



Multiturn absolute encoder

CVM58S

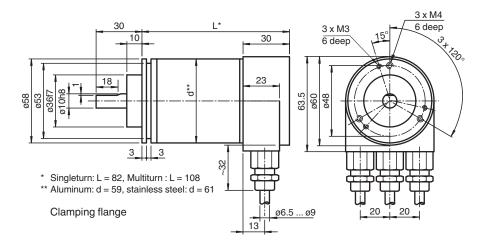
- Integrated functional safety with twin processor structure and dual sensing for extra security
- For systems up to SIL3 and PLe
- Industrial standard housing Ø58 mm
- 30 Bit multiturn
- Galvanically isolated CAN interface
- DSP 406/301/304, CLASS 1 and 2
- Servo or clamping flange
- 2 limit switches
- CANopen and CANopen Safety interface

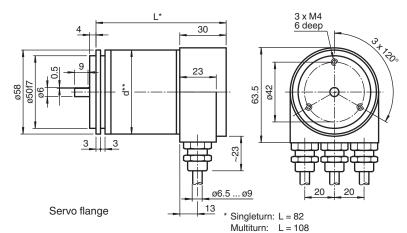






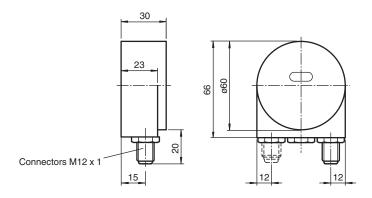
Dimensions

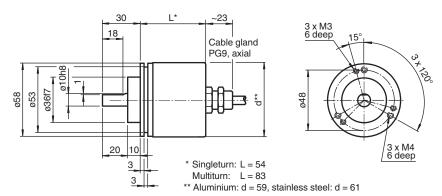




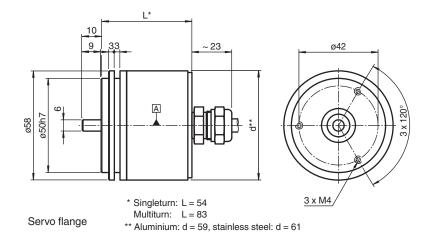
** Aluminium: d = 59, stainless steel: d = 61

Dimensions





Clamping flange



Technical Data

General specifications		
Detection type		photoelectric sampling
Device type		Multiturn absolute encoder
Electrical specifications		
Operating voltage	U _B	12 30 V DC
No-load supply current	I_0	max. 100 mA
Linearity		Non Safety:; \pm 4 LSB at 16 Bit, \pm 0,5 LSB at 12 Bit Safety Value: 10 bit \pm 0 LSB

Technical Data			
Output code	binary code		
Code course (counting direction)	cw ascending (clockwise rotation, code course ascending) cw descending (clockwise rotation, code course descending)		
Interface			
Interface type	CANopen / CANopen Safety		
Resolution			
Single turn	CANopen: up to 16 Bit CANopen Safety: 10 Bit		
Multiturn	14 Bit		
Overall resolution	up to 30 Bit		
Transfer rate	max. 1 MBit/s		
Standard conformity	DSP 406/301/304, CLASS 1 and 2		
Output			
Output type	DSP 406/301/304, CLASS 1 and 2		
Connection			
Terminal compartment	in removable housing cover		
Standard conformity			
Degree of protection	DIN EN 60529, shaft side: IP64 (without shaft seal)/IP66 (with shaft seal) housing side: IP65		
Climatic testing	DIN EN 60068-2-3, no moisture condensation		
Emitted interference	EN 61000-6-4:2007		
Noise immunity	EN 61000-6-2:2005		
Shock resistance	DIN EN 60068-2-27, 100 g, 6 ms		
Vibration resistance	DIN EN 60068-2-6, 10 g, 10 1000 Hz		
Functional safety	IEC 62061:2005 ISO 13849-1:2006		
Approvals and certificates			
UL approval	cULus Listed, General Purpose, Class 2 Power Source		
Ambient conditions			
Operating temperature	-30 70 °C (-22 158 °F)		
Storage temperature	-30 70 °C (-22 158 °F)		
Mechanical specifications			
Material			
Combination 1	housing: powder coated aluminum flange: aluminum shaft: stainless steel		
Combination 2 (Inox)	housing: stainless steel flange: stainless steel shaft: stainless steel		
Mass	approx. 800 g (combination 1) approx. 1300 g (combination 2)		
Rotational speed	max. 12000 min ⁻¹		
Moment of inertia	30 gcm ²		
Starting torque	≤ 3 Ncm (version without shaft seal)		

Accessories

Shaft load

Axial Radial

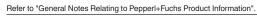
C	9203	Angled flange
	9310-3	Synchro clamping element



40 N

110 N

Acces	Accessories			
	9300	Mounting bracket for servo flange		
	KW-10/10	Helical coupling		
	KW-6/10	Helical coupling		
	KW-6/6	Helical coupling		
	KW-6/8	Helical coupling		
	9401 10*10	Spring steel coupling		
	9401 10*12	Spring steel coupling		
	9401 6*10	Spring steel coupling		
	9401 6*6	Spring steel coupling		
	9402 6*6	Spring steel coupling		
	9404 10*10	Spring disk coupling		
	9404 6*6	Spring disk coupling		
	9409 10*10	Bellows coupling		
	9409 6*10	Bellows coupling		
	9409 6*6	Bellows coupling		
	9409 6*8	Bellows coupling		
(3)	9410 10*10	Precision coupling		
3	9410 6*6	Precision coupling		
	MBT-36ALS	Spring-loaded mounting bracket with a diameter of 36 mm		



This absolute rotary encoder with Safety CANopen interface fulfills through its mechanical and electronical concept with twin-microcontroller structure and double sampling all safety function requirements of modern fuctional safe control systems. It is suitable for the use in machines and plants with safety categories up to:

- SIL3 acc. to EN 62061
- PLe acc. to IEC 13849
- Category 4 acc. to IEC 13849

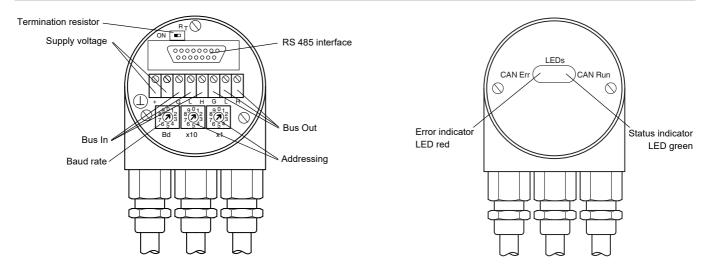
The bus electronics is integrated in the removable housing cover. Due to this the encoder and the bus electronics can be installed or replaced separately in case of maintenance and service. This device is made for shaft mounting and comes with a clamping-flange.

Connection

Electrical connection

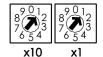
Terminal	Cable	Connector(s)	Explanation
Τ	-	-	Ground connection for power supply
(+)	Red	2	Power supply, +12 +30 VDC
(-)	Black	3	Power supply, 0 VDC
CG	-	1	CAN Ground (Bus In)
CL	Blue	5	CAN Low (Bus In)
СН	White	4	CAN High (Bus In)
CG	-	1	CAN Ground (Bus Out)
CL	Blue	5	CAN Low (Bus Out)
CH	White	4	CAN High (Bus Out)
		$2 \underbrace{\begin{array}{c} 1 \\ 5 \\ 3 \end{array}}^{5} 4 \qquad \qquad 4 \underbrace{\begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \end{array}}^{5} 2$	

Additional Information



Adjusting the participant address

The participant address can be adjusted with the rotary switches. The address can be defined between 1 and 64, and may only be assigned once.



Adjusting the termination resistor

The terminating resistor R_T (121 Ω) can be connected to the circuit by means of the switch:



Baud rate adjustment

Baud rate [kBit/s]	Switch position	Value Object 3001h	Baud rate [kBit/s]	Switch position	Value Object 3001h
20	0	0	500	5	5
50	1	1	800	6	6
100	2	2	1000	7	7
125	3	3	reserved	8	-
250	4	4	reserved	9	-

LED CAN Err (rot)	Status	Meaning		
off	No error	Device operates in normal mode.		
single flash	Warning limit reached	At least one of the CAN controllers error counter has reached or crossed the warning limit		
		(too many error frames).		
double flash	Error event	NMT error monitor event or heartbeat error has happened.		
flashing continously	Invalid configuration	General configuration fault.		
on	Bus off	The CAN controller has disconnected from the bus		
LED CAN Run (grün)	Status	Meaning		
off	Reset	Devive is performing a reset.		
single flash	STOPPED	The devices status is STOPPED.		
flashing continuously	PRE-OPERATIONAL	The devices status is PRE-OPERATIONAL.		
on	OPERATIONAL	The devices status is OPERATIONAL.		

Order code

