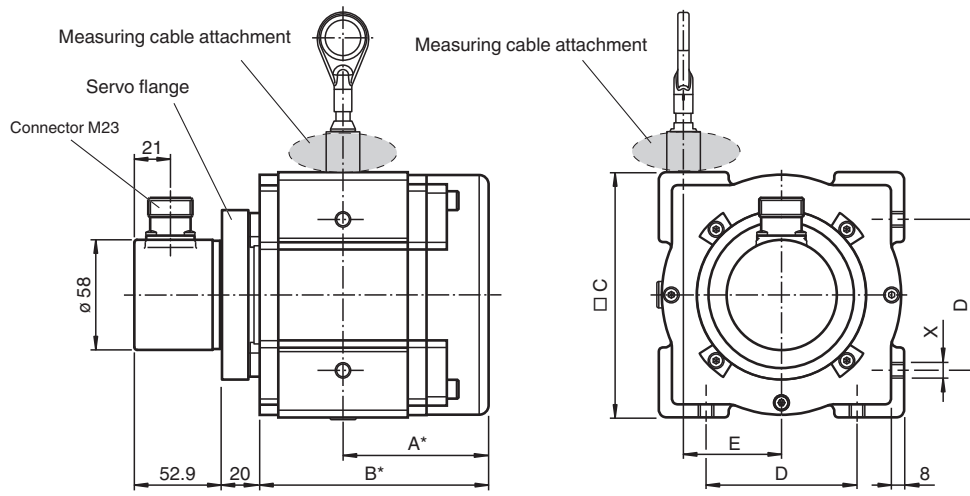


### Function

Flexible cable pull rotary encoder designed to meet tough requirements in all fields of application.

### Dimensions

Details of variable specifications of designs and measuring length see chapter „Variable Data and Dimensions“



\*depending on measuring length

Measuring length	X
01 - 02	4 x M6 ↓8
03	8 x M6 ↓8
05 - 10	4 x M8 ↓8
15 - 30	12 x M8 ↓8
35 - 60	12 x M10 ↓11

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**Dimensions**

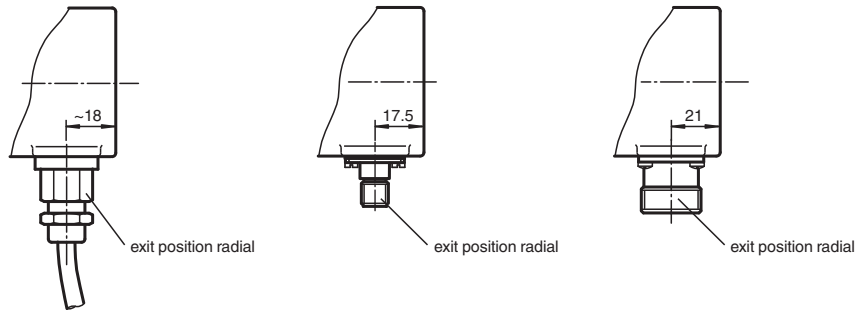
Connections

Dimensions in mm

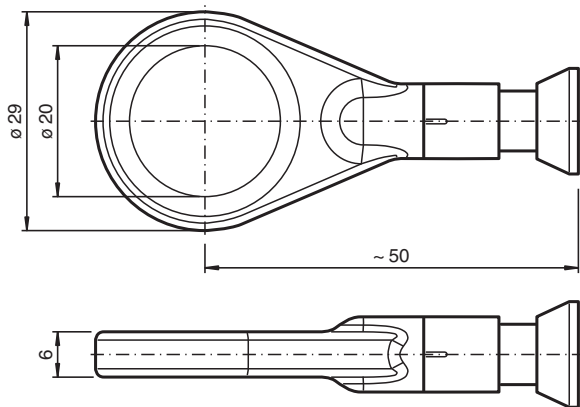
Cable

Connector M12

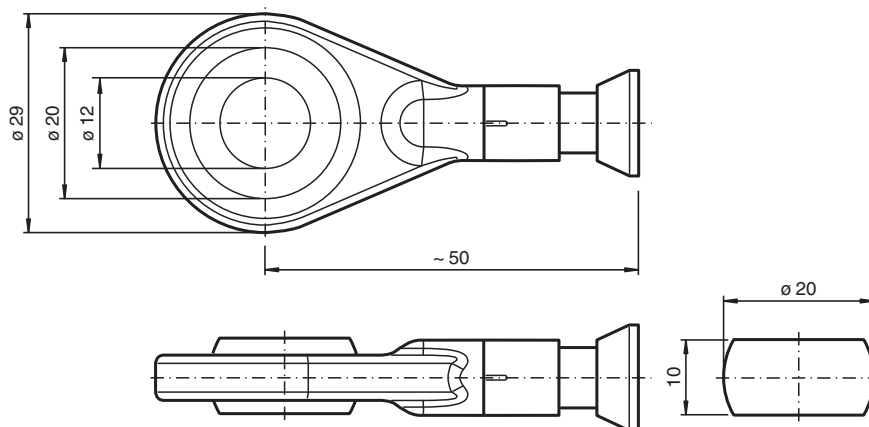
Connector M23



**A**



**C**



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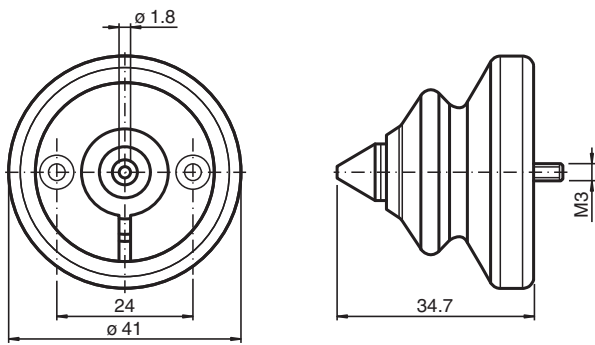
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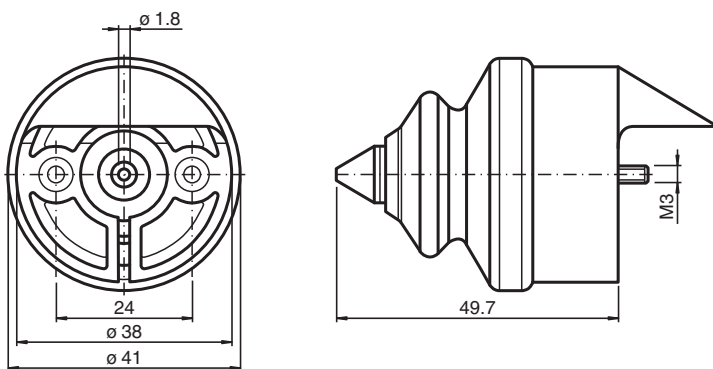
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**Dimensions**

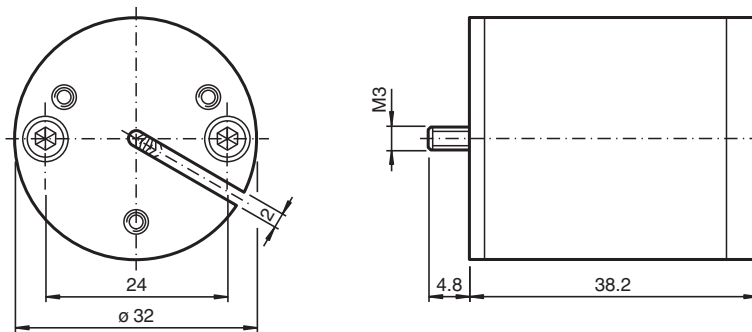
**1 For design 130/190**



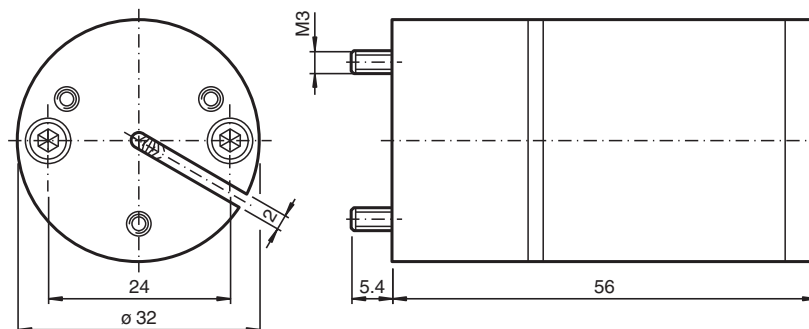
**1 For design 80**



**2 For design 130/190**



**2 For design 80**

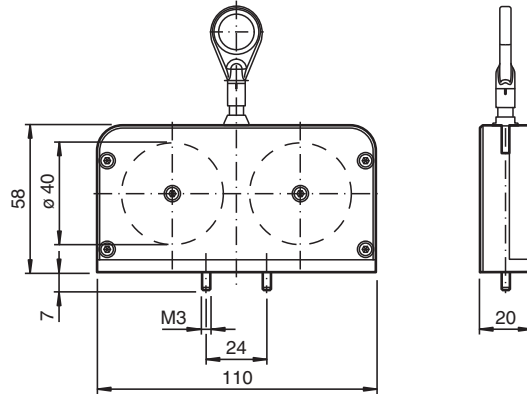


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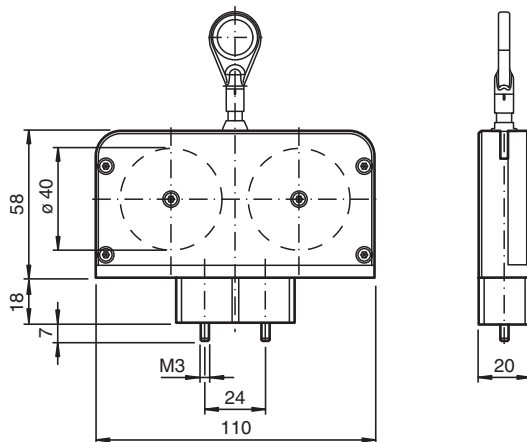


## Dimensions

### 5 For design 130/190



### 5 For design 80



## Technical Data

### General specifications

Detection type	magnetic sampling	
Device type	Premium Line with SSI interface	
Measuring range	1000 ... 60000 mm	
Construction type	80 mm, 130 mm, 190 mm	
Resolution	Cable pull: Design 80 mm: 0,024 mm Design 130 mm: 0,041 mm Design 190 mm: 0,059 mm Encoder: 25 Bit (13 Bit/revolution)	

### Functional safety related parameters

$B_{10d}$	300000
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### Electrical specifications

Operating voltage	$U_B$	4.75 ... 30 V DC
No-load supply current	$I_0$	typ. 50 mA
Power consumption	$P_0$	approx. 1.5 W
Time delay before availability	$t_v$	< 450 ms
Output code	Gray code, binary code	
Code course (counting direction)	adjustable	

### Interface

Interface type	SSI	
Cycle time	< 100 $\mu$ s	
Standard conformity	RS 422	

### Input 1

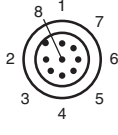
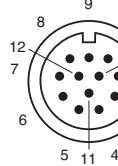
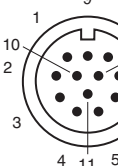
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## Technical Data

Input type		Selection of counting direction (cw/ccw)
Signal voltage		
High		4.75 V ... $U_B$ (cw descending)
Low		0 ... 2 V or unconnected (cw ascending)
Input current		< 6 mA
<b>Input 2</b>		
Input type		zero-set (PRESET 1) with falling edge
Signal voltage		
High		4.75 V ... $U_B$
Low		0 ... 2 V
Input current		< 6 mA
Signal duration		min. 1.1 s
<b>Connection</b>		
Connector		M12 connector, 8-pin or M23 connector, 12-pin
Cable		Ø7 mm, 6 x 2 x 0.14 mm <sup>2</sup> , 1 m (cable length, see order code)
<b>Standard conformity</b>		
Degree of protection		DIN EN 60529, IP65
Climatic testing		DIN EN 60068-2-3, no moisture condensation
Emitted interference		EN 61000-6-4:2007
Noise immunity		EN 61000-6-2:2005
<b>Ambient conditions</b>		
Ambient temperature		-30 ... 70 °C (-22 ... 158 °F)
Operating temperature		-30 ... 70 °C (-22 ... 158 °F)
Storage temperature		-30 ... 70 °C (-22 ... 158 °F)
Relative humidity		98 % , no moisture condensation
<b>Mechanical specifications</b>		
Rope diameter		1.35 mm
Bending radius		min. 17 mm
Breaking force		min. 1227 N
<b>Material</b>		
Cable pull		anodized aluminum or Aluminum with Hart Coat coating
Rotary encoder		housing: nickel-plated steel Flange: aluminum
Flange		Aluminum
Rope		Stainless steel 1.4401/316
Life span		up to 10 <sup>6</sup> Cycles

**Connection**

Signal	Cable, 12-core	Connector M12, 8-pin	Connector M23, 12-pin, cw	Connector M23, 12-pin, ccw	Explanation
GND (encoder)	White	1	1	1	Power supply
U <sub>B</sub> (encoder)	Brown	2	2	8	Power supply
Clock (+)	Green	3	3	3	Positive cycle line
Clock (-)	Yellow	4	4	11	Negative cycle line
Data (+)	Grey	5	5	2	Positive transmission data
Data (-)	Pink	6	6	10	Negative transmission data
Reserved	Black		7	12	Not wired, reserved
V/R	Red	8	8	5	Input for selection of counting direction
PRESET 1	Blue	7	9	9	zero-setting input
Reserved	Violet		10	4	Not wired, reserved
Reserved	Grey/Pink		11	6	Not wired, reserved
Reserved	Red/Blue		12	7	Not wired, reserved
					

**Technical Features**

**Variable Data and Dimensions**

Technical Data	Design 80			Design 130						Design 190			
	01	02	03	05	10	15	20	25	30	35	40	50	60
Max. measuring length (in m)													
Drum size (incl. cable) (in mm)	200			334,1						491,5			
Retraction speed (in m/s)	8			8		6		3		4			
Spring retraction force (in N)	5-15			10-21	15-21	10-21	15-21	10-21	15-21	18-37			
Weight (in kg)	0,9	1,1	1,5	2,5	3,5	5	6	7,5	8,5	16	20	14,5	15,5
<b>Dimensions (in mm)</b>													
A	34	42	60	77	124	147	193	216	262	188	203	195	210
B	57	72	98	122	190	236	304	350	418	315	346	292	322
C	80			130						190			
D	50			80						140			
E	31,5			52						79			

**Measuring Cable Attachments**

Dimensions (in mm)		Design 80		Design 130/design 190	
Attachment		Length	Width/Ø	Length	Width/Ø
1	Bellows	49.7	41/38	34.7	41
2	Brush attachment with bellows and steel tip	90.7	32	72.9	32
4	Guide pulley	86	32	70	32
5	Double guide pulley	110	58	110	58

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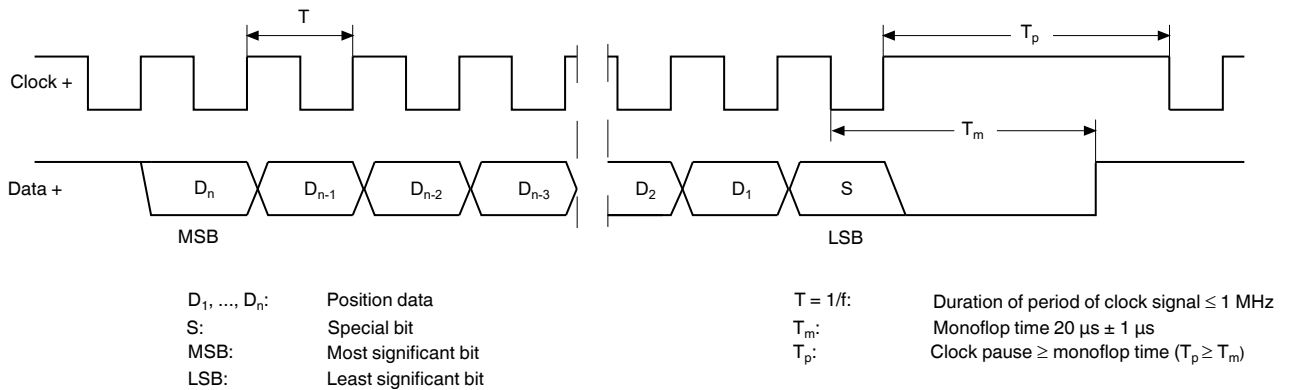
		<b>Design 80/130/190</b>	
		<b>Length</b>	
8	Brush attachment + guide pulley	126	108.2

## Interface

### Description

The Synchronous Serial Interface was specially developed for transferring the output data of an absolute encoder to a control device. The control module sends a clock bundle and the absolute encoder responds with the position value. Thus only 4 lines are required for the clock and data, no matter what the resolution of the rotary encoder is. The RS 422 interface is optically isolated from the power supply.

### SSI signal course Standard



### SSI output format Standard

- At idle status signal lines "Data +" and "Clock +" are at high level (5 V).
- The first time the clock signal switches from high to low, the data transfer in which the current information (position data (D<sub>n</sub>) and special bit (S)) is stored in the encoder is introduced.
- The highest order bit (MSB) is applied to the serial data output of the encoder with the first rising pulse edge.
- The next successive lower order bit is transferred with each following rising pulse edge.
- After the lowest order bit (LSB) has been transferred the data line switches to low until the monoflop time T<sub>m</sub> has expired.
- No subsequent data transfer can be started until the data line switches to high again or the time for the clock pause T<sub>p</sub> has expired.
- After the clock sequence is complete, the monoflop time T<sub>m</sub> is triggered with the last falling pulse edge.
- The monoflop time T<sub>m</sub> determines the lowest transmission frequency.

### SSI output format ring slide operation (multiple transmission)

- In ring slide operation, multiple transmission of the same data word over the SSI interface makes it possible to offer the possibility of detecting transmission errors.
- In multiple transmission, n bits are transferred per data word in standard format. The value n equals the total resolution of the encoder.  
As an example: a multiturn encoder with a resolution of 8192 steps/revolution (13 bit) and a max. number of 4096 revolutions (12 bit) has a total resolution of n = 25 bit.
- If the clock change is not interrupted after the last falling pulse edge, ring slide operation automatically becomes active. This means that the information that was stored at the time of the first clock change is generated again.
- After the first position transmission, the n+1 pulse controls data repetition. If the n+1 pulse follows after an amount of time greater than the monoflop time T<sub>m</sub>, a new current data word will be transmitted with the following pulses.



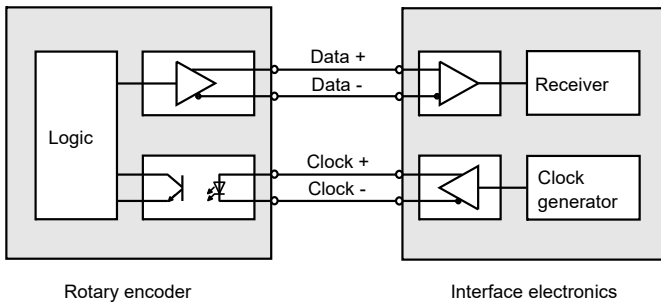
If the pulse line is exchanged, the data word is generated offset.

### Block diagram

### Line length

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Line length in m	Baudrate in kHz
< 50	< 400
< 100	< 300
< 200	< 200
< 400	< 100

## Parameterization

### Push buttons on encoder with model characteristic SB2, SG2

In addition to the electrical preset function (PRESET 1) these models are equipped with 2 push buttons for manually setting the zero point of the rotary encoder.

#### Manually zero set

1. Simultaneously press and hold the push buttons A and B for 2 s.

After releasing the push buttons the rotary encoder sets the current position as zero point.

## Type Code

### Model Number



#### Connection type

- C1** Cable, 1 m
- C2** Cable, 2 m
- C5** Cable, 5 m
- CA** Cable, 10 m
- AA** M23 device plug, cw
- AB** M23 device plug, ccw
- BE** M12 device plug, 8-pin

#### Electrical interface

- SG1** SSI Gray
- SB1** SSI binary
- SG2** SSI Gray, with push buttons
- SB2** SSI binary, with push buttons

#### Material

- A** STD anodized aluminum
- H** Aluminum, Hart Coat coating

#### Attachment

- 1** Bellows with steel tip
- 2** Brush attachment with bellows and steel tip
- 4** Guide pulley
- 5** Double guide pulley
- 8** 2+4

#### Cable mounts

- A** Ring PE carrier
- C** Ball joint

#### Length of measuring cable

**01-60** See table "Variable Data and Dimensions"

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